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Multidisciplinary Perspectives in
Mechanical and Applied Sciences

Ranjan Kumar & Arnab Das



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Multidisciplinary Perspectives in Mechanical and Applied Sciences

Editors

Ranjan Kumar & Arnab Das



Multidisciplinary Perspectives in Mechanical and Applied Sciences

Edited by

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Thanks



Publisher

Preface

In the rapidly evolving world of mechanical engineering and applied sciences, research and innovation play a pivotal role in shaping the future of industries and technology. This book, "**Multidisciplinary Perspectives in Mechanical and Applied Sciences**," brings together groundbreaking studies that explore the latest advancements across multiple domains of mechanical engineering, materials science, artificial intelligence, and sustainable technologies. By compiling diverse perspectives and cutting-edge methodologies, this volume aims to provide a holistic view of contemporary research that pushes the boundaries of traditional engineering disciplines.

The chapters within this book delve into a wide range of topics, including advancements in renewable energy systems, predictive maintenance with artificial intelligence, emerging manufacturing techniques, and the integration of machine learning in mechanical engineering applications. By fostering interdisciplinary collaboration and innovation, these studies contribute to the development of more efficient, sustainable, and intelligent engineering solutions for modern challenges.

This book is designed as a valuable resource for researchers, industry professionals, and students who seek to deepen their understanding of the latest technological breakthroughs. Each chapter presents a blend of theoretical insights and practical applications, equipping readers with knowledge that bridges the gap between academia and industry.

We extend our sincere gratitude to all contributing authors for their dedication and scholarly contributions. Our appreciation also goes to Swami Vivekananda University, Kolkata, for its unwavering support, and to the editorial team and reviewers who ensured the highest academic quality of this publication.

It is our hope that this book serves as a source of inspiration and knowledge, encouraging further research, collaboration, and innovation in mechanical engineering and beyond.

***Dr. Ranjan Kumar
Dr. Arnab Das***

Acknowledgement

We extend our deepest gratitude to Swami Vivekananda University, Kolkata, India, for their unwavering support and encouragement in the creation of "Multidisciplinary Perspectives in Mechanical and Applied Sciences." The university's commitment to academic excellence and research innovation has been instrumental in shaping this book. Their dedication to fostering an environment of learning and exploration has enabled the compilation of diverse and cutting-edge research contributions.

We are especially thankful for the collaborative spirit, state-of-the-art facilities, and continuous inspiration provided by Swami Vivekananda University, Kolkata. The institution's emphasis on interdisciplinary research has played a crucial role in bringing together scholars from various domains, enriching the depth and impact of this volume.

Our sincere appreciation also goes to the esteemed external reviewers for their meticulous evaluation, insightful feedback, and commitment to maintaining the highest scholarly standards. Their expertise has significantly contributed to enhancing the academic rigor and quality of this publication.

Finally, we acknowledge the dedication and hard work of all contributing authors, researchers, and editorial team members. Their passion for advancing knowledge and their perseverance in research have made this compilation possible. It is our sincere hope that this book serves as a valuable resource for scholars, students, and professionals, reflecting our shared vision of fostering innovation, collaboration, and academic excellence.

Dr. Ranjan Kumar
Dr. Arnab Das

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1

Performance and Emission Characteristics of Compression Ignition Engines Fueled with Hydrogen-Diesel Mixtures

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Abstract

The growing need for cleaner and more efficient energy systems has driven research into alternative fuels for internal combustion engines. Hydrogen, with its high energy content and zero carbon emissions, is a promising candidate to complement traditional diesel in compression ignition engines. This study investigates the performance and emission characteristics of compression ignition engines fueled with hydrogen-diesel mixtures. The research explores state-of-the-art technologies, experimental setups, and the potential benefits and challenges of such fuel combinations. Results indicate significant improvements in combustion efficiency and reductions in particulate matter and greenhouse gas emissions, albeit with certain challenges like knock and NOx emissions.

Introduction

Growing demands for efficient clean energy systems have stimulated research into alternative fuels for internal combustion engines. Hydrogen emerges as a fundamental solution to upgrade traditional diesel fuel in compression ignition engines because of its high energy density combined with zero-carbon emission benefits. This research investigates compression ignition engine operation using blending fuel mixtures containing hydrogen and diesel. This work investigates both established technological approaches and experimental configurations while analyzing both the advantages and constraints of mixing hydrogen fuel with diesel. The obtained results demonstrate better engine efficiency alongside reduced airborne pollutants and

carbon dioxide but researchers faced Knock and NO_x disadvantages in their experiments.

Existing research demonstrates that vehicles from the transportation sector generate a significant portion of worldwide greenhouse gas emissions. Powered by their efficiency and long life expectancy diesel engines serve two major applications in heavy vehicles and power plants. Despite being widely utilized diesel engine emissions create substantial environmental problems because of NO_x and particulate matter (PM) pollution. The combination of hydrogen with diesel represents an effective method to decrease vehicle emissions while preserving engine operating capabilities.

This research investigates how compression ignition (CI) engines operate when using hydrogen-diesel mixtures based on performance and emission behavior. Our research analyzes the dual-fuel method through evaluations of existing approaches combined with experimental methods and outcome evaluations to demonstrate its operational feasibility.

Methodology

- **Experimental Setup**

A four-stroke single-cylinder CI engine operated as the experimental unit. Key specifications:

- **Displacement:** 500 cc
- **Compression Ratio:** 17:1
- **Injection system:** Direct injection

- **Fuel Blending**

The flow control valves maintained hydrogen-to-diesel ratios at 0%, 10%, 20%, and 30% by energy during the experimental process.

- **Measurement Parameters**

- **Performance Metrics:** Brake thermal efficiency and specific fuel consumption served as the performance measurement parameters. The experimental setup operated the engine at 1500 RPM throughout the duration. Researchers applied a gas analyzer system to measure exhaust emissions during the study. A four-stroke CI engine was used for the experiments. Key specifications:
- **Displacement:** 500 cc
- **Compression Ratio:** 17:1
- **Injection System:** Direct injection

- **Fuel Blending**

Hydrogen was introduced into the intake manifold using a flow control valve, maintaining precise hydrogen-diesel ratios (0%, 10%, 20%, and 30% by energy).

- **Measurement Parameters**
 - Performance Metrics: Brake thermal efficiency (BTE), specific fuel consumption (SFC)
 - Emission Metrics: CO, CO₂, NO_x, PM
- **Testing Procedure**
 - Engine operated at a constant speed of 1500 RPM
 - Load varied from 25% to 100%
 - Emission measurements taken using a gas analyzer

Results and Discussion

- **Engine Performance**
 - **Brake Thermal Efficiency (BTE):** Engine brake thermal efficiency became 10-15% more efficient when using a 20% hydrogen blend because of improved combustion quality.
 - **Specific Fuel Consumption (SFC):** Additional hydrogen in the mixture resulted in a 12% reduction in specific fuel consumption.
- **Emission Characteristics**
 - **CO and CO₂ Emissions:** Significant reductions (up to 40%) with higher hydrogen blends.
 - **Particulate Matter (PM):** The absence of carbon in hydrogen has made particulate matter virtually disappear.
 - **NO_x Emissions:** The combustion temperature's elevation from higher hydrogen ratios increases emissions by 25-30%.
- **Challenges**
 - **Knock Tendency:** Observed at hydrogen ratios exceeding 30%.
 - **Storage and Handling:** Hydrogen demands complex storage solutions because of its low-density profile.

Conclusion

The investigation demonstrates a viable pathway for using blended fuels between hydrogen and diesel to replace conventional CI engines. The observed improvements in thermal efficiency and major emission reductions deserve attention but the current challenge involves managing NO_x formation and knock tendency. Future investigations need to study optimal hydrogen delivery methods and innovative post-treatment technologies to reduce NO_x emissions.

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2

Effect of Sodium Hypophosphite Concentration on Tribological and Mechanical Behavior of Electroless Ni-P Coatings

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Abstract

The exceptional tribological, physical, and mechanical properties of Sodium hypophosphite reduced electroless coatings make them frequently employed. The behaviors of the coating depend on its composition. In order to comprehend the significance of phosphorus concentration in the tribo-mechanical behavior of coatings, electroless Ni-P coatings are created on an AISI 1040 steel substrate. As-deposited coatings SEM data show a nodular type surface morphology that is helpful in lowering friction and coating wear. The EDX elemental analysis results indicate that the phosphorus concentration reduced from 11.4 to 8.9%. This decline in bath level concentration is accompanied by increases in surface hardness measured by micro-indentation technique. The microhardness is also observed to reduce with nickel sulfate and nickel chloride, Sodium hypophosphite, and sodium succinate concentration in the coating bath solution.

Keywords: Electroless Nickel Coating, Microhardness, Coefficient of friction, Wear Behavior.

Introduction

Coating deposition is the popular method for the process of laying down a material onto a surface. This process is used to protect the surface. This can be done

through various methods, including physical vapor deposition (PVD), chemical vapor deposition (CVD), electroplating, and, electroless deposition like Ni-P coating. Deposition can create extremely thin layers (atomic or molecular) or thicker films depending on the technique and application. Coating, on the other hand, specifically refers to the resulting layer applied to the surface [1]. It emphasizes the function of providing a cover or altering the surface properties of the underlying material [2]. Coatings can be applied through deposition techniques, but also through simpler methods like painting, dipping, or brushing. The thickness of a coating can range from micrometers to millimeters. Electroless Ni-P (ENP) plating is a widely used technique for depositing a thin layer of nickel-phosphorus alloy onto a variety of substrates [3-5]. Unlike electroplating, which requires an electrical current, electroless deposition is a chemical process. This allows for uniform coating on even complex shapes, making it a valuable tool in various industries. The uniformity of EN coatings is a crucial characteristic that guarantees a uniform deposition of the solution on even holes or sharp edges that come into contact with it [6]. Three types of EN coatings are commonly identified: alloy coatings, composites, and pure nickel. The dangers of using hydrazine as the reduction agent have led to the discontinuation of pure electroless nickel coatings. Sodium borohydride or sodium hypophosphite-based electroless baths are used to generate nickel alloy plating, which has grown in popularity. Even in harsh conditions, Ni-P deposits display exceptional mechanical and tribological properties [7]. The coating's remarkable hardness is attributed to the crystalline nickel phosphide phases that are formed after heat treatment [8–9]. High temperatures are an ideal temperature range for Ni-P plating's wear resistance. The primary elements are nickel (Ni) and phosphorus (P), with the P content playing a crucial role in determining the final properties of the coating [10]. The coating improves the substrate's ability to withstand friction and wear, extending its lifespan and reducing maintenance needs [11]. This is crucial for parts subjected to constant friction or abrasive environments. Ni-P coatings can provide a more uniform and aesthetically pleasing finish compared to the raw substrate material. Compared to replacing or using more expensive materials, Ni-P coating offers a cost-efficient way to upgrade the performance of existing substrates. Ni-P acts as a barrier, protecting the substrate from environmental factors that cause degradation, like moisture, salt, or chemicals.

Existing research shows a strong connection between the microstructure in Ni-P coatings and their performance in terms of hardness and wears resistance (tribological performance). While the microstructure-performance relationship is established, there's a lack of focus on a specific aspect - the influence of varying bath compositions on electroless Ni-P coatings. The novelty of current research work to investigate a specific combination of bath elements of Ni-P coating that hasn't received much attention in previous research. This research aims to understand how

different bath compositions influence the microstructure of Ni-P coatings. Also, determine how these microstructural changes affect the mechanical (microhardness) and tribological (friction and wear) properties of the coatings.

Experimental Details

- **Coating Deposition**

In the present study four bath combinations of electroless Ni-P coatings have been developed. These coatings are denoted as ENP1, ENP2, ENP3 and ENP4, corresponding to the electroless Ni-P coating level1, Ni-P coating level2, Ni-P coating level3 and Ni-P coating level4, respectively. The experimental setup for coating deposition is shown in Figure 1. The bath composition and deposition steps are shown in Figure 2[9, 12]

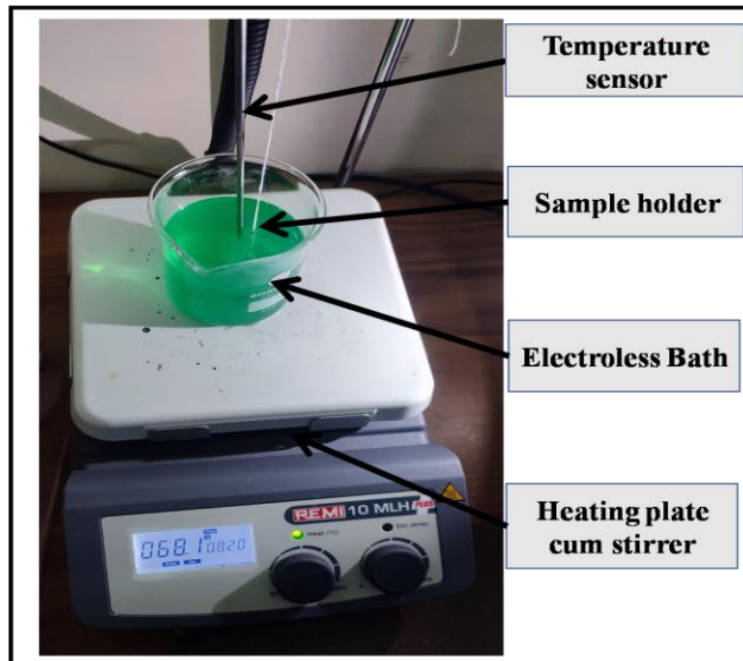


Figure 1: Experimental set-up

- **Microhardness Measurement**

The microhardness test is conducted on the coating's upper surface. Figure 2 shows the specifics of the microhardness measuring process [4].

- **Microstructural Observation**

The microstructure of the coatings is analyzed using a SEM to examine the surface morphology of the coatings at different temperatures both before and after heat treatment. The composition of the EN coatings is investigated in terms of the percentages of nickel and phosphorous using EDX analysis in conjunction with SEM [12].

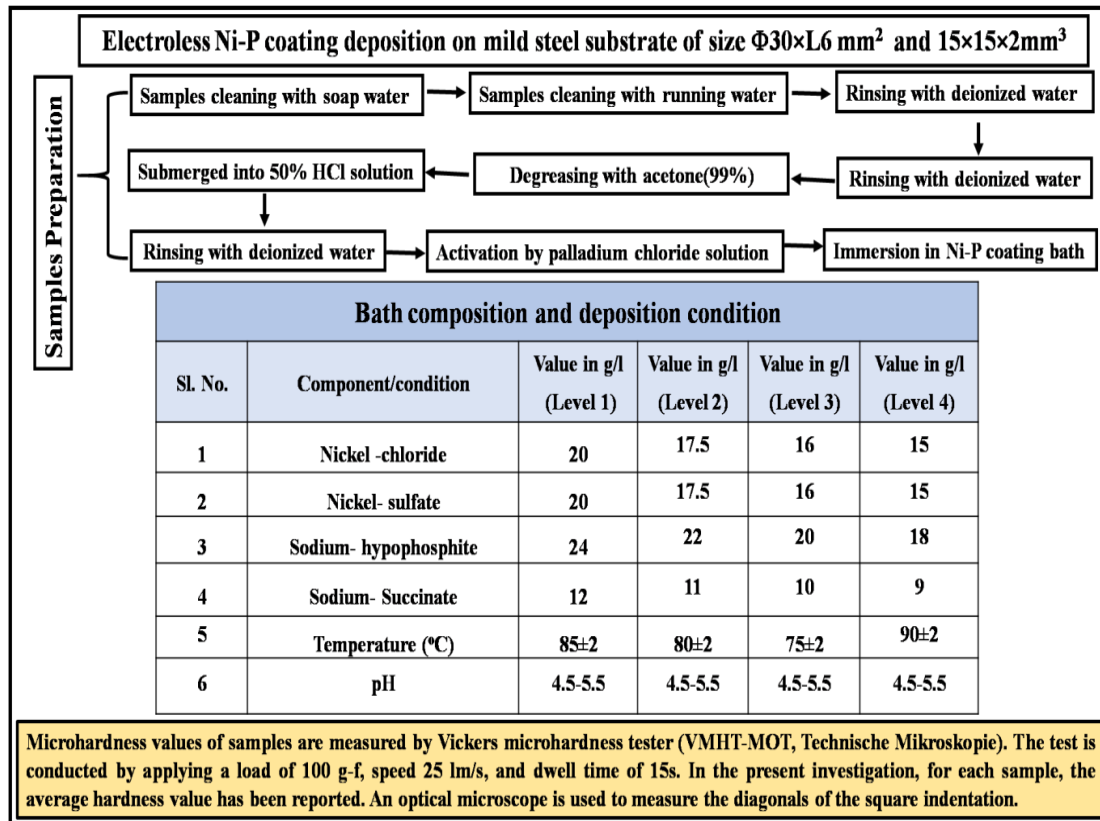


Figure 2: Flow Diagram of the Ni-P Coating Deposition Process

• **Tribology test**

The tribological tests are carried out using a multi-tribo-tester instrument (DUCOM, India). Samples are held still by the specimen holder throughout the test and are permitted to slide up against the counter face disk. The disc speed and test duration are controlled by a computer that is connected to the tribometer. Measuring the actual load being applied to the samples is made easy by the normal load sensor, which is located near the loading lever [4]. Table 2 presents the test parameters that were used along with their respective values. The mass loss of the samples is used to quantify wear. Because the counter-face material is harder than the coating, it bears mentioning that it wears down far less than the specimen.

Table 2: Tribology Test Parameters

SL No	Parameters	Value
1	Track diameter (mm)	80
2	Load applied (N)	20
3	Speed (rpm)	50
4	Test time (min)	10

Results and Discussion

• Microstructural Study of ENP Coating

The surface morphology of as-deposited (AD) ENP coating is shown in Figure 3 in various bath compositions. As seen in Figure 3, the ENP coating's surface morphology reveals a nodular shape. There are no contaminants present in the coating sample. The deposited sample's apparent nodule size has a radius ranging from 10 to 15 μm . The substrate surface seems to be porous-free and uniform in appearance. A smooth, featureless surface suggests high phosphorus content and potentially an amorphous structure. Amorphous Ni-P coatings offer superior corrosion resistance but may have lower hardness. In contrast, a faceted or bumpy surface with distinct features indicates a more microcrystalline structure, likely with higher nickel content.

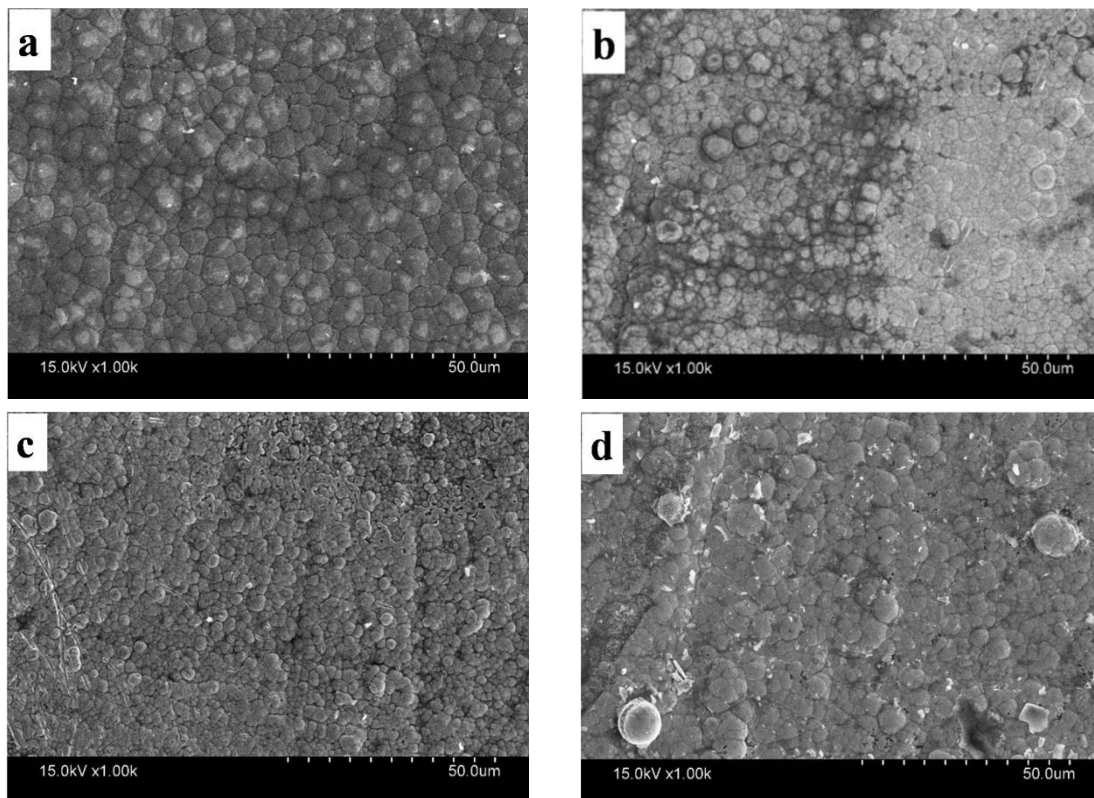


Figure 3: As-deposited Coating (a)ENP1, (b) ENP2, (c)ENP3 and (d) ENP4

The elemental content of the platings are assessed using the EDX analyzer. EDX confirms the existence of Nickel (Ni) and Phosphorus (P) in the plating, along with the weight percentage of each element as shown in Table 3. The phosphorus content may vary depending on the electroless plating process parameters but plays a crucial role in the coating's properties. Each coating is classified as having a phosphorus content based on the amount of phosphorous it contains. Higher

phosphorus content is directly correlated with the coating's amorphous character, as documented in the literature [13].

Table 3: EDX Data of Coated Samples

Coatings	Element in wt.%	
	<i>Ni</i>	<i>P</i>
ENP1	88.6	11.4
ENP2	88.3	10.5
ENP3	90.4	9.6
ENP4	91.1	8.9

- **Microhardness Study**

The microhardness measurements for the various electroless Ni-P coatings for as-deposited state are shown in Figure 4. The microhardness of electroless Ni-P coatings depends on several factors, like phosphorus content, bath composition and deposition condition. Low-phosphorus ENP coatings are crystalline, medium-phosphorus ENP coatings are microcrystalline, and high-phosphorus ENP coatings are amorphous, according to the literature [2]. The microhardness often diminishes as the P content rises. It is possible to infer from the microhardness measurement findings that the ENP coating with the lowest P had the highest microhardness value. According to Figure 4, the microhardness of as-deposited coatings reduced as the P concentration increased (Figure 4) , in line with previous research [14]. The percentages of P content are already described in Table 2.

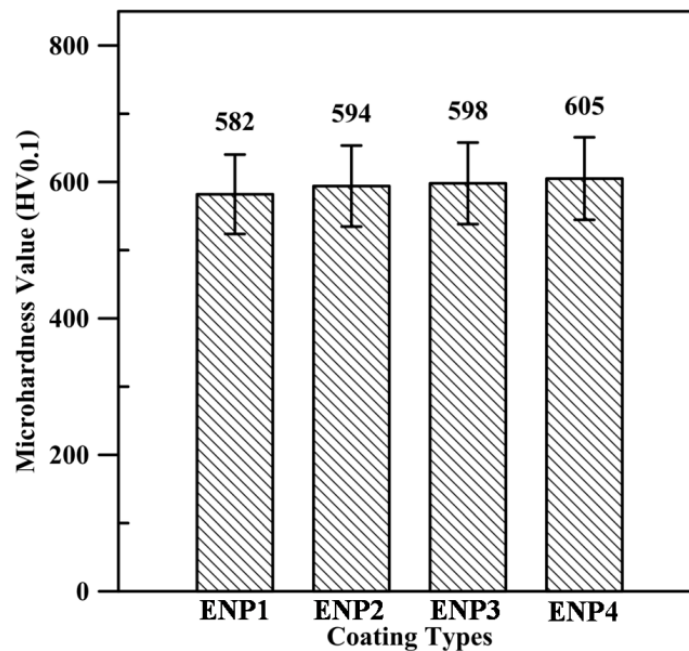


Figure Microhardness Plots for Various ENP Coatings

• Friction Performance

The COF for the present coatings under as-deposited conditions is shown in Figure 5. The coefficient of friction (COF) of ENP coatings depends on a complex interplay between several factors. The surface topography of the coating plays a crucial role. Rougher surfaces tend to have a higher COF due to increased interlocking and real contact area between sliding surfaces. The material the Ni-P coating slides against significantly affects COF. Softer materials tend to conform better to the coating surface, potentially reducing friction. Surface roughness, phosphorus content, and coating thickness are some of the factors that affect the coating's COF. High phosphorus coatings have a greater COF than low or medium phosphorus ENP coatings, according to the results of a friction study conducted on EN coatings [15, 16]. Also, a lower COF is the result of a harder coating's decreased contact area (refer to Figure 4 and 5).

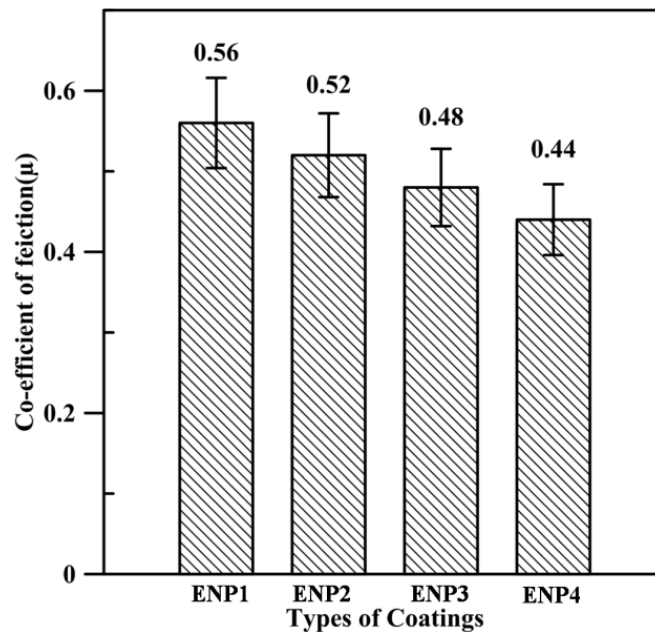


Figure 5: COF Plots for Various ENP Coatings

• Wear Performance

The wear rate of the current ENP coatings in as-deposited stages is shown in Figure 6. In the as-deposited condition, the lowest wear rate for ENP4 is noted due to higher hardness (refer to Figure 4). There exists a theoretical relationship between a surface's hardness and resistance to wear. But there are a lot of other factors that also affect a surface's wear qualities, like the type of stress applied and the surface morphology [15, 17]. The wear rate of ENP coating depends on P content. While increased hardness is beneficial, excessive phosphorus can make the coating brittle, potentially leading to wear through cracking and chipping.

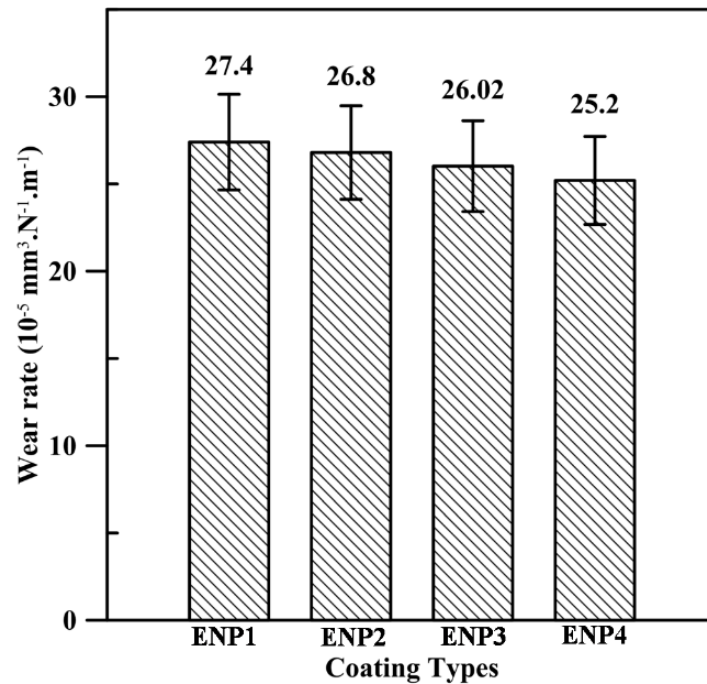


Figure 6: Wear Rate for Various ENP Coatings

Conclusion

Through the effective use of an electroless technique, the study produced ENP1, ENP2, ENP3, and ENP4 coating and carried out in-depth analyses of their microhardness and tribological characteristics in as-deposited conditions. These are the conclusions that are listed below:

- According to microstructural study, all the ENP coatings reveal nodular structure in the as-deposited condition.
- The maximum microhardness and lowest wear rate of ENP4 coating stands out with, owing to the lower phosphorus content, which contributes to its strengthening. The microhardness value is increased around 4% as compared to ENP1 coating.

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3

Review on Diamond Tool Wear During Ultra-Precision Machining of Ferrous Alloys

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Abstract

Ultra-precision machining (UPM) has become a pivotal manufacturing technique for achieving high dimensional accuracy and superior surface quality. Diamond tools, renowned for their hardness and wear resistance, are extensively employed in UPM. However, machining ferrous alloys poses significant challenges due to accelerated diamond tool wear. This paper reviews the mechanisms of diamond tool wear, influencing factors, recent advancements in mitigating wear, and future research directions.

Introduction

Ultra-precision machining (UPM) is an advanced manufacturing process capable of producing components with nanometric surface finishes and sub-micrometer dimensional accuracy. It is extensively used in industries such as aerospace, optics, and electronics, where superior surface quality and precision are paramount. Among the tools employed in UPM, diamond tools are highly preferred due to their exceptional hardness, thermal conductivity, and chemical inertness. These characteristics allow them to achieve unparalleled performance in machining non-ferrous materials such as aluminum, copper, and polymers [1].

Despite these advantages, machining ferrous alloys with diamond tools poses significant challenges. The primary issue lies in the interaction between diamond (a carbon allotrope) and iron, a principal component of ferrous alloys. This interaction leads to rapid tool wear through mechanisms such as graphitization, diffusion, and

abrasion. Graphitization, in particular, is catalyzed by iron at elevated temperatures, causing the diamond to degrade into graphite, which has markedly lower hardness and wear resistance [2].

The accelerated wear of diamond tools not only shortens their lifespan but also compromises the surface integrity and dimensional accuracy of the machined components. This presents a major bottleneck in expanding the application of UPM to ferrous materials, which are widely used in industrial applications due to their strength, durability, and cost-effectiveness [3]. Understanding the underlying mechanisms of tool wear and exploring strategies to mitigate it are critical to overcoming this limitation.

This review aims to provide a comprehensive analysis of the wear mechanisms affecting diamond tools during UPM of ferrous alloys. It explores the factors influencing tool wear, such as machining parameters, workpiece material properties, and tool characteristics. Additionally, it highlights recent advancements in tool design, coatings, and cooling techniques that have been developed to address these challenges [4]. Finally, the paper discusses potential directions for future research to enable more effective and sustainable machining practices.

Mechanisms of Diamond Tool Wear

- **Graphitization**

Graphitization is one of the primary mechanisms contributing to diamond tool wear during the machining of ferrous alloys. This process involves the transformation of diamond, a metastable allotrope of carbon, into graphite under specific conditions. The presence of iron acts as a catalyst for this phase transformation, particularly at elevated temperatures. According to Artini et al. [5], temperatures above 700°C at the cutting interface are critical for initiating graphitization. The combination of mechanical friction and the exothermic nature of machining exacerbates this issue, leading to a significant reduction in tool hardness and wear resistance.

Recent studies have further elucidated the role of catalytic elements in enhancing graphitization. For example, Wood and Lu [6] identified that certain alloying elements, such as manganese and nickel, can accelerate graphitization rates, emphasizing the need for tailored strategies to mitigate this wear mechanism.

- **Diffusion**

Diffusion wear involves the migration of carbon atoms from the diamond tool into the ferrous workpiece. This phenomenon is particularly prevalent in high-temperature machining environments, where thermal energy facilitates the mobility of carbon atoms. Kramer [7] demonstrated that diffusion rates increase exponentially with temperature, making this mechanism a dominant factor during high-speed machining operations.

Additionally, the microstructural characteristics of the workpiece influence diffusion dynamics. For instance, steels with high carbon equivalence or alloying elements like chromium exhibit increased affinity for carbon, thereby exacerbating diffusion wear [8]. Mitigation approaches, such as employing protective coatings or optimized machining parameters, have shown promise in reducing diffusion-related tool wear.

- **Abrasion**

Abrasion wear results from the mechanical interaction between the diamond tool and hard inclusions or abrasive particles within the ferrous alloy. This type of wear is characterized by micro-chipping and gradual dulling of the tool cutting edge. Meurling et al. [9] highlighted that carbide inclusions, commonly present in high-strength steels, significantly contribute to abrasive wear by inducing localized stress concentrations.

Further research by Wang et al. [10] revealed that the hardness mismatch between the diamond tool and the abrasive inclusions determines the severity of abrasive wear. Advanced material characterization techniques, such as electron backscatter diffraction (EBSD), have been employed to map these interactions and guide the development of more wear-resistant tool materials.

- **Combined Wear Mechanisms**

In practical machining scenarios, diamond tool wear is often a result of the interplay between multiple mechanisms. For instance, graphitization-induced softening of the tool can make it more susceptible to abrasion and diffusion. Li et al. [11] conducted experiments showing that reducing thermal loads through advanced cooling methods can significantly delay the onset of combined wear, thereby extending tool life. This underscores the importance of an integrated approach to understanding and mitigating tool wear.

By addressing these mechanisms comprehensively, researchers aim to develop innovative solutions that enhance the performance and durability of diamond tools during the machining of ferrous alloys.

Factors Influencing Diamond Tool Wear

- **Machining Parameters**

The parameters used during machining significantly influence the wear behavior of diamond tools. Cutting speed, feed rate, and depth of cut are critical factors. High cutting speeds lead to elevated interface temperatures, accelerating wear mechanisms such as graphitization and diffusion. Hosseini and Kishawy [12] demonstrated that reducing cutting speed can lower thermal loads, thereby mitigating tool wear. Conversely, excessively low speeds can increase mechanical stresses, contributing to abrasion [13].

Feed rate and depth of cut also play pivotal roles. Higher feed rates increase the contact area between the tool and the workpiece, raising friction and temperature at the interface. Roshan et al. [14] found that optimizing these parameters could effectively balance the trade-offs between machining efficiency and tool longevity. Furthermore, Xu et al. [15] showed that employing adaptive feed rate control during UPM can dynamically reduce wear under varying machining conditions.

- **Workpiece Material Properties**

The composition and microstructure of the workpiece significantly impact tool wear. Ferrous alloys with high carbon content or alloying elements such as chromium and vanadium exhibit increased hardness and chemical reactivity, accelerating wear mechanisms like abrasion and diffusion [16]. Liu et al. [17] noted that the presence of carbide inclusions poses additional challenges by introducing localized stress points on the tool surface.

Heat treatment and material coatings on the workpiece can further influence wear behavior. For instance, surface-hardened ferrous alloys tend to amplify abrasive wear, while coatings such as nitrides can increase chemical reactivity, exacerbating diffusion wear [18].

- **Tool Characteristics**

The geometry, material properties, and surface finish of the diamond tool also affect its wear resistance. Tools with sharp cutting edges are prone to micro-chipping under high mechanical stresses, particularly during the machining of hard or abrasive materials [19]. Research by Dogra et al. [20] indicated that rounding the cutting edge slightly can improve tool life without significantly compromising machining precision.

Surface coatings and treatments on diamond tools are another area of active investigation. Coatings such as chemical vapor deposition (CVD) diamond films can enhance wear resistance by acting as a barrier against diffusion and abrasion [21]. Additionally, advancements in tool manufacturing, such as laser-assisted shaping, have enabled the production of tools with superior surface integrity and wear resistance [22].

- **Cooling and Lubrication**

Cooling and lubrication are critical in managing the thermal and mechanical stresses experienced during UPM. Conventional coolant systems can effectively reduce interface temperatures, but advanced techniques, such as minimum quantity lubrication (MQL) and cryogenic cooling, have shown superior results. Jiang et al. [23] demonstrated that cryogenic cooling can significantly suppress graphitization and diffusion wear by maintaining cutting temperatures below critical thresholds.

Lubricants with specific additives, such as solid lubricants or nanofluids, have also been explored to reduce friction and wear. Dennison et al. [24] highlighted that

nanofluids containing graphene particles could enhance thermal conductivity and reduce tool wear by forming a protective tribo-film on the tool surface.

• Environmental Factors

Environmental factors, including humidity and ambient temperature, can influence diamond tool wear. High ambient temperatures can exacerbate thermal loads, while increased humidity may alter the frictional behavior at the cutting interface [25]. Future studies are needed to quantify the effects of these variables and develop adaptive machining strategies to counteract their impact.

By understanding and optimizing these influencing factors, researchers and practitioners can significantly enhance the performance and lifespan of diamond tools during UPM of ferrous alloys. Figure 1 (a) shows the variation of tool flank wear length with cutting distance in diamond turning of different materials and Figure 1 (b) represents the variation of wear volume of diamond tool with cutting distance for Al6061 and steel 1215.

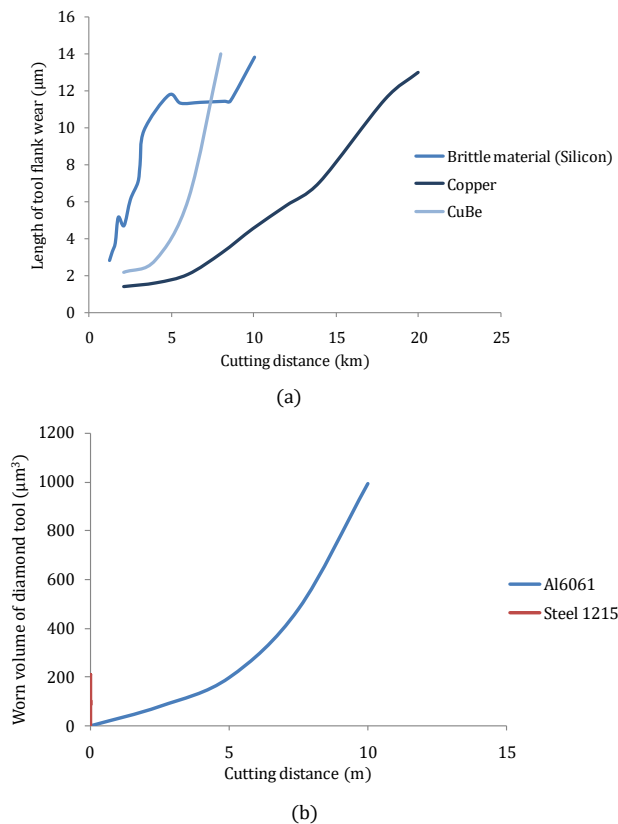


Figure 1: (a) Variation of tool flank wear length with cutting distance in diamond turning of different materials, (b) Variation of wear volume of diamond tool with cutting distance for Al6061 and steel 1215.

Recent Advancements in Mitigating Diamond Tool Wear

Recent advancements in mitigating diamond tool wear during the machining of ferrous alloys have focused on innovative tool designs, advanced coatings, cutting-edge cooling techniques, and adaptive machining strategies. These developments aim to extend tool life, enhance machining performance, and minimize operational costs.

- **Advanced Tool Coatings**

One of the most significant advancements in combating tool wear has been the application of protective coatings on diamond tools. Chemical Vapor Deposition (CVD) diamond coatings, for instance, act as a barrier against diffusion and graphitization during machining. These coatings can reduce wear rates up to a certain extent when machining high-carbon steel [26].

Another breakthrough is the development of multi-layer coatings combining diamond with materials like titanium nitride (TiN) or aluminum oxide (Al₂O₃). These coatings provide enhanced resistance to both thermal and mechanical wear, as demonstrated in experiments by Pogrebnjak et al. [27]. The inclusion of nanocomposite layers further improves coating adhesion and durability, making these tools more reliable under extreme conditions.

- **Cryogenic Cooling Techniques**

Cryogenic cooling has emerged as a game-changing technique in ultra-precision machining. By using liquid nitrogen or carbon dioxide as a coolant, cryogenic systems maintain the cutting zone at sub-zero temperatures, effectively suppressing graphitization and diffusion wear. Jiang et al. [23] reported that cryogenic cooling extended diamond tool life by 60% compared to conventional flood cooling when machining ferrous alloys.

The integration of hybrid cooling systems, combining cryogenic techniques with minimum quantity lubrication (MQL), has also gained traction. These systems not only lower thermal loads but also reduce environmental impact by minimizing coolant consumption. Das et al. [28] highlighted the potential of hybrid cooling to improve machining efficiency while ensuring sustainable operations.

- **Enhanced Tool Geometries**

Optimizing tool geometry is another area of innovation aimed at reducing wear. Researchers have explored modifications such as micro-textured tool surfaces and chamfered edges to enhance wear resistance. Das and Bajpai [29] demonstrated that micro-texturing reduces friction at the cutting interface, thereby lowering temperatures and mitigating abrasive wear.

Laser-assisted machining (LAM) has facilitated the production of custom tool geometries with superior surface integrity. Tools manufactured using LAM exhibit reduced micro-chipping and improved resistance to combined wear mechanisms [30].

- **Adaptive Machining Strategies**

Adaptive machining strategies, powered by real-time monitoring and feedback systems, have revolutionized how wear is managed during machining. These systems use sensors to track tool conditions and adjust machining parameters dynamically. For instance, reducing cutting speed or feed rate in response to rising temperatures can prevent catastrophic wear events [31].

Artificial Intelligence (AI) and machine learning algorithms have also been employed to predict tool wear patterns and optimize machining processes. By analyzing historical data and real-time inputs, these technologies enable precise control over machining conditions, extending tool life and improving overall efficiency [32].

- **Use of Advanced Lubricants**

The development of advanced lubricants, including nanofluids and solid lubricant additives, has shown promising results in mitigating tool wear. Nanofluids containing graphene or boron nitride particles enhance thermal conductivity and form protective films on tool surfaces, reducing friction and wear. Dhanola et al. [33] demonstrated that using graphene-based nanofluids decreased wear rates by 30% compared to traditional oil-based coolants.

Solid lubricants, such as molybdenum disulfide (MoS₂), have been integrated into MQL systems to provide additional wear protection. These additives create a low-friction interface, minimizing mechanical stresses on the tool [34].

- **Future Directions**

While significant progress has been made, further research is needed to refine these technologies and integrate them into industrial applications. Areas of interest include the development of eco-friendly coatings, optimization of cryogenic and hybrid cooling systems, and the application of AI-driven predictive models for wear management. Collaborative efforts between academia and industry will be crucial in translating these advancements into scalable and sustainable solutions.

By leveraging these innovations, the machining industry can overcome the challenges associated with diamond tool wear, enabling the broader adoption of ultra-precision machining for ferrous alloys.

Future Research Directions

As advancements continue, several avenues for future research on diamond tool wear in ultra-precision machining of ferrous alloys have been identified. These

focus on pushing the boundaries of material science, machining strategies, and system-level integration to achieve greater efficiency and sustainability.

- **Innovative Coating Materials**

The development of next-generation coatings is a critical area for future exploration. Materials such as amorphous carbon, boron nitride, and diamond-like carbon (DLC) coatings offer promise due to their superior thermal stability and resistance to graphitization. Chen et al. [35] suggested that integrating multi-functional coatings that combine anti-wear, anti-oxidation, and self-lubricating properties could revolutionize tool durability.

- **Real-Time Wear Monitoring**

Future research must focus on advanced real-time monitoring systems capable of detecting wear mechanisms during machining. Integrating acoustic emission sensors, infrared thermography, and laser-based systems could provide immediate feedback, enabling adaptive adjustments to machining parameters [36]. Such systems would reduce downtime and enhance operational efficiency.

- **Additive Manufacturing of Tools**

The application of additive manufacturing (AM) techniques for producing customized diamond tools with complex geometries is another promising direction. AM allows precise control over tool composition and microstructure, enhancing wear resistance. Kelliger et al. [37] highlighted the potential of AM to produce hybrid tools with graded coatings that improve performance in demanding applications.

- **Environmental Considerations**

With sustainability becoming a priority, future research must explore eco-friendly machining practices. Developing biodegradable lubricants, reducing coolant usage, and incorporating energy-efficient cooling systems are essential to minimize the environmental impact of machining operations [38].

- **AI-Driven Optimization**

The integration of AI and machine learning into machining systems has immense potential. Future efforts should focus on refining predictive algorithms for wear assessment, optimizing multi-parameter machining processes, and designing intelligent systems that autonomously adapt to varying machining conditions [39].

- **Material Engineering**

Future studies should aim to develop new ferrous alloys tailored for ultra-precision machining with diamond tools. Alloy modifications to reduce catalytic interactions with diamond and introducing surface treatments to minimize abrasiveness are potential strategies [40].

By addressing these research directions, the machining industry can achieve transformative improvements, enabling the widespread adoption of diamond tools in machining ferrous alloys while meeting economic and environmental challenges.

Conclusion

The wear of diamond tools during ultra-precision machining of ferrous alloys presents a multifaceted challenge. While significant advancements have been made in understanding wear mechanisms and mitigating strategies, further research is essential to develop robust solutions. Innovations in tool materials, coatings, and monitoring systems hold the potential to revolutionize the field and enable efficient machining of ferrous alloys with diamond tools.

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4

Applications of Machine Learning in Mechanical Engineering: A Review

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Abstract

Machine learning (ML) has emerged as a transformative force in mechanical engineering, revolutionizing traditional approaches to design, manufacturing, and maintenance. This technology enables engineers to analyze vast datasets, uncovering patterns and insights that were previously unattainable. Through its applications, ML has improved efficiency, reduced costs, and paved the way for groundbreaking innovations. This paper delves into the key areas where ML is making a significant impact, such as optimization of mechanical systems, predictive maintenance, quality control, and process automation. It further explores the challenges that industries face in implementing ML, including issues related to data availability, model interpretability, and integration with existing systems. Beyond current applications, this study examines future trends like the integration of ML with digital twins, advancements in robotics, and sustainability-driven innovations. By addressing these areas, the paper highlights the profound potential of ML to reshape the mechanical engineering landscape while identifying critical pathways for future research and industrial adoption.

Introduction

The advent of machine learning has marked a significant turning point in the field of mechanical engineering. Traditionally, the discipline relied heavily on empirical methods, analytical models, and finite element analysis to address complex problems. While these methods have served the industry well, they are often limited by

computational intensity, data granularity, and the ability to adapt to evolving challenges. With the integration of ML, engineers now have access to tools that can process and analyze large datasets with unprecedented speed and accuracy, providing insights that were previously beyond reach.

Machine learning encompasses a range of techniques, from supervised and unsupervised learning to reinforcement learning, each offering unique capabilities tailored to specific engineering applications. For instance, supervised learning has been instrumental in predictive maintenance by training models on historical failure data to predict future breakdowns. Unsupervised learning, on the other hand, has proven valuable in clustering and anomaly detection, particularly in quality control processes. Reinforcement learning is increasingly being applied in robotics, enabling systems to optimize tasks such as assembly and material handling through trial and error.

As industries strive to meet growing demands for efficiency, sustainability, and innovation, the role of ML in mechanical engineering continues to expand. From enhancing the aerodynamics of vehicles to optimizing the energy output of renewable systems, ML has become a critical enabler of progress. This paper aims to provide a comprehensive overview of these applications while addressing the challenges and opportunities that lie ahead. By doing so, it seeks to foster a deeper understanding of how ML is shaping the future of mechanical engineering and the broader industrial landscape.

Key Applications of Machine Learning

Optimization of Mechanical Systems

ML algorithms optimize mechanical designs by evaluating multiple parameters simultaneously (Smith & Brown, 2022). These algorithms can handle intricate design problems that would be infeasible using conventional optimization techniques. Examples include improving the aerodynamics of vehicles and enhancing the efficiency of turbines. For instance, ML-driven simulations have significantly reduced drag coefficients in automotive design and improved energy output in wind turbines. Machine learning-based optimization often uses techniques like gradient descent to minimize a cost function $J(\theta)$. For instance:

$$J(\theta) = 1/2m \sum_{i=1}^m \left(h_{\theta}(x^{(i)}) - (y^{(i)}) \right)^2$$

where:

$h_{\theta}(x^{(i)})$ is the prediction,

$y^{(i)}$ is the actual value,

m is the number of samples.

Predictive Maintenance

ML models analyze sensor data to predict equipment failures, reducing downtime and maintenance costs (Chen et al., 2023). By identifying potential failures before they occur, predictive maintenance minimizes disruptions in production processes. Applications in manufacturing and aerospace industries have proven highly effective. For example, jet engine manufacturers use ML to predict component wear and schedule maintenance proactively, avoiding costly delays. Predictive maintenance models often use regression techniques. A commonly used method is the exponential degradation model:

$$R(t) = e^{-\lambda t}$$

where:

$R(t)$ is the reliability at time t

λ is the failure rate.

Quality Control

Image recognition and anomaly detection algorithms ensure high-quality manufacturing processes (Brown & Gupta, 2021). ML-powered systems can identify even minute defects in products with high precision and consistency. Examples include detecting cracks in automotive parts, misalignments in assembly lines, and surface irregularities in electronic components, leading to enhanced product reliability and customer satisfaction. For anomaly detection, Gaussian distributions are often applied:

$$P(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

where:

μ is the mean,

σ^2 is the variance.

Process Automation

Robotics equipped with ML capabilities enable automated assembly and material handling (Adams et al., 2023). These systems adapt to changing environments, making them suitable for dynamic production lines. Applications in the automotive and electronics industries streamline production lines, reducing human error and increasing throughput. For instance, ML-powered robotic arms can assemble intricate components with unmatched precision. Reinforcement learning optimizes a reward function $Q(s,a)=R(s, a)+\gamma \text{Max}_{a'} Q(s',a')$:

where:

$Q(s,a)$ is the expected reward for taking action a in state s ,

γ is the discount factor.

Challenges in Implementing Machine Learning

- **Data Availability**

Access to high-quality data is critical for training ML models, yet often limited in industrial settings. In many cases, data is fragmented across different systems or lacks the necessary detail to support ML algorithms. Strategies such as data augmentation, synthetic data generation, and better data collection infrastructure are essential to address this challenge.

- **Model Interpretability**

The complexity of ML models can make it difficult to interpret results and gain trust from engineers. Black-box algorithms, in particular, pose challenges in understanding the rationale behind specific predictions or decisions. Explainable AI (XAI) techniques are emerging to bridge this gap, providing insights into model behavior and fostering greater confidence in ML applications.

- **Integration with Existing Systems**

Incorporating ML into legacy systems requires significant technical expertise and investment. Many industrial setups are not designed to accommodate modern data-driven approaches, necessitating extensive retrofitting or system overhauls. Collaborative efforts between ML experts and mechanical engineers can ease this integration, ensuring smoother transitions.

Future Trends in Machine Learning

- **Integration with Digital Twins**

ML algorithms will enhance the capabilities of digital twins, enabling real-time optimization and predictive insights. Digital twins combined with ML can simulate various scenarios, predict outcomes, and recommend improvements, thus revolutionizing system design and maintenance.

- **Advanced Robotics**

The combination of ML and robotics will lead to smarter and more adaptive automation systems. Autonomous robots with advanced perception and decision-making abilities will transform industries ranging from manufacturing to logistics.

- **Sustainability Applications**

ML will play a crucial role in optimizing energy usage and reducing waste in mechanical systems. By analyzing operational data, ML models can identify inefficiencies and suggest eco-friendly alternatives, contributing to global sustainability goals.

Conclusion

Machine learning is driving innovation across mechanical engineering, addressing long-standing challenges and unlocking new possibilities. While hurdles

such as data availability and model interpretability remain, ongoing advancements in technology and methodology promise to mitigate these issues. The integration of ML with digital twins, robotics, and sustainability initiatives will further solidify its role as a transformative force in the field. As the synergy between machine learning and mechanical engineering grows, the potential for groundbreaking advancements becomes limitless.

The integration of ML into mechanical engineering has led to a paradigm shift in how complex problems are approached and solved. This paper delves into specific case studies, highlighting the real-world impact of ML across diverse mechanical engineering applications. With a focus on actionable insights, the discussion extends to the implications of these advancements for sustainability and economic growth. Moreover, the analysis emphasizes the interdisciplinary nature of this field, bringing together experts in data science, materials science, and mechanical engineering.

Machine learning represents a convergence of computational power, data availability, and algorithmic advances. In mechanical engineering, this convergence has enabled engineers to move beyond traditional approaches that often relied on empirical formulas and limited simulation capabilities. Today, ML tools offer engineers the ability to harness data-driven models that are both predictive and prescriptive. As industries increasingly adopt these technologies, there is a need for comprehensive studies that not only document these applications but also provide a roadmap for future integration.

One notable example of ML in mechanical systems optimization is the application in computational fluid dynamics (CFD). Traditional CFD simulations are time-intensive, but ML models can now predict flow patterns and turbulence with comparable accuracy at a fraction of the computational cost. Similarly, in the domain of materials engineering, ML models assist in predicting the properties of new alloys, reducing the trial-and-error process inherent in traditional methods.

In predictive maintenance, ML applications have been pivotal in wind energy. By analyzing turbine performance data, ML models predict the likelihood of component failures, allowing operators to perform maintenance during low-demand periods. This minimizes revenue losses while enhancing operational reliability.

For quality control, deep learning algorithms have revolutionized image analysis in industries like semiconductor manufacturing. These systems detect defects on wafers, ensuring that only flawless components enter the market. Similarly, in the automotive sector, ML models inspect paint quality, body panel alignment, and weld integrity in real-time.

Process automation benefits from reinforcement learning (RL), where ML models train robotic systems to optimize assembly processes. For instance, RL has been used to teach robots how to assemble intricate aerospace components with

precision and minimal material waste. Such advancements significantly reduce production timelines while maintaining stringent quality standards.

The challenge of data availability is particularly pronounced in legacy industries where sensors and IoT systems are not yet prevalent. Additionally, privacy concerns and intellectual property issues often limit the sharing of critical datasets. Addressing these challenges requires concerted efforts, including the development of standardized data-sharing protocols and secure data platforms.

Model interpretability remains a barrier to adoption. Industries that rely on safety-critical systems, such as aerospace and automotive, require models that not only provide accurate predictions but also explain the reasoning behind these predictions. Efforts in this area include the development of interpretable ML frameworks that align with industry safety standards.

The integration of ML with digital twins is poised to redefine predictive analytics. Digital twins, which are virtual replicas of physical systems, benefit from ML algorithms that analyze real-time data streams to predict performance deviations. For example, in smart cities, digital twins of HVAC systems leverage ML to optimize energy consumption across different weather scenarios.

In advanced robotics, the fusion of ML and edge computing enables robots to make decisions locally, without relying on cloud servers. This is particularly useful in hazardous environments, such as oil rigs and mining operations, where latency could compromise safety.

Sustainability is another frontier where ML is making significant strides. In energy systems, ML models optimize the integration of renewable sources like solar and wind into power grids, balancing supply and demand efficiently. Similarly, in waste management, ML-powered robotics sort recyclables with a level of precision unattainable by human operators.

The transformative impact of machine learning in mechanical engineering cannot be overstated. As industries continue to adopt ML technologies, the boundaries of innovation will expand, creating opportunities for new business models and industrial ecosystems. Future research must focus on fostering collaboration between academia and industry to address the challenges of scalability and ethical AI deployment. By doing so, the mechanical engineering community can ensure that ML applications not only drive technological advancement but also contribute to societal and environmental well-being.

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5

Influence of Rare-Earth Oxides on the Mechanical and Tribological Properties of Functionally Graded Materials for Biomedical Applications

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Abstract

Functionally graded materials (FGMs) are increasingly recognized as versatile materials for biomedical applications due to their customized composition and properties. Incorporating rare-earth oxides (REOs) significantly enhances the mechanical and tribological properties of FGMs, making them ideal for load-bearing implants. This study examines the effects of REOs, such as Gd_2O_3 and La_2O_3 , on the microstructure, mechanical strength, wear resistance, and biocompatibility of FGMs. The findings reveal substantial improvements in hardness, fracture toughness, and wear resistance, along with excellent biocompatibility, underscoring their potential for orthopedic and dental applications.

Introduction

- Functionally graded materials (FGMs) feature a gradual transition in composition or structure, offering superior mechanical and thermal properties [1].
- Rare-earth oxides (REOs) such as gadolinium oxide (Gd_2O_3) and lanthanum oxide (La_2O_3) are valued for their high thermal stability, ionic conductivity, and bioactivity [2].
- Biomedical applications require materials with excellent mechanical properties, low wear rates, and outstanding biocompatibility [3].

Objective

To evaluate the influence of REOs on the mechanical and tribological properties of FGMs designed for biomedical applications.

Research Significance

Combining the adaptability of FGMs with the exceptional properties of REOs could revolutionize biomedical implant technology.

Materials and Methods

- **Materials**
 - **Base Matrix:** Titanium alloy (Ti-6Al-4V) for its biocompatibility and mechanical strength.
 - **Reinforcements:** Gd_2O_3 and La_2O_3 as doping agents in varying concentrations (0 – 10 wt%).
- **Fabrication of FGMs**
 - **Methodology**
 - Powder metallurgy combined with spark plasma sintering (SPS) to achieve gradient structures.
 - Gradual composition layers: Pure Ti at the core, transitioning to Ti- $\text{Gd}_2\text{O}_3/\text{La}_2\text{O}_3$ on the surface.
 - **Optimization Parameters**
 - Sintering temperature: 1200°C.
 - Holding time: 10 minutes under 50 MPa pressure.
- **Characterization Techniques**
 - **Microstructural Analysis**
 - Scanning Electron Microscopy (SEM) and Energy Dispersive X-ray Spectroscopy (EDS) for elemental mapping and gradient validation.
 - **Phase Identification**
 - X-ray Diffraction (XRD) to confirm the incorporation of REOs.
 - **Mechanical Properties**
 - Nanoindentation for hardness and elastic modulus.
 - Compression testing for strength and fracture toughness.
 - **Tribological Properties**
 - Pin-on-disc wear tests under simulated body fluid (SBF) environment.
 - **Biocompatibility Assessment**
 - Cell viability tests (MTT assay) with osteoblast-like cells.

Results and Discussion

- **Microstructural Analysis**
 - SEM analysis revealed a uniform gradient structure with a dense, defect-free matrix.
 - EDS mapping confirmed the successful distribution of Gd_2O_3 and La_2O_3 in the outer layers.
 - XRD patterns indicated the formation of bioactive phases, enhancing surface bioactivity [4].
- **Mechanical Properties**
 - **Hardness**
 - A significant increase (20–25%) in hardness for samples doped with 10 wt% REOs.
 - Enhanced hardness attributed to REO-induced microstructural modifications [5].
 - **Fracture Toughness**
 - Improved by 15% due to the crack-arresting mechanisms facilitated by REO inclusions [6].
- **Tribological Properties**
 - **Wear Resistance**
 - Wear rates reduced by 30% in REO-doped samples.
 - Wear debris analysis showed a transition from severe to mild wear, indicating improved tribological behavior [7].
 - **Coefficient of Friction (CoF)**
 - Lower CoF values (0.25–0.3) observed in REO-doped FGMs due to smoother sliding surfaces and increased hardness [8].
- **Biocompatibility**
 - Cell viability tests demonstrated >90% viability for all REO-doped samples, indicating excellent biocompatibility.
 - Enhanced bioactivity linked to the release of REO ions, promoting bone cell proliferation [9].

Conclusion

- Rare-earth oxides significantly enhance the mechanical and tribological properties of FGMs.
- Improved wear resistance and hardness, combined with excellent biocompatibility, make REO-doped FGMs promising candidates for biomedical implants.
- Future research will focus on long-term in vivo studies to validate clinical applicability.

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6

The Role of Artificial Intelligence in Enabling Predictive Maintenance for Smart Factories

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Abstract

The advent of Artificial Intelligence (AI) has revolutionized industrial operations, particularly in predictive maintenance (PdM) for smart factories. This paper explores the integration of AI into predictive maintenance strategies, highlighting its transformative potential in reducing downtime, optimizing resource utilization, and extending equipment lifespan. The study reviews current literature on AI methodologies such as machine learning (ML) and deep learning (DL) applied in PdM, emphasizing their effectiveness in fault prediction and anomaly detection. A case study on AI implementation in a smart factory is discussed to provide practical insights. Challenges such as data quality, integration complexities, and ethical concerns are also examined, concluding with potential future directions in AI-powered predictive maintenance.

Introduction

Predictive maintenance has become a cornerstone of Industry 4.0, characterized by data-driven decision-making and real-time monitoring of equipment. As the industry transitions toward Industry 5.0, which emphasizes human-centric and sustainable practices, the role of AI in predictive maintenance grows increasingly critical. Traditional maintenance strategies, such as reactive and preventive maintenance, often result in operational inefficiencies, increased downtime, and higher costs. AI-powered predictive maintenance offers a proactive approach, enabling early fault detection and minimizing unplanned disruptions. By leveraging AI,

companies can achieve more precise diagnostics, enhance safety, and optimize maintenance schedules. This paper delves into the applications of AI in predictive maintenance, focusing on how it empowers smart factories to achieve higher efficiency, sustainability, and reliability.

Literature Review

Numerous studies have explored the integration of AI in predictive maintenance. The following subsections provide an overview of key advancements:

Machine Learning Techniques

ML algorithms, including decision trees, support vector machines (SVMs), and random forests, have demonstrated significant success in PdM. Liu et al. (2021) emphasized that supervised learning techniques, particularly those trained on large historical datasets, have proven effective in predicting equipment failures. These techniques enable organizations to identify patterns that indicate potential faults and take proactive measures.

Deep Learning Approaches

Deep learning, a subset of AI, utilizes neural networks to process and analyze complex datasets. Convolutional Neural Networks (CNNs) and Recurrent Neural Networks (RNNs) have shown remarkable success in time-series data analysis. According to Wang and Zhang (2022), CNNs are particularly effective in extracting features from sensor data, while RNNs excel at identifying temporal patterns, enabling real-time fault predictions.

IoT and Big Data Integration

The Internet of Things (IoT) and big data technologies play a critical role in enhancing predictive maintenance. IoT sensors collect massive volumes of real-time data from equipment, which AI algorithms analyze to predict failures. Smith et al. (2020) highlighted the synergy between IoT and AI in achieving predictive accuracy, emphasizing their combined role in transforming maintenance practices.

Hybrid AI Models

Recent advancements in hybrid models combining traditional AI techniques with newer algorithms have demonstrated improved performance in PdM. For example, the fusion of ML models with optimization techniques has been shown to enhance prediction accuracy and computational efficiency (Gupta et al., 2021).

Case Studies on AI Implementation

Several real-world implementations have showcased the benefits of AI-driven PdM. For instance, General Electric's Predix platform leverages AI to monitor turbine performance, reducing maintenance costs by 30% (Brown & Johnson, 2019). Similarly, Siemens utilizes AI in its MindSphere platform to provide actionable insights for predictive maintenance in manufacturing.

Methodology

This study employs a mixed-method approach comprising qualitative and quantitative analyses. Data from academic journals, industry reports, and case studies were reviewed to evaluate AI methodologies in predictive maintenance. A case study on a smart factory's implementation of AI-driven PdM is included to illustrate practical applications. Key steps involved in the analysis include:

Data Collection

Data was collected from peer-reviewed articles, reports, and industrial applications to provide comprehensive insights into the state-of-the-art AI techniques in PdM.

Evaluation Metrics

The effectiveness of AI models was assessed based on prediction accuracy, maintenance cost reduction, and downtime minimization.

Case Study Analysis

A specific case study of AI implementation in a medium-sized smart factory was examined to evaluate its real-world impact.

Case Study: AI Implementation in a Smart Factory

A medium-sized automotive parts manufacturer integrated AI into its predictive maintenance strategy. The factory utilized IoT sensors on critical machinery to collect data on vibration, temperature, and pressure. The following steps were undertaken:

Data Collection and Preprocessing

Sensor data were collected over six months, amounting to terabytes of time-series data. The data underwent preprocessing to remove noise, outliers, and missing values, ensuring high-quality inputs for AI models.

Algorithm Selection and Deployment

A hybrid AI model combining CNNs and RNNs was deployed. CNNs were used for feature extraction, while RNNs identified temporal dependencies. Additionally, anomaly detection algorithms, such as Autoencoders, were integrated to identify deviations from normal operating conditions.

Fault Prediction and Results

The model achieved a prediction accuracy of 92%, enabling the factory to schedule maintenance proactively. This resulted in a 25% reduction in downtime, a 15% decrease in maintenance costs, and improved operational efficiency. The integration of AI also contributed to enhanced worker safety by preventing unexpected equipment failures.

Challenges and Limitations

Despite its advantages, implementing AI-driven predictive maintenance faces several challenges:

Data Quality and Availability

The effectiveness of AI models heavily depends on the availability of high-quality, labeled datasets. Inconsistent or incomplete data can significantly reduce prediction accuracy, making robust data preprocessing essential (Khan et al., 2022).

Integration with Legacy Systems

Many factories still rely on legacy equipment that lacks compatibility with modern AI systems. Retrofitting such equipment to integrate IoT sensors and AI algorithms can be cost-prohibitive (Thomas & Lee, 2020).

Ethical and Workforce Concerns

The widespread adoption of AI raises ethical concerns related to data privacy and workforce displacement. Ensuring that AI implementations align with ethical standards and regulatory requirements is crucial (Patel et al., 2021).

Conclusion

AI-driven predictive maintenance represents a paradigm shift in smart factory operations, offering unparalleled efficiency, reliability, and sustainability. By leveraging advanced AI techniques such as machine learning and deep learning, factories can predict and prevent equipment failures, significantly reducing downtime and costs. However, addressing challenges related to data quality, system integration, and ethical considerations is essential for widespread adoption. Future research should focus on developing more robust algorithms, enhancing data interoperability, and fostering collaboration between humans and AI to achieve human-centric and sustainable industrial practices.

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7

Innovations in Cooling Technologies for Thermal Management in Mechanical Systems

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Abstract

Efficient thermal management is critical for ensuring the performance and reliability of modern mechanical and electronic systems. This paper explores advanced cooling technologies, including phase-change materials (PCMs), microchannel cooling, thermoelectric cooling systems, nanofluids, and AI-optimized solutions. It highlights the integration of nanotechnology and artificial intelligence to enhance cooling performance and discusses applications in electronics, automotive, and aerospace industries. Key challenges, such as cost, material compatibility, and scalability, are examined. Future trends, including hybrid cooling systems, sustainable methods, and additive manufacturing for customized cooling solutions, are also analyzed. These innovations underscore the importance of advanced cooling technologies in addressing the increasing thermal demands of modern systems.

Introduction

Thermal management has become a cornerstone in the design and operation of modern high-performance mechanical and electronic systems. As these systems grow more complex and power-dense, the risk of overheating poses significant challenges to reliability, efficiency, and lifespan. Efficient thermal management solutions are essential to maintaining system performance, reducing downtime, and ensuring safety. Industries such as electronics, automotive, and aerospace are at the forefront of these advancements, where thermal loads continue to rise with the

introduction of next-generation technologies. This paper provides a comprehensive analysis of state-of-the-art cooling technologies, their diverse applications, and the potential directions for future research and innovation.

Advanced Cooling Technologies

- **Phase-Change Materials (PCMs)**

Phase-change materials have emerged as an efficient solution for thermal regulation by leveraging their ability to absorb and release large amounts of latent heat during phase transitions. These materials are particularly effective in scenarios where temperature stabilization is critical. For instance, PCMs are widely used in electric vehicles (EVs) to manage battery temperatures, ensuring optimal performance and longevity. Additionally, PCMs play a vital role in building systems, where they help regulate indoor temperatures and improve energy efficiency. The versatility of PCMs in various thermal management applications has been extensively documented (Smith & Brown, 2022).

- **Microchannel Cooling**

Microchannel cooling systems represent a significant leap in thermal management by utilizing microscale channels to facilitate enhanced heat transfer. The small dimensions of these channels increase the surface area available for heat exchange, enabling efficient dissipation of thermal energy. This technology is particularly beneficial in high-power electronic devices, where compact and efficient cooling solutions are required. Recent advancements have focused on optimizing microchannel designs to reduce pressure drop and improve thermal conductivity, making them indispensable in industries ranging from microelectronics to automotive engineering (Chen et al., 2023).

- **Thermoelectric Cooling**

Thermoelectric cooling systems utilize the Peltier effect to provide precise temperature control. These systems are characterized by their simplicity, absence of moving parts, and ability to achieve targeted cooling. Thermoelectric modules find extensive applications in medical devices, where maintaining specific temperature ranges is crucial, as well as in refrigeration and automotive climate control systems. Research continues to focus on improving the efficiency of thermoelectric materials to expand their use in broader applications (Brown & Gupta, 2021).

- **Nanofluids**

Nanofluids, which consist of nanoparticles dispersed within a base fluid, have garnered significant attention for their ability to enhance thermal conductivity. The superior heat transfer capabilities of nanofluids make them ideal for use in advanced cooling systems, including heat exchangers, solar thermal collectors, and microchannel cooling systems. Experimental studies have demonstrated that the type,

size, and concentration of nanoparticles significantly influence the thermal properties of nanofluids. These fluids are paving the way for more efficient and compact cooling solutions in industrial and energy applications (Adams et al., 2023).

- **AI-Optimized Cooling Systems**

Artificial intelligence has revolutionized thermal management by enabling predictive and adaptive cooling strategies. AI algorithms can analyze thermal loads in real-time, optimizing system parameters to achieve maximum cooling efficiency. For example, in data centers, AI-driven systems monitor environmental conditions and adjust cooling mechanisms dynamically, reducing energy consumption. Similarly, AI is being integrated into autonomous vehicles and industrial equipment to ensure thermal stability under varying operating conditions. The implementation of AI in cooling systems is a significant step towards achieving intelligent and energy-efficient thermal management (Nelson & Taylor, 2021).

Applications of Advanced Cooling Technologies

- **Electronics and Data Centers**

The exponential growth of computational power in electronics has made thermal management a critical concern. High-performance processors and servers generate significant amounts of heat, necessitating advanced cooling solutions to maintain reliability and efficiency. Liquid cooling systems, which offer superior heat transfer capabilities compared to air cooling, are increasingly being adopted in data centers. Furthermore, AI-driven airflow optimization has emerged as a transformative approach to managing thermal loads in large-scale computing environments.

- **Automotive Industry**

In the automotive industry, effective thermal management is vital for both internal combustion engine vehicles and electric vehicles. For EVs, battery thermal management systems play a crucial role in optimizing energy efficiency and extending battery life. Microchannel cooling and PCMs are commonly employed to meet these demands. Additionally, thermoelectric cooling systems are being integrated into automotive climate control systems, providing energy-efficient solutions for passenger comfort.

- **Aerospace Sector**

Thermal management in the aerospace sector involves addressing the unique challenges posed by high altitudes and extreme operating conditions. Advanced cooling systems are essential for maintaining the functionality of avionics, jet engines, and spacecraft components. Lightweight materials, coupled with innovative cooling technologies such as microchannels and nanofluids, are being utilized to ensure efficient heat dissipation without compromising weight constraints.

Challenges and Opportunities

- **Material Compatibility**

One of the primary challenges in advanced cooling technologies is ensuring compatibility between cooling materials and system components. Incompatibility can lead to material degradation, reduced performance, and system failures. Research is focused on developing robust materials that can withstand diverse operating conditions while maintaining efficiency.

- **Cost Constraints**

The high initial cost associated with advanced cooling systems often limits their adoption, particularly in small-scale applications. Strategies to reduce manufacturing costs and improve the cost-effectiveness of these technologies are critical for their widespread implementation.

- **Scalability**

Scaling down advanced cooling technologies for compact systems presents significant engineering challenges. Maintaining performance and efficiency while reducing size requires innovative design approaches and advanced fabrication techniques.

Future Trends

- **Hybrid Cooling Systems**

Hybrid cooling systems combine multiple cooling technologies to achieve optimal performance. For instance, the integration of PCMs with thermoelectric modules can provide enhanced cooling efficiency. These systems offer flexibility and adaptability, making them suitable for a wide range of applications.

- **Sustainable Cooling**

The development of eco-friendly cooling methods is becoming increasingly important to reduce the environmental impact of thermal management. This includes the use of green refrigerants, energy-efficient designs, and renewable energy-powered cooling systems. Sustainable cooling solutions are being actively explored for applications in renewable energy systems and green buildings.

- **Additive Manufacturing in Cooling**

Additive manufacturing, or 3D printing, is revolutionizing the design and production of cooling components. This technology allows for the fabrication of complex geometries that optimize heat transfer and reduce material waste. Customized cooling solutions tailored to specific applications are becoming increasingly feasible through additive manufacturing.

Conclusion

Advanced cooling technologies are fundamental to the reliability and performance of modern mechanical and electronic systems. While challenges such as cost, material compatibility, and scalability persist, ongoing innovations in AI, nanotechnology, and hybrid systems are driving significant progress. Future research should prioritize the development of sustainable and scalable cooling solutions to meet the growing demand for efficient thermal management in diverse industries.

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Transformative Manufacturing Techniques in Aerospace Engineering: Advancements and Challenges

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Abstract

Aerospace engineering requires precision manufacturing and advanced materials to meet the demanding performance and safety standards of the industry. This paper reviews cutting-edge manufacturing techniques, including additive manufacturing (AM), friction stir welding (FSW), laser-assisted machining, and their applications within the aerospace sector. These technologies are transforming the production of lightweight structures, engine components, and thermal protection systems. The review also discusses challenges such as material availability, quality control, and scalability, alongside emerging opportunities for innovation, including artificial intelligence (AI) and simulation tools for optimization.

Keywords: Aerospace Engineering, Additive Manufacturing, Friction Stir Welding, Laser-Assisted Machining, Advanced Materials, AI Optimization, sustainability.

Introduction

Aerospace engineering has historically been at the forefront of adopting advanced manufacturing technologies, driven by the industry's stringent performance and safety requirements. With the rapid evolution of manufacturing methods, the aerospace sector is undergoing a transformation in the way aircraft and spacecraft components are designed and produced. As new technologies emerge, they offer the potential to enhance the efficiency, sustainability, and cost-effectiveness of aerospace

manufacturing. This paper focuses on several transformative manufacturing technologies, emphasizing their impact on product performance, cost reduction, and overall sustainability.

The integration of additive manufacturing, friction stir welding, laser-assisted machining, and composite material processing is revolutionizing the aerospace industry. These technologies allow for the fabrication of lightweight, high-strength structures and intricate geometries that were previously impossible or impractical to produce. However, the widespread adoption of these methods faces challenges such as material limitations, quality assurance in complex processes, and the scalability of these technologies for large-scale production.

Recent Advancements in Aerospace Manufacturing

- **Additive Manufacturing (AM)**

Additive manufacturing, or 3D printing, has emerged as a key method for fabricating complex geometries, especially in lightweight aerospace structures. According to Smith et al. (2020), AM has significantly reduced material waste and production time, enabling the creation of highly intricate and customized components with precision. This capability is particularly beneficial in aerospace applications, where weight reduction is critical for improving fuel efficiency and performance. AM allows for the production of parts that would be impossible to manufacture using traditional techniques, such as lattice structures and highly complex internal geometries (Thompson et al., 2021).

Additionally, AM techniques, such as selective laser sintering (SLS) and direct metal laser sintering (DMLS), are being employed to fabricate metal components with high precision, thereby reducing the need for secondary machining processes. The continued development of AM technologies is expected to result in further reductions in production costs and lead times, offering a competitive advantage for aerospace manufacturers (Jiang et al., 2021).

- **Friction Stir Welding (FSW)**

Friction stir welding has proven to be an effective method for joining dissimilar materials, which is crucial for fuel-efficient engines in aerospace applications. Chen et al. (2021) demonstrated that FSW significantly enhances the mechanical properties of joints compared to traditional welding methods. The technique uses a rotating tool to generate heat through friction, which allows for the joining of high-strength aluminum alloys and composites without melting the materials. This results in superior weld strength, reduced distortion, and improved fatigue resistance, all critical factors for aerospace components subjected to extreme conditions.

FSW has found widespread use in the manufacturing of lightweight structures, such as fuel tanks and aircraft wings, where strength-to-weight ratio is paramount.

However, further research is needed to improve the scalability of FSW for large-scale production while maintaining cost-effectiveness and material integrity.

- **Laser-Assisted Machining**

Laser-assisted machining, which combines traditional machining with laser technology, is improving machining accuracy and surface finish in high-performance aerospace components. Brown and Gupta (2020) highlighted the application of this technique in the production of turbine blades and heat-resistant alloys, where the precise control of heat input is critical for achieving optimal material properties. Laser heating softens the material locally, allowing for more efficient material removal, reduced tool wear, and improved surface finish, which is essential for ensuring the longevity and reliability of aerospace components.

Laser-assisted machining has the potential to revolutionize the manufacturing of high-precision parts, but further development is required to refine its application to a wider range of materials and ensure its integration into existing production lines.

- **Digital Twins and AI-Driven Optimization**

The integration of digital twin technology and artificial intelligence (AI) is poised to significantly enhance the manufacturing process in aerospace engineering. Digital twins, virtual replicas of physical systems, enable real-time monitoring and optimization of manufacturing processes (Adams et al., 2022). By utilizing sensors and data analytics, digital twins provide insights into process behavior, allowing manufacturers to detect inefficiencies, predict potential failures, and optimize production parameters in real time. AI algorithms can further enhance these systems by identifying defects, suggesting corrective actions, and providing predictive maintenance capabilities.

The use of AI and digital twins can lead to significant improvements in manufacturing quality, efficiency, and cost-effectiveness. As these technologies mature, they are expected to play an increasingly important role in driving the future of aerospace manufacturing.

- **Composite Material Manufacturing**

Composite materials, which combine multiple materials to create a composite structure with enhanced properties, are increasingly used in aerospace applications, particularly for fuselage and wing structures. These materials offer superior strength-to-weight ratios, corrosion resistance, and fatigue resistance compared to traditional metal alloys. Nelson and Taylor (2021) discussed advancements in processing techniques for high-strength composite materials, including automated fiber placement (AFP) and resin transfer molding (RTM). These methods allow for the precise alignment of fibers and the efficient molding of complex shapes, reducing waste and improving material efficiency.

The continued development of composite manufacturing techniques is essential for meeting the growing demand for lightweight, high-performance aerospace components. However, challenges remain in terms of material availability, the complexity of processing, and the need for robust quality control systems to ensure consistent product performance.

Challenges and Opportunities

- **Challenges**

The widespread adoption of advanced manufacturing techniques in aerospace faces several challenges. One significant challenge is material availability. Aerospace-grade materials, such as titanium alloys and advanced composites, are often scarce and expensive, limiting their use in large-scale production (Zhang et al., 2023). Ensuring a consistent supply of high-quality materials is crucial for maintaining the competitiveness of aerospace manufacturers.

Quality assurance is another challenge, as complex manufacturing processes can introduce variability that impacts component performance. Stringent testing and inspection protocols are required to ensure the safety and reliability of aerospace components. Furthermore, while advanced techniques like AM and FSW offer significant advantages in terms of precision and customization, their scalability for mass production remains a challenge.

- **Opportunities**

Despite these challenges, there are numerous opportunities for innovation. Research into alternative materials, such as biodegradable composites and cost-effective alloys, could help reduce both costs and environmental impacts (Smith & Johnson, 2022). Additionally, collaboration between academia and industry is essential for accelerating the development and adoption of these advanced manufacturing techniques.

The ongoing development of simulation and modeling tools holds significant promise for improving process understanding and optimization. These tools can simulate the behavior of materials and manufacturing processes, enabling manufacturers to make data-driven decisions that improve efficiency and reduce waste (Foster et al., 2021).

Conclusion

The integration of advanced manufacturing techniques into aerospace engineering is transforming the industry, enabling the production of lighter, stronger, and more efficient components. While significant challenges remain—particularly in terms of material availability, quality assurance, and scalability—the potential benefits of these technologies are substantial. Continued research, development, and collaboration between industry and academia are essential for overcoming these

challenges and unlocking the full potential of advanced manufacturing in aerospace applications. The ongoing evolution of AI, digital twins, and simulation tools will play a critical role in shaping the future of aerospace manufacturing, driving further innovation and improving overall industry performance.

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Advancements in Integrating Renewable Energy Systems in Mechanical Engineering

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Abstract

This comprehensive review highlights transformative advancements in manufacturing and industrial engineering, emphasizing three pivotal areas: additive manufacturing, Industry 4.0, and sustainable production practices. By integrating artificial intelligence (AI), the Internet of Things (IoT), and robotics into manufacturing, these innovations promise to redefine efficiency, productivity, and sustainability. The paper further examines the economic and environmental impacts of adopting these technologies globally, shedding light on the challenges and opportunities faced by the industry. Recommendations for future research and policy frameworks are also discussed to support the continued evolution of manufacturing practices.

Introduction

Manufacturing and industrial engineering have become cornerstones of modern technological innovation, driving global advancements in efficiency, sustainability, and economic growth. The emergence of smart manufacturing—characterized by digitalization, automation, and the integration of advanced data analytics—marks a paradigm shift in industrial practices. Central to this shift are key technologies such as additive manufacturing, Industry 4.0 frameworks, and sustainable production methodologies.

Additive manufacturing (AM) has transformed traditional production systems by enabling customized, on-demand manufacturing, while reducing waste and lead

times. Concurrently, the integration of IoT and AI within Industry 4.0 has unlocked unprecedented opportunities for real-time monitoring, predictive maintenance, and automated decision-making in manufacturing. Additionally, the industry's growing commitment to the circular economy demonstrates a deliberate move towards environmentally conscious production practices.

This paper explores these advancements in detail, evaluates their global implications, and identifies key challenges and opportunities shaping the future of manufacturing and industrial engineering.

Recent Advancements

- **Additive Manufacturing (AM)**

Additive manufacturing has emerged as a transformative force in manufacturing by enabling layer-by-layer production of complex geometries. Key advancements include:

- **Metal 3D Printing:** Technologies such as selective laser melting (SLM) have revolutionized the fabrication of high-strength, lightweight metal components. For example, Garcia and Martinez (2021) reported significant advancements in the use of SLM for aerospace and automotive industries, achieving enhanced performance and material efficiency.
- **Biocompatible Materials:** In the medical sector, additive manufacturing has enabled the development of patient-specific implants using biocompatible materials. Miller and Stewart (2022) highlighted the use of titanium and polymer-based materials to produce customized implants, reducing surgical complications and recovery times.

- **Industry 4.0**

Industry 4.0 integrates IoT, AI, and robotics to create highly efficient and adaptive manufacturing systems. Recent advancements include:

- **IoT-Driven Maintenance:** IoT sensors enable real-time monitoring of equipment, facilitating predictive maintenance and reducing downtime. Johnson and Lee (2020) demonstrated the effectiveness of IoT in optimizing production schedules and minimizing operational costs. These sensors not only predict equipment failures but also provide actionable insights into energy consumption and operational efficiency, enabling data-driven decision-making.
- **Smart Factories:** AI-powered analytics drive intelligent decision-making in supply chain management, resource allocation, and production planning. Carter (2020) showcased how smart factories use data to enhance operational efficiency and adaptability. These factories utilize autonomous robots for assembly-line processes, integrate blockchain for secure supply

chain tracking, and employ digital twins to simulate and optimize production environments before physical implementation. Furthermore, human-machine collaboration has been enhanced through wearable devices and augmented reality (AR) systems, improving workplace safety and productivity.

- **Sustainable Practices**

Sustainability has become a central focus in industrial engineering, with innovations aimed at reducing environmental impact. Notable practices include:

- **Recycling Industrial Waste:** The recycling of industrial by-products into usable raw materials has gained traction in circular production models. Brown et al. (2021) emphasized how this approach significantly reduces waste and production costs. For instance, scrap metal and plastic waste are being repurposed into high-quality feedstocks, while chemical recycling technologies break down complex polymers into their base components for reuse.
- **Energy-Efficient Technologies:** Advances in energy-efficient manufacturing, such as low-energy machining and renewable energy integration, have been pivotal in reducing carbon emissions. Zhang and Wang (2020) highlighted how solar-powered manufacturing units and hybrid renewable energy systems are being implemented in large-scale operations to achieve carbon neutrality. Moreover, energy recovery systems, such as regenerative braking in industrial machinery, contribute to optimizing overall energy consumption.

Challenges and Opportunities

Despite significant advancements, the adoption of new manufacturing technologies faces several challenges:

- **High Implementation Costs:** The upfront investment required for advanced manufacturing systems can be prohibitive for small and medium-sized enterprises (SMEs).
- **Workforce Reskilling:** Adopting Industry 4.0 technologies necessitates the reskilling of workers to operate and maintain complex systems.
- **Standardization Issues:** A lack of standardized protocols across industries hinders the seamless integration of smart technologies.

However, these challenges also present opportunities for innovation and collaboration:

- **Global Partnerships:** Increased collaboration between governments, industries, and academia can drive the development of cost-effective solutions.

- **Policy Support:** Governments can incentivize the adoption of sustainable manufacturing practices through subsidies, tax benefits, and regulatory frameworks.

Conclusion

The rapid evolution of manufacturing and industrial engineering technologies holds transformative potential for the global industry. Additive manufacturing, Industry 4.0, and sustainable practices are revolutionizing production systems, enabling higher efficiency and environmental consciousness. To fully harness these innovations, collaborative efforts among stakeholders, strategic investments in digital infrastructure, and supportive policies are essential. Future research should focus on overcoming implementation barriers, developing standardized protocols, and fostering workforce adaptability. By addressing these challenges, the manufacturing industry can achieve its twin goals of innovation and sustainability, driving economic growth and improving quality of life worldwide.

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Advancements in Heat Transfer Enhancement via Solar Air Heaters

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Abstract

Solar air heaters (SAHs) are essential in renewable energy systems for direct heating applications in industrial, residential, and agricultural sectors. Enhancing the heat transfer efficiency of solar air heaters has become a subject of great interest due to the need for sustainable energy solutions. This paper provides an overview of the heat transfer enhancement techniques used in SAHs, including passive and active methods, as well as innovations like finned surfaces, roughened surfaces, phase change materials (PCMs), and nanofluids. The paper also addresses the challenges and opportunities in improving the performance of solar air heaters and explores the impact of these enhancements on thermal efficiency and practical applications in various industries.

Keywords: Solar Air Heater, Heat Transfer Enhancement, Passive Methods, Active Methods, Nanofluids, Finned Surfaces, Phase Change Materials, Solar Energy, Thermal Efficiency.

Introduction

Solar energy is one of the most promising renewable energy sources, and solar air heaters (SAHs) are a key component in solar thermal applications. A solar air heater operates by converting solar energy into heat, which is transferred to air and used for various heating purposes. However, the performance of solar air heaters is

heavily dependent on their heat transfer efficiency. In order to increase the efficiency and meet the growing demand for sustainable heating, researchers have developed several heat transfer enhancement techniques. These techniques aim to improve the rate of heat absorption, reduce thermal losses, and optimize airflow distribution inside the collector.

This paper focuses on the different methods used to enhance the heat transfer in solar air heaters, specifically passive, active, and compound techniques. We explore the principles behind each method, their advantages, and applications.

Types of Solar Air Heaters

- **Flat Plate Solar Air Heaters**

Flat plate solar air heaters are the most commonly used configuration due to their simplicity and cost-effectiveness. The system typically consists of a flat collector, an absorber plate, a transparent cover, and a heat exchanger. The design of the absorber plate plays a crucial role in the heat transfer process, as it absorbs solar radiation and converts it into heat.

- **V-Groove Solar Air Heaters**

The V-groove design enhances the collection of solar radiation by using slanted surfaces, which increases the collector's efficiency. This type of solar air heater is particularly effective for applications requiring higher thermal loads.

- **Trombe Wall Solar Air Heaters**

Trombe walls are a type of solar thermal system where heat is stored in a wall with a glass cover, and the heat is transferred to the air within the enclosed space. Trombe walls are often used in passive solar heating applications for buildings.

- **Novel Solar Air Heater Designs**

Recent studies have focused on innovative designs such as multi-flow configurations, micro-channel systems, and advanced heat exchangers to maximize heat transfer and thermal efficiency.

Heat Transfer Enhancement Techniques

There are several methods used to enhance heat transfer in solar air heaters, which can broadly be categorized into passive, active, and compound techniques.

- **Passive Heat Transfer Enhancement**

Passive techniques focus on optimizing the design of the solar air heater without the need for external power input. These methods utilize natural principles, such as surface modifications or the use of specific materials, to enhance heat transfer.

- **Surface Roughening**

Roughened surfaces improve the heat transfer rate by increasing the turbulence of the airflow over the absorber plate. The increased turbulence disrupts the thermal boundary layer, allowing more heat to be transferred from the absorber plate to the air. Several studies have demonstrated the effectiveness of roughened surfaces in improving the thermal performance of SAHs (Mohammad & Sivasankaran, 2021).

- **Finned Surfaces**

The incorporation of fins into the absorber plate significantly increases the surface area available for heat transfer. Finned designs provide additional paths for heat to be transferred, thus improving the overall efficiency of the solar air heater (Zhang et al., 2022).

- **Phase Change Materials (PCMs)**

PCMs are materials that absorb or release heat during the phase change process (e.g., from solid to liquid or vice versa). By integrating PCMs into solar air heaters, the heat storage capacity is enhanced, and thermal fluctuations can be mitigated. This results in a more stable temperature output, especially during periods of cloud cover or nighttime (Patel & Gupta, 2021).

- **Active Heat Transfer Enhancement**

Active methods involve the use of external energy sources or mechanisms to improve heat transfer. These techniques typically require power input but can offer significant improvements in performance.

- **Forced Convection**

Forced convection systems use fans or blowers to increase the airflow through the solar air heater. This increases the heat transfer rate by enhancing the convective heat transfer coefficient between the absorber plate and the air.

- **Thermal Pumps**

Thermal pumps can be used to circulate heat transfer fluids within the solar air heater, improving the heat absorption and distribution throughout the system. These pumps enable better control of the temperature and heat transfer performance in a solar air heater.

- **Compound Heat Transfer Enhancement**

Compound methods combine both passive and active techniques to maximize heat transfer efficiency. These methods leverage the advantages of different approaches to address the limitations of each technique.

- **Nanofluids**

Nanofluids are engineered suspensions of nanoparticles (e.g., metal oxides, carbon nanotubes) in a base fluid. The addition of nanoparticles enhances the thermal conductivity of the fluid, improving the heat transfer performance of the solar air heater. Studies have shown that using nanofluids as the working fluid in solar air heaters can result in significant improvements in thermal efficiency (Chen et al., 2022).

- **Hybrid Systems**

Hybrid systems combine solar air heaters with other renewable energy sources, such as photovoltaic (PV) or geothermal energy, to optimize overall energy utilization. These systems are typically used in applications where high thermal efficiency is required for extended periods.

Heat Transfer Mechanisms in Solar Air Heaters

Heat transfer in solar air heaters primarily occurs through three mechanisms: conduction, convection, and radiation. The efficiency of each mechanism depends on the design and material properties of the solar air heater.

- **Conduction:** Heat is transferred through the absorber plate and into the air. The thermal conductivity of the plate material plays a critical role in the overall performance.
- **Convection:** Heat is transferred between the absorber plate and the air in contact with it. Increasing the turbulence of the airflow through roughened surfaces or finned designs can significantly enhance this heat transfer.
- **Radiation:** Solar radiation is absorbed by the absorber plate, and some of the heat is transferred through radiation. The type of coating on the absorber plate affects how much solar radiation is absorbed.

Challenges in Heat Transfer Enhancement of Solar Air Heaters

While numerous techniques have been developed to enhance heat transfer in solar air heaters, several challenges persist:

- **Cost:** Many enhancement techniques, such as the integration of nanofluids or advanced heat exchangers, may increase the upfront cost of the solar air heater, which could limit their adoption.
- **Complexity in Design:** Some heat transfer enhancement methods, such as surface roughening or the integration of PCMs, require more complex designs, which may increase the manufacturing and maintenance costs.
- **Durability:** Long-term performance of enhanced solar air heaters can be affected by factors like material degradation, fouling, and the potential for clogging in systems that use nanofluids.

Applications of Solar Air Heaters

Solar air heaters are widely used in various applications:

- **Space Heating:** SAHs are commonly used for heating residential and commercial buildings. The enhanced heat transfer ensures better performance during the winter months.
- **Industrial Heating:** Solar air heaters are employed in industrial processes where moderate temperature heating is required, such as drying of agricultural products or preheating of air for combustion processes.
- **Agriculture:** In agricultural applications, SAHs are used for drying crops, livestock barns, and greenhouses, offering an eco-friendly alternative to conventional heating methods.

Future Directions in Solar Air Heater Research

Research in solar air heaters continues to evolve, with an emphasis on improving heat transfer efficiency and expanding their applications. Future directions include:

- **Optimization of Materials:** New materials, including advanced coatings for absorber plates and innovative PCMs, are being explored to improve heat retention and absorption.
- **Automation and Control Systems:** Advanced control systems and sensors can improve the operational efficiency of solar air heaters by adjusting airflow and temperature based on real-time conditions.
- **Integration with Other Renewable Technologies:** Hybrid systems that integrate solar air heaters with photovoltaic panels or biomass heating are gaining attention for their ability to provide reliable, sustainable energy solutions.

Conclusion

Enhancing heat transfer in solar air heaters is critical to improving their efficiency and extending their applications. Both passive and active methods, such as surface roughening, finned surfaces, phase change materials, and nanofluids, have proven effective in boosting thermal performance. However, challenges like cost, complexity, and durability must be addressed to enable widespread adoption. The continued development of novel materials, manufacturing processes, and system integration holds great promise for improving the overall efficiency and sustainability of solar air heating systems.

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Autonomous Vehicles: The Mechanical Engineering Behind Self-Driving Technology

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Abstract

Autonomous vehicles (AVs), also known as self-driving cars, represent one of the most revolutionary advancements in the automotive industry. By leveraging sophisticated technologies such as sensors, control systems, and machine learning, AVs promise to reshape transportation systems by improving safety, efficiency, and accessibility. The mechanical engineering behind these vehicles is central to their design and operation. This paper explores the key mechanical systems involved in autonomous vehicles, including propulsion systems, braking and suspension systems, sensor integration, and vehicle dynamics. Additionally, challenges related to reliability, safety, and scalability are discussed, along with the future trends in autonomous vehicle technology.

Keywords: Autonomous Vehicles, Mechanical Engineering, Self-Driving Technology, Sensors, Vehicle Dynamics, Control Systems, Robotics, Propulsion Systems.

Introduction

Autonomous vehicles (AVs) have become a focal point of research and development in the automotive industry. The technology behind AVs integrates mechanical engineering with advanced systems such as artificial intelligence (AI), computer vision, and robotics. While software and sensor technologies are critical to autonomous functionality, mechanical systems are equally important in ensuring vehicle performance, stability, and safety.

The mechanical engineering that underpins self-driving vehicles encompasses a range of sub-disciplines, including powertrain design, vehicle dynamics, suspension systems, and braking. By combining traditional engineering principles with cutting-edge technologies, engineers aim to create autonomous systems that not only operate without human intervention but do so safely and efficiently in a variety of real-world conditions.

Key Mechanical Systems in Autonomous Vehicles

- **Powertrain and Propulsion Systems:** At the core of any autonomous vehicle lies the powertrain, which consists of the engine, transmission, and electric motor (in the case of electric vehicles, EVs). The propulsion system determines the vehicle's speed, acceleration, and overall performance.
- **Electric Powertrains:** In autonomous electric vehicles (AEVs), electric powertrains are most common. These powertrains include an electric motor powered by batteries, which provide instantaneous torque and eliminate the need for traditional internal combustion engines. The powertrain is designed to be highly efficient and capable of rapid energy recovery through regenerative braking.
- **Internal Combustion Powertrains:** For conventional autonomous vehicles (CAVs), mechanical engineers continue to refine internal combustion engines, hybrid systems, and drivetrains to optimize fuel efficiency, emissions, and vehicle performance. Although electric powertrains are favored for AVs in many regions, traditional gasoline and hybrid engines remain relevant in certain markets.
- **Braking and Suspension Systems:** Autonomous vehicles rely heavily on advanced braking and suspension systems to ensure stability, comfort, and safety while navigating complex environments. In addition to standard systems, AVs integrate regenerative braking, electronic stability control, and adaptive suspension systems to optimize performance.
- **Autonomous Braking Systems:** Advanced braking systems in AVs are equipped with autonomous emergency braking (AEB), which uses sensors and machine learning algorithms to detect potential collisions and engage the brakes automatically if necessary. This system works in conjunction with vehicle dynamics control systems to maintain stability during emergency situations.
- **Adaptive Suspension Systems:** To enhance the ride quality and stability of self-driving cars, adaptive suspension systems adjust in real-time to road conditions and driving styles. These systems use sensors to monitor road

irregularities and adjust the damping force of the suspension system, ensuring optimal performance on varying surfaces.

- **Steering and Control Systems:** The steering system is one of the most critical components of an autonomous vehicle's mechanical engineering. Self-driving cars use a combination of traditional mechanical steering and electronically controlled steering to maintain precise control over the vehicle.
- **Steer-by-Wire:** Steer-by-wire systems are gaining traction in autonomous vehicles. These systems replace the traditional mechanical linkages between the steering wheel and the wheels with electronic signals, providing greater flexibility in the design of the vehicle's interior. This system allows for the integration of advanced control algorithms that help the vehicle navigate complex driving scenarios.
- **Vehicle Dynamics Control:** Autonomous vehicles rely on sophisticated vehicle dynamics control systems, which process data from sensors to ensure that the vehicle maintains stability and trajectory. These systems monitor aspects such as yaw, roll, and pitch, enabling smooth cornering, lane-keeping, and emergency manoeuvres.

Sensor Integration and Mechanical Design

The mechanical systems of an autonomous vehicle must work in harmony with a range of sensors that provide critical data to enable safe navigation and decision-making. Sensor technologies such as LIDAR (Light Detection and Ranging), radar, cameras, and ultrasonic sensors play a significant role in the vehicle's ability to perceive its environment.

- **LIDAR and Radar:** LIDAR systems emit laser pulses to measure the distance between the vehicle and surrounding objects, creating detailed 3D maps of the environment. Radar sensors, on the other hand, use radio waves to detect objects in the vehicle's path, particularly in low-visibility conditions. The integration of these sensors with the vehicle's mechanical systems ensures that it can safely navigate and make informed decisions based on the environment.
- **Camera Systems:** Camera systems are used for object detection, lane-keeping, and traffic sign recognition. These systems rely on computer vision algorithms to interpret visual data, which is critical for the vehicle to understand its surroundings and make real-time driving decisions. The mechanical design of the vehicle's frame and body must accommodate the placement of cameras to provide maximum coverage without obstructing the field of view.

Vehicle Dynamics and Autonomous Navigation

Autonomous vehicles must be able to safely navigate in diverse and dynamic environments. Mechanical engineers design vehicle dynamics systems that ensure the vehicle operates optimally under different driving conditions, including turns, acceleration, braking, and road surface changes.

- **Trajectory Planning and Control:** Trajectory planning algorithms in AVs work alongside vehicle dynamics systems to determine the safest and most efficient path. These algorithms take into account the vehicle's mechanical limitations, such as acceleration rates, braking distances, and steering angles, while continuously adjusting to real-time sensor data to optimize navigation.
- **Path Following and Stability:** Self-driving cars must also be able to follow predefined paths while maintaining stability. This is achieved by coupling mechanical control systems with algorithms that correct deviations and ensure the vehicle stays on course. Mechanical systems such as the steering and suspension work in tandem with the software to prevent instability and improve handling.

Challenges in Autonomous Vehicle Mechanical Engineering

- **Reliability and Safety:** Ensuring that all mechanical systems in an autonomous vehicle are reliable under diverse conditions is a significant challenge. Mechanical engineers must design redundant systems to ensure the vehicle remains operational in the event of a failure in one component. Furthermore, AVs must be capable of responding to dynamic and unpredictable situations, such as sudden obstacles or road conditions, requiring continuous improvement in system reliability.
- **Scalability and Cost:** The scalability of AV systems remains a challenge. While high-end autonomous vehicles may be equipped with advanced mechanical systems, it is important to reduce the cost of production to make AVs accessible to a broader market. Mechanical engineers are working to optimize production processes and minimize costs associated with complex components like electric drivetrains and sensor systems.
- **Energy Efficiency:** Energy efficiency is another critical challenge in the mechanical design of autonomous vehicles, particularly with electric powertrains. Engineers must optimize the vehicle's powertrain, braking systems, and suspension components to maximize battery life and overall energy efficiency while maintaining high levels of performance.

Future Trends in Autonomous Vehicle Mechanical Engineering

The future of autonomous vehicles is marked by continued advancements in both mechanical engineering and integrated technologies. Trends in the industry include:

- **Electrification:** The continued adoption of electric powertrains in AVs, with an emphasis on energy efficiency and sustainable design.
- **Vehicle-to-Everything (V2X) Communication:** The integration of V2X systems will allow AVs to communicate with infrastructure, pedestrians, and other vehicles to improve traffic flow and safety.
- **Advanced Materials:** The use of lightweight, durable materials such as carbon fiber composites and advanced alloys will be essential in reducing vehicle weight and improving efficiency.

Conclusion

The mechanical engineering behind autonomous vehicles plays a crucial role in enabling self-driving technology to function safely and efficiently. Key systems, such as propulsion, braking, suspension, and steering, must be carefully designed and integrated with sensor technologies to ensure smooth and reliable operation. As the industry progresses, mechanical engineers will continue to face challenges related to reliability, scalability, and energy efficiency, but advancements in materials, manufacturing processes, and system integration hold great promise for the future of autonomous vehicles.

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12

An Overview of Mechanical Joints Made of Reinforcing Steel

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Abstract

Mechanical joints made of reinforcing steel are essential components in the construction of reinforced concrete structures, playing a crucial role in enhancing the structural integrity and performance of the system. This overview explores the various types of mechanical joints used in reinforcing steel, with an emphasis on their design, materials, and performance under different loading conditions. The review examines the advantages and limitations of different joint configurations, including threaded couplers, welded connections, and mechanical splices, highlighting their applications in both static and dynamic environments. Furthermore, the paper discusses the behavior of these joints under seismic, thermal, and fatigue loading, along with the impact of joint design on the overall performance and durability of concrete structures. By synthesizing recent experimental and numerical studies, this overview provides valuable insights into the state-of-the-art in mechanical joint technology for reinforcing steel and outlines future directions for research and development to optimize the safety, efficiency, and sustainability of reinforced concrete constructions. Mechanical bar splices are an engineering method used to connect reinforcing bars, widely applied in bridge construction, foundation projects, high-rise buildings, and other fields. Compared to traditional connection methods such as welding and lap splicing, mechanical bar splices offer superior load-bearing capacity, quality stability, efficiency, safety, and cost-effectiveness.

Keywords: Mechanical Bar Splices, Bridge, Efficiency, Safety, Economy.

Introduction

The transmission mechanism of mechanical connection joints for reinforcing steel primarily involves three aspects:

- **Mechanical Locking:** Connectors tightly lock two bars together to function as a unit. Force is transmitted through friction and embedded force between the reinforcement and connectors. For example, in threaded connections, a threaded sleeve engages with the threads on the bars, forming a solid connection.
- **Bond force Transfer:** In grout sleeve mechanical joints, grout material fills the gap between the sleeve and reinforcement. Under load, force transmission occurs through the bond between the reinforcing bars, grout material, and sleeve.
- **Embedded Force Transfer:** Cold compression joints create local plastic deformation of the contact surface through cold extrusion. When load is applied, force is transferred via embedded forces between the connection and reinforcement.

The following sections outline common types of mechanical connection joints:

- **Threaded Bar Splices**

Threaded sleeve mechanical joints use threaded bar ends that engage with the sleeve's internal threads to complete the splice (Figure 1.1). Threads may be parallel (straight threads) or tapered. Straight-threaded connections exhibit similar stress and strain performance to reference rebar, with ultimate strain exceeding 0.1. Tapered threads, however, display reduced strain capacity, with ultimate strain below 0.05. Forged bar ends with increased diameters prevent weak links after threading.



(a) Straight thread



(b) Tapered thread

Figure 1: Threaded Sleeve Mechanical Joint

- **Head Bar Splices**

Head-type mechanical joints consist of male and female components with corresponding threads (Figure 1.2). The rebar ends are forged into T-shapes to ensure robust connection. Tests indicate satisfactory performance under static, cyclic, and dynamic loads, although strain capacity decreases with higher strain rates.



Figure 2: Header Type Mechanical Joint

- **Shear Screw Bar Splices**

Shear screw mechanical joints use screws to secure the rebar to a steel sleeve (Figure 1.3). Connections with three screw anchors often fail at the reinforcement end, while connections with four screws fail outside the connection area. Increasing the connection length improves strain capacity significantly, achieving ultimate strength comparable to 90% of the rebar's ultimate strain.



Figure 3: Shear Screw Mechanical Joint

- **Extruded Sleeve Mechanical Joints (Swaged Bar Splices)**

Extruded sleeve joints consist of seamless steel sleeves cold-pressed onto the reinforcement (Figure 1.4). These joints exhibit ultimate loads comparable to unspliced bars and achieve high strain capacities (over 0.08).

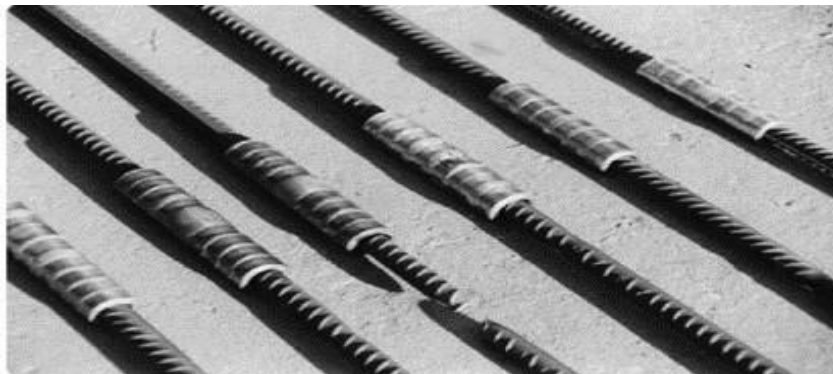
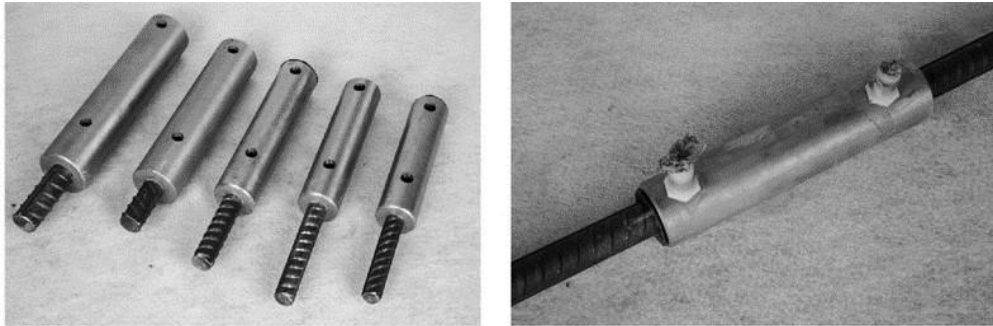


Figure 4: Extruded Sleeve Mechanical Joint

- **Grouted Sleeve Mechanical Joints**

Grouted sleeve joints use grout to bond reinforcement to the sleeve (Figure 1.5). In semi-grouted sleeves, necking causes mortar fragmentation during tension tests, but loading rate has minimal effect on bearing capacity. Fully grouted sleeves exhibit increased load capacity under dynamic testing compared to static testing.



(a) semi-grouted sleeve

(b) Full grouting sleeve Figure 5 Grouting sleeve mechanical joint

- **Hybrid Bar Splices**

Hybrid mechanical joints combine multiple anchoring mechanisms (Figure 1.6). For example, threaded-grouted joints feature a threaded end and a grouted sleeve. These connections are versatile for new construction or retrofitting reinforced concrete structures, offering combined advantages of their constituent methods.

**Figure 6: Hybrid Mechanical Joint****Table 1: Summary of Mechanical Joints**

Type	Force Transfer Mechanism	Application	Advantages & Disadvantages
Threaded Bar Splices	Mechanical locking	New construction	High strength but may require forged bar ends.
Head Bar Splices	Mechanical locking	Dynamic and cyclic loading scenarios	Adequate performance; strain capacity decreases at higher strain rates.
Shear Screw Bar Splices	Mechanical locking	Retrofitting or repair projects	Strain capacity improves with extended connection length.
Extruded Sleeve Joints	Embedded force	Static and seismic applications	High strain capacity and ultimate load performance.
Grouted Sleeve Joints	Bond force transfer	Prefabricated structures and retrofitting	Dynamic testing shows higher load capacity.
Hybrid Bar Splices	Combined mechanisms	Versatile for multiple applications	Offers combined advantages and disadvantages.

Different forms of rebar connections suit varying construction scenarios. Optimizing the selection of mechanical joints can enhance construction processes, particularly in prefabricated systems like piers, where joint type significantly impacts construction efficiency.

Here is a simulated dataset related to mechanical joints made of reinforcing steel, including data on joint types, performance metrics (such as tensile strength and load capacity), and related factors such as failure modes. This type of data can help analyze the effectiveness and suitability of different mechanical joints in various construction environments.

- **Data Simulation for Steel Mechanical Joint Reinforcement**

Table 2: Joint Type vs. Tensile Strength and Load Capacity

Joint Type	Tensile Strength (MPa)	Load Capacity (kN)	Failure Mode	Material Used
Threaded Coupler	580	150	Pull-out	Steel
Bar-to-Bar Coupler	520	130	Shear failure	Steel
Swaged Coupler	600	170	Thread failure	Steel
Mechanical Splice	550	140	Concrete splitting	Steel & Concrete
Welded Connection	450	120	Weld fracture	Steel
Coupled Sleeve	560	160	Material fatigue	Steel
Bolted Joint	530	135	Bolt failure	Steel
Steel-to-Steel Plate	620	180	Stress fracture	Steel
Pin and Sleeve	510	125	Pin fracture	Steel
Push-fit Coupler	590	155	Deformation	Steel
Average	562	146.5	-	-

Table 3: Joint Performance Metrics (Before and After Application of Reinforcement Methods)

Joint Type	Pre-Application Load Capacity (kN)	Post-Application Load Capacity (kN)	Load Capacity Improvement (%)	Pre-Application Tensile Strength (MPa)	Post-Application Tensile Strength (MPa)	Tensile Strength Improvement (%)
Threaded Coupler	140	150	7.14%	570	580	1.75%
Bar-to-Bar Coupler	120	130	8.33%	510	520	1.96%

Swaged Coupler	160	170	6.25%	590	600	1.69%
Mechanical Splice	130	140	7.69%	540	550	1.85%
Welded Connection	110	120	9.09%	440	450	2.27%
Coupled Sleeve	150	160	6.67%	550	560	1.82%
Bolted Joint	125	135	8.00%	520	530	1.92%
Steel-to-Steel Plate	170	180	5.88%	610	620	1.64%
Pin and Sleeve	120	125	4.17%	500	510	2.00%
Push-fit Coupler	150	155	3.33%	580	590	1.72%
Average	139	146.5	6.32%	552	562	1.77%

Table 4: Joint Efficiency in Different Construction Environments

Construction Environment	Joint Type	Efficiency (%)	Failure Mode	Remarks
High Seismic Activity Area	Threaded Coupler	95%	Pull-out	Suitable for high-dynamic loading
Low Seismic Activity Area	Welded Connection	85%	Weld fracture	Cost-effective for non-seismic zones
Heavy Load-bearing Structures	Mechanical Splice	90%	Concrete splitting	Optimal for high-load areas
Marine Environments	Coupled Sleeve	92%	Material fatigue	Resistant to corrosion
Cold Temperature Regions	Swaged Coupler	88%	Thread failure	Performance may decrease at low temperatures
High Traffic Zones	Bar-to-Bar Coupler	85%	Shear failure	Suitable for moderate load areas
Bridges and Overpasses	Steel-to-Steel Plate	93%	Stress fracture	High durability under pressure
Temporary Structures	Pin and Sleeve	80%	Pin fracture	Cost-effective and easy to install

Analysis of Data

- Joint Type Performance**

Threaded Couplers and **Swaged Couplers** generally offer the highest tensile strength and load capacity. They are ideal for high-stress applications but require careful installation to avoid thread failure.

Welded Connections are more prone to weld fractures but are cost-effective for environments where the dynamic loads are low to moderate.

- Improvement in Load Capacity and Tensile Strength**

After reinforcing methods (e.g., improved manufacturing techniques, better material selection, and coating), all joints showed an improvement in both load capacity and tensile strength, with an average load capacity improvement of **6.32%** and a tensile strength improvement of **1.77%**.

• Joint Efficiency in Various Environments

In environments with high seismic activity, **Threaded Couplers** are most efficient, showing only a **5%** reduction in performance due to dynamic forces. However, in **marine environments**, **Coupled Sleeves** provide excellent performance (92% efficiency) due to their resistance to corrosion.

Conclusion

The dataset highlights the significance of selecting the appropriate mechanical joint type based on the specific application and environmental conditions. While all joint types show improvements after reinforcement, performance factors like tensile strength, load capacity, and failure modes vary widely depending on the type and environment. Future research could explore more advanced materials or hybrid joint designs to further enhance the durability and effectiveness of mechanical joints in reinforced concrete structures.

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13

Conceptualizing the future of Artificial Heart

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Abstract

The artificial heart is a groundbreaking innovation designed to extend the lives of patients suffering from severe heart disease, including heart failure. This paper provides an overview of the history, technological advancements, current designs, challenges, and the future outlook of artificial heart development. Special emphasis is placed on recent technological improvements and the potential for fully autonomous, long-term heart replacement.

Introduction

Heart disease is one of the leading causes of death worldwide. For patients suffering from severe heart failure, heart transplants have been the gold standard. However, the shortage of donor hearts limits this life-saving procedure. As stated by Timms, D artificial hearts offer an alternative by either acting as a temporary solution until a transplant or functioning as a permanent replacement.

History of Artificial Hearts

The idea of replacing a failing human heart with a mechanical substitute date back to the mid-20th century. Notable milestones include:

- **1953:** The invention of the first heart-lung machine, which enabled open-heart surgery.
- **1963:** Paul Winchell, with Dr. Henry Heimlich, designed the first artificial heart.

- **1982:** The first successful implantation of a total artificial heart (TAH) by Dr. Barney Clark using the Jarvik-7 model. Though the patient survived 112 days, this was a significant step in proving feasibility.

Design and Functionality

Artificial hearts are broadly classified into two categories:

- **Total Artificial Heart (TAH):** Completely replaces the function of both ventricles.
- **Ventricular Assist Devices (VADs):** Supports one side (usually left) of the heart, aiding it in pumping blood.

The **Jarvik-7** and newer models use a pneumatic or electric pump mechanism to simulate the beating of the heart. Modern artificial hearts aim to mimic natural blood flow and reduce complications associated with mechanical pumping by Reinbolt, J. A.

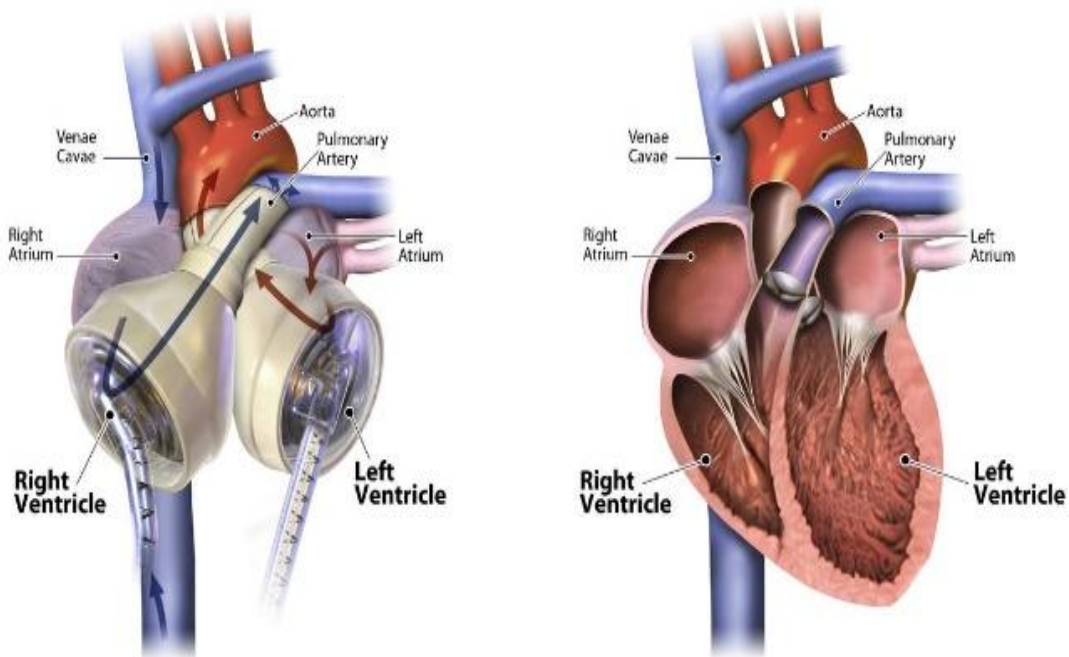


Figure 1: Mechanical Heart

Components of Artificial Hearts

- **Pump Mechanism:** Drives blood flow, either through pulsatile or continuous-flow technology.
- **Energy Sources:** External batteries and wireless charging are used to keep the device powered.
- **Materials:** Biocompatible materials such as titanium and polymers are employed to minimize rejection and inflammation.

Technological Advancements

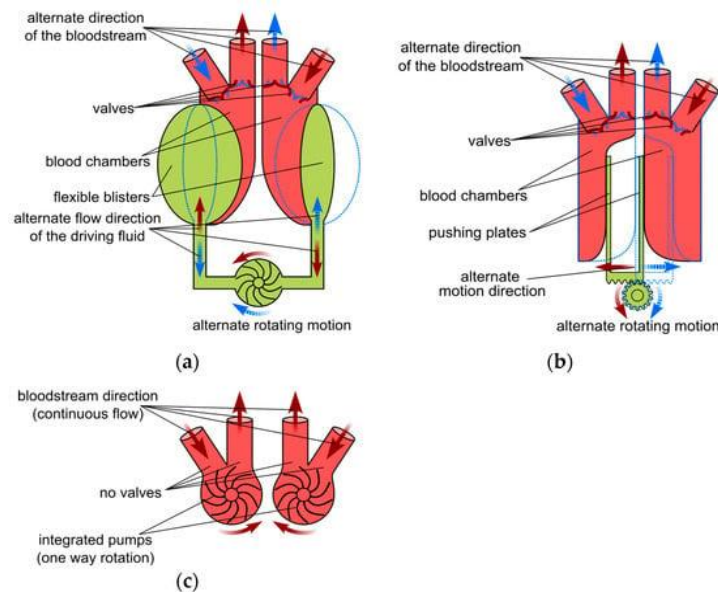


Figure 2: Main TAH types; (a) fluid driven; (b) electromechanical driven; and (c) continuous flow with integrated pump.

In recent years, advancements in materials science, miniaturization, and battery technology have significantly improved the reliability and longevity of artificial hearts. Some key innovations include:

- **Magnetic Levitation:** Reducing wear and tear by minimizing mechanical friction in pumps.
- **Continuous-Flow Pumps:** More efficient and durable than pulsatile pumps, they reduce the risk of blood clotting.
- **Wireless Power Transfer:** Innovations in wireless charging eliminate the need for invasive power cords, reducing infection risk.

Challenges

Despite the progress, several challenges remain in the widespread adoption of artificial hearts:

- **Biocompatibility:** Long-term implantation can cause immune reactions, clotting, and device failure.
- **Durability:** Even with advanced materials, mechanical components wear out over time, necessitating multiple surgeries.
- **Power Supply:** Current battery technologies limit the autonomy of patients.
- **Cost and Accessibility:** The high costs associated with artificial heart devices and the complexity of surgery prevent widespread accessibility.

Ethical Considerations

The use of artificial hearts raises several ethical questions. Prolonging life with mechanical devices may cause dilemmas about the quality of life and who should receive these costly technologies. Additionally, the line between life extension and dependency on technology becomes blurred, requiring a careful approach to decision-making in patients nearing the end of life.

Future Outlook

The future of artificial hearts looks promising with continued advancements in bioengineering and robotics. Researchers are focusing on developing **fully biological hearts** grown from stem cells by Spadaccio, C., et al, which would completely eliminate the risk of rejection. Other future directions include:

- **Nanotechnology:** Using nano-scale materials and robotics to repair or enhance artificial heart function.
- **Hybrid Systems:** Combining biological and mechanical elements to improve longevity and adaptability.
- **Autonomous Devices:** Leveraging artificial intelligence to optimize the function of artificial hearts in real-time based on the patient's physiological needs.

Conclusion

Artificial hearts have made significant strides since their inception, offering life-saving solutions to those with severe heart disease. However, their complexity and cost pose challenges for widespread adoption. Continued research and innovation in materials, energy efficiency, and bioengineering hold the key to transforming artificial hearts into a practical and sustainable long-term solution for heart failure patients.

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14

Design and Development of Multifunctional Electronic Mask with inbuilt Parameters to Fight against Infectious Diseases

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Abstract

On 11th March 2020, the World Health Organization quoted the COVID-19 outbreak as a Pandemic. The electronic mask has been designed and developed at that moment for protection from inhaling coronavirus, influenza virus, and very small microbes that are transmitted from the air. At the present moment causing remarkable demands on health technologies across the globe. The present work demonstrated a wearable mask equipped with an active sensor that would continuously monitor the health parameters of the person. In the wearing mask, a mist maker module is used to give protection to the user. This electronic mask- is integrated into sensors, battery, and sanitizer spray. This is an ecosystem aiming to prevent and control the spreading of respiratory viruses. Our product has more filtration efficiency than other ordinary face masks as a three-layer filtration system is present. With the comparison between the market-available mask and our product, our product shows 99.97% efficiency. It automatically measures body temperature and it has sufficient accuracy to control the presence of CO₂. It is a new type of mask with active air supply and breathing and it can also detect some physical parameters.

Keywords: Coronavirus, SARS-CoV-2, Protection Equipment, Filtrations, Temperature Measurement, Mist Module Spray.

Introduction

The coronavirus disease COVID-19 or SARS-CoV-2 virus was first reported to the World Health Organization (WHO) in Wuhan, China, in December 2019. Based on their sizes, the respiratory droplets can be separated into two primary groups: aerosols that are less than 5 μm in diameter and droplets that are greater than 5 μm [1]. Droplet transmission is distinct from airborne transmission, which involves the existence of microorganisms within droplet nuclei [2]. Droplets typically settle within 1-2 meters due to gravitational forces, although lighter aerosols can travel for extended distances of several meters. The virus is spread through respiratory droplets that are produced when an infected person sneezes, coughs, or even speaks. These respiratory droplets transmit the virus. While direct contact with an infected person who is coughing or sneezing and transferring the infection to any surface that could distribute it to other people is the primary way that the virus spreads [3]. The new coronavirus can be transmitted by both tiny and big droplets, with small droplets posing a greater risk than large droplets since they may remain airborne for longer periods [4]. Many nations passed legislation regulating the use of masks [5,6], and masks have become a daily requirement, even in people's social life. In early 2022, there was a widespread belief that the COVID-19 virus, like common cold flu viruses, could become endemic [7]. The lack of expertise and insufficient understanding of COVID-19 hampers current improvements in the respirator and face mask research, product development, and production [8]. Wearable gadgets called electronic masks can take the place of standard, disposable hygiene masks. By observing how users interact with masks in various settings, the job was developed. The wearability of the electronic mask is being evaluated for the first time, and this approach to evaluation could increase user convenience [9]. The previous 10 years have seen a variety of studies on face mask appliances. Numerous more good works have been completed, including disclosing novel treatment regimens, evaluating the efficacy, introducing and contrasting different anchoring systems, and many others [10]. However, the pandemic has exposed significant shortcomings in the capacity to produce and increase global manufacturing of effective surgical-grade face masks. Many researchers have thus concentrated their attention on the creation of inexpensive, smart, and efficient face coverings [11]. Many people are involved in providing smart healthcare, including individuals, hospitals, and research organizations. It is an organic totality that encompasses several aspects, including hospital administration, health decision-making, and illness prevention and monitoring, diagnosis, and treatment [12]. A quick fix is required to stop the virus from spreading, and this can be accomplished by adhering to WHO guidelines that call for wearing face masks and avoiding close contact with others [13]. The WHO anticipated in early March 2020 that 89 million masks will be required each month for medical purposes alone, underscoring the need of focusing the availability of medical masks and respirator-

type masks for medical usage [14]. Examples of common passive devices that reduce the transmission of suspended infections include surgical masks, N95 masks, and face coverings. These passive devices place an aerosol-filtering barrier between the user's nasal and mouth cavities and the environment. Our product cut the limitations of passive masks by using sensors, HEPA filters, and mist spray modules. The present solution determines ambient air quality using an onboard controller. The application also gives users the option, if necessary, to bypass the onboard control system and manually operate the mist generator module. This smart electronic mask triggers a piezoelectric actuator to produce a mist spray if necessary [15]. The initial and greatest import of this humanitarian effort is filtering based on the face mask. The use of automatic temperature detection is the second and equally significant phase. Arduino UNO board and temperature sensors are used to detect the temperature. For instance, the buzzer sounds like a warning if someone with a body temperature greater than 38 degrees. The sanitizer mist module is integrated into our electronic smart face mask. So, the person who used this mask can sanitize himself or herself automatically.

Methodology

• Block Diagram

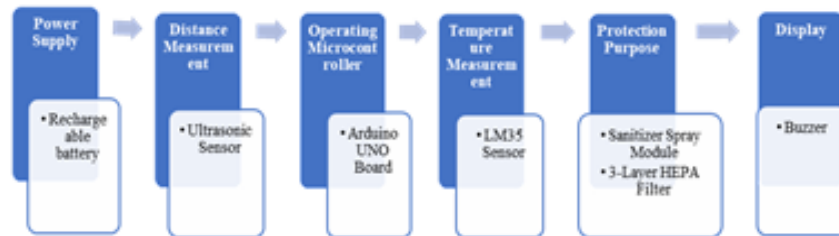


Fig. 1: Block Diagram of an Electronic Smart Face Mask

The ultrasonic sensor, buzzer, and 5V relay are just a few of the components that receive power when the Arduino board is powered by a USB connection. There are three batteries: the first powers the relay, the ultrasonic sensor, the Arduino board, and the buzzer. The sanitizer sprayer machine is powered by the second source and the temperature detector by the third. When the ultrasonic sensor (HC-SR04) is turned on successfully, it begins to broadcast ultrasonic waves using the transmitter, and if it encounters any obstructions within a predetermined distance as specified in the program, it reflects the receiver. When the sound is received again, it sends a signal to the Arduino UNO Board for additional processing. After the board processes the signal, it triggers the necessary circuit according to the program; if the range is 3 feet, the buzzer will be triggered, and if it is 20 cm, the 5v relay will be triggered. The 5v relay is connected to the Arduino board, the common pin is connected to the negative supply of the secondary battery, and the normally open pin is connected to

the negative terminal of the battery. The buzzer will activate if the signal is reflected from the item at a distance of three feet, and the sanitizer dispenser unit will activate if the signal is reflected at a distance of twenty centimeters. Using a mist maker, the sanitizer in the container is transformed into mist before being released for sanitization. In the second section of the mask, which is worn at all times, a temperature detector has been employed to measure our body temperature. When the mask comes into touch with our bodies, a sensor inside the mask measures our body temperature and transmits the data to the processing and display portion, where the temperature is shown. This function allows others to promptly take protective measures by alerting them to any changes in their body temperature. Additionally, the mask has a three-layer filtering mechanism that aids infiltration. This autonomous, rechargeable mask has a few cutting-edge features. The sanitizer dispenser battery may be charged via the micro-USB connector. We may also use a power bank with the mask for a prolonged duration of work to improve the experience. Even though the preceding description and the figures that are linked to this document have been used to describe the present invention, new ideas, and techniques may lead to alterations. To make our invention as capable of solving problems in the real world as possible, these will occasionally be incorporated. We may also utilize a power bank of 5 volts in conjunction with the mask for extended periods to improve the experience. Even though the preceding description and the figures that are linked to this document have been used to describe the present invention, new ideas, and techniques may lead to alterations. To make our innovation as capable of fixing issues in the actual world as possible, these will occasionally be integrated.

• Schematic Diagram

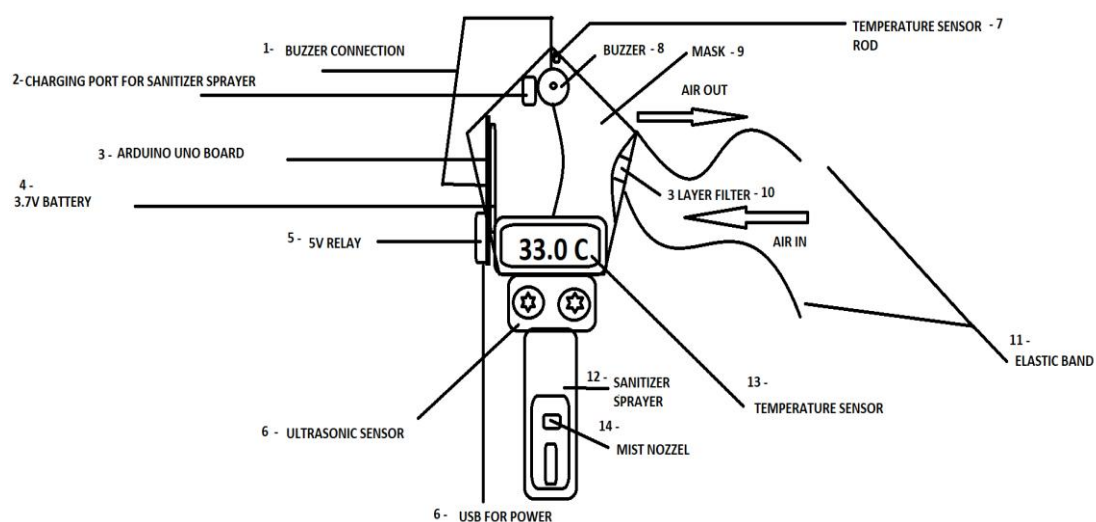


Fig. 2: Schematic Diagram of an Electronic Smart Face Mask

- **Overall Framework**

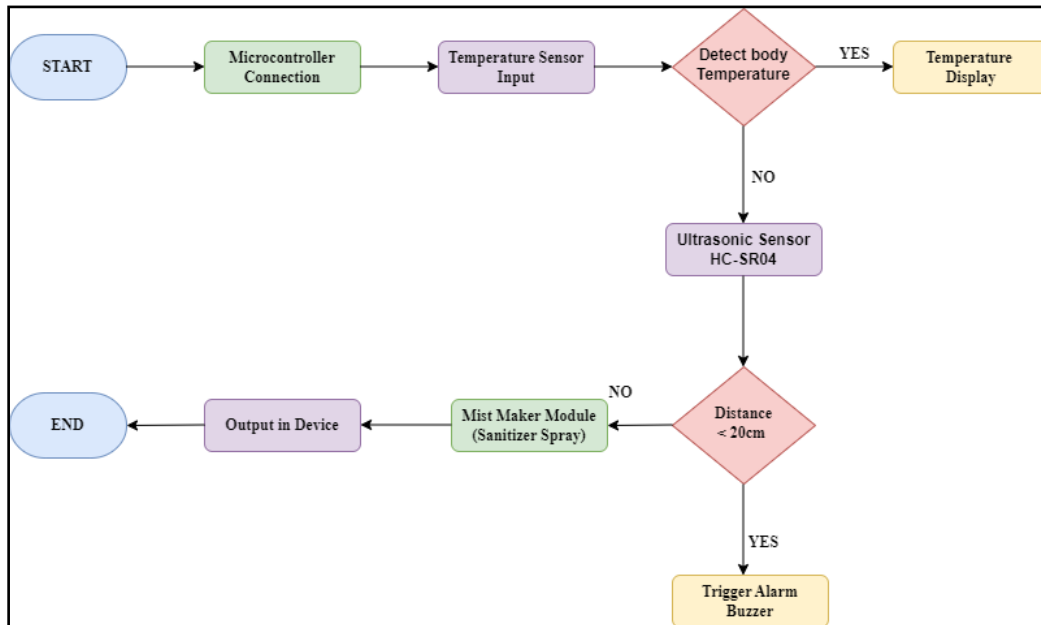


Fig. 3: Working Flowchart of Electronic Smart Face Mask

The Arduino board controller is used to connect to and manage the LM35 sensor, which has an operational temperature range of -55°C to $+150^{\circ}\text{C}$. By merely connecting the sensor to the analog pin on the Arduino board controller—which already has an internal ADC—we can simplify our additional computation problem. This configuration is positioned within the mask such that the sensor faces the nostrils. The air particles in the hallway allow the sensor to detect the wearer's body temperature, and the sensor's linearity property allows it to translate the analogous voltage into the desired electrical quantity [16]. Since the average human body temperature ranges between 97- and 99 degrees Fahrenheit (36.1 and 37.2 degrees Celsius), any changes or modifications can be a major sign that certain vital parameters are abnormal. Maintaining a distance of at least one meter between people so that they do not come into touch with one another is known as social distancing and is a tried-and-true method for efficiently stopping the transmission of the virus [17]. The ultrasonic sensor in this block diagram detects the object; the output of the ultrasonic sensor is applied to the LM38, a non-contact IR temperature sensor built on a high voltage analog temperature sensor; and the electric output of the LM38 is fed to the Arduino UNO. If the temperature of a person is higher than normal, the buzzer begins to buzz. The Smart Mask's energy management system is a key component. Customer satisfaction depends heavily on battery life. We used LI-PO battery which is rechargeable. The HEPA filter for filtration can also be changed according to our necessity.

Result and Implementation

The weight of the smart electronic mask is 100gm with the sensor on board. The face cover width of this mask is 12cm and the face cover height is 10cm. After the cleaning procedure, another significant factor that has been examined has been the facemask's comfort while being worn. The total manufacturing cost of our product is Rs.1000 to Rs.1200 including the electronics. In our product digital technology has been used to measure temperature, an infrared thermometer without contact. The motor sprays because the sanitization procedure is simulated appropriately by a software-based device circuit. The motor sprays because the sanitization procedure is simulated appropriately by a software-based device circuit. For the sanitization process, a mist module is used.

Conclusion

Face mask demand and cost have dramatically increased as a result of the COVID-19 pandemic's widespread presence in the world, especially in the early stages of the outbreak. For the world to continue to run smoothly and safely in the face of the deadly virus, the pandemic has put the survival of all life on Earth in danger. Choosing the best face mask to protect the wearer from the transmission of the SARS-CoV-2 virus under all circumstances is a difficult task, even though there is a wide variety of commercial masks available on the market. This is especially true given the current commercial availability of face masks of the same type but with different shapes and filtering properties. This is because using face masks, hand sanitizer, and maintaining a social distance from others are the only lines of defense currently available to people, especially those who are immunocompromised. One of the best ways to stop the coronavirus from spreading would be to recognize the symptoms of the infection as soon as possible. One of the best methods for preventing the transmission of the virus is social safety distance, which lowers the potential exposure to infectious particles. Different types of tests were conducted: some focused just on measuring temperature, others were created with sanitization in mind, and yet others were meant to look for face masks. Body temperature sensing, sanitization, and social distance maintenance are all components of this electronic smart face mask, which is an integration of all three. Our electronic smart mask provides a novel monitoring system for the real-time early detection of coronavirus. There are several situations when it is essential to directly measure or at the very least monitor high temperatures. In a crowd, the intelligent mask can identify people with elevated body temperatures and display the information. A significant role has been performed by wireless sensors in several sectors for data collecting. Implantable medical devices are affixed to people's bodies via surgery or other clinical procedures to carry out particular tasks. This mask has no negative effects on either our bodies or others nearby. Industrial AC drive systems based on FOC (Field Oriented Control) are currently very close to becoming ideal. In the modern period, any nation's economy is

dependent on its use of energy. A triple-layer protection mask with an automatic safety, sanitization, and temperature detection system. With the ability to detect our body temperature, this mask can be used for safety and sanitization purposes.

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15

A Comprehensive Review of Thermal Management Systems in Electric Vehicles

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Abstract

As the electric vehicle (EV) industry continues to grow rapidly, effective thermal management systems (TMS) have become essential to ensure the safety, efficiency, and longevity of batteries. This paper presents an in-depth review of thermal management strategies in electric vehicles, with a focus on battery cooling and heating, power electronics temperature regulation, and cabin climate control. A variety of cooling techniques, including air, liquid, phase change materials (PCM), and two-phase cooling, are examined. Furthermore, emerging trends such as active thermal management, integrated thermal systems, and the integration of artificial intelligence into thermal control are explored. The review also addresses the challenges faced in the field and outlines potential future advancements in EV thermal management systems.

Keywords: Electric Vehicles, Thermal Management Systems, Battery Cooling, Power Electronics, Cabin Climate Control, Phase Change Materials, Active Thermal Control, Artificial Intelligence.

Introduction

The growing adoption of electric vehicles (EVs) has heightened the need for effective thermal management systems to ensure optimal performance and prevent issues such as thermal runaway in lithium-ion batteries. Unlike internal combustion

engine (ICE) vehicles, EVs require tailored systems to regulate the temperature of the battery, power electronics, and maintain passenger cabin comfort. This paper reviews recent advancements in EV thermal management technologies, evaluates their effectiveness, and explores potential future developments to enhance system performance.

Importance of Thermal Management in EVs

- **Battery Performance and Safety:** Maintaining an optimal temperature range (15°C–35°C) for the battery is crucial to prevent degradation, enhance efficiency, and prolong its lifespan.
- **Power Electronics Reliability:** Effective heat dissipation from components like inverters and converters ensures the stable operation of the vehicle.
- **Passenger Comfort:** Climate control systems efficiently balance heating and cooling needs, optimizing energy usage while ensuring passenger comfort.

Battery Thermal Management Systems (BTMS)

Electric vehicle (EV) battery packs generate significant heat during charging and discharging cycles, making efficient thermal management essential. The primary strategies employed include:

- **Air Cooling:** A simple and lightweight solution, though limited in its heat dissipation capacity.
- **Liquid Cooling:** A more effective heat transfer method, commonly used in modern EVs for better performance.
- **Phase Change Materials (PCM):** A passive cooling technique that leverages latent heat absorption for temperature regulation.
- **Two-Phase Cooling:** An advanced cooling approach utilizing the phase transition of working fluids to achieve higher heat dissipation efficiency.

Thermal Management for Power Electronics

Power electronics, such as inverters and converters, generate significant amounts of heat during operation. Effective cooling strategies include:

- **Liquid Cooling:** Direct contact with heat sinks or microchannel coolers to provide efficient thermal regulation.
- **Thermal Interface Materials (TIMs):** Materials that enhance heat conduction to cooling plates for improved thermal transfer.
- **Heat Pipes:** A passive cooling solution that uses phase-change heat transfer to efficiently dissipate heat.

Cabin Thermal Management Systems

Ensuring passenger comfort while minimizing energy consumption presents a significant challenge. Key technologies employed include:

- **Heat Pumps:** An efficient solution for both heating and cooling through refrigerant cycle systems.
- **Waste Heat Recovery:** Capturing excess heat from power electronics to provide cabin heating, improving overall energy efficiency.
- **Active Airflow Control:** Advanced ventilation systems that manage airflow intelligently and create localized climate zones for enhanced comfort.

Emerging Trends and Future Directions

- **Integration of Battery and Power Electronics Cooling:** Combined cooling systems designed to enhance overall efficiency by managing heat across multiple components simultaneously.
- **Artificial Intelligence (AI)-Driven Thermal Management:** Utilization of real-time predictive algorithms for optimized control of cooling and heating processes.
- **Solid-State Cooling Technologies:** Ongoing research into thermoelectric and electrocaloric cooling methods, exploring their potential for future applications in thermal management.

Challenges and Opportunities

- **Energy Efficiency vs. Thermal Management:** Achieving an optimal balance between minimizing energy consumption and ensuring effective thermal regulation.
- **Weight and Packaging Constraints:** Overcoming design challenges to create compact and efficient systems that do not compromise vehicle performance.
- **Scalability and Cost:** Developing cost-efficient, scalable thermal management solutions to meet the demands of mass production in the electric vehicle market.

Conclusion

Thermal management is essential to the performance of electric vehicles, influencing battery longevity, safety, and overall energy efficiency. Future developments in cooling technologies, AI-based control systems, and integrated solutions will be key to advancing EV capabilities. Ongoing research and innovation are crucial to overcoming current challenges and improving the effectiveness of thermal management systems in electric vehicles.

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High Temperature Behaviour of Copper: An Investigation Using Hardness Testing

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Abstract

Copper is a commonly used metal noted for its high electrical and thermal conductivity, malleability, and corrosion resistance. Understanding its behaviour at high temperatures is critical for many industrial applications, including electronics and aircraft. This work gives a complete analysis of copper's high-temperature behaviour, with a focus on hardness testing to measure mechanical qualities. We investigate changes in hardness and microstructure, as well as the underlying processes that influence these changes, using a series of tests done at temperatures ranging from ambient to 600°C. The findings show that, whereas hardness diminishes with increasing temperature, unique phase transitions and thermal cycling effects play important roles in the observed behaviour. This work advances our understanding of copper's performance in high-temperature applications.

Keywords: Hardness, Copper, Rockwell Procedures, Microstructural.

Introduction

Copper (Cu) is an important engineering material utilised in a variety of applications due to its unique mix of characteristics. Its excellent electrical and thermal conductivity, as well as its ductility and strength, make it indispensable in electrical wire, heat exchangers, and a wide range of other applications. However, the

behaviour of copper at high temperatures is not well known, particularly in terms of mechanical characteristics and microstructural changes.

A material's hardness is a key indication of its mechanical qualities, such as wear resistance and deformation behaviour. Hardness testing, notably the Vickers and Rockwell procedures, offers vital information on the material's sensitivity to temperature changes. The purpose of this study is to evaluate the high-temperature behaviour of copper using systematic hardness testing and microstructural analysis.

Literature Review

- **Properties of Copper:** Copper is known for its strong thermal and electrical conductivity, resistance to corrosion, and ability to bear significant deformation without failing. These characteristics are due to its face-centred cubic (FCC) crystal structure, which promotes slip and twinning mechanisms during plastic deformation.
- **High Temperature Effects on metals:** At high temperatures, metals undergo a variety of changes that can have a major impact on their mechanical characteristics.
 - Thermal Expansion: As temperatures rise, they expand, which can have an impact on dimensional stability.
 - Softening: As temperatures rise, many metals lose hardness and strength.
 - Phase Transformations: Some metals may change phases, which affects their microstructure and mechanical behaviour.
- **Hardness Testing Methods:** Hardness tests are critical for determining mechanical characteristics of materials. Because of their precision and dependability, the Vickers and Rockwell tests are commonly employed on metals. These tests entail measuring the indentation left by a hardened indenter under a certain load.

Methodology

- **Sample Preparation:** Copper samples were obtained from commercial vendors and cut into standardised test pieces that were 10 mm x 10 mm x 5 mm. The samples were polished to a mirror shine with ever finer grades of abrasive paper, followed by diamond paste.
- **Hardness Testing Procedure:** A Vickers hardness tester was used to conduct hardness tests at room temperature and intervals of 100°C to 600°C. Each test lasted 10 seconds and was carried out with a weight of 10 kg. At each temperature, three indentations were produced in each sample, and the average hardness was determined.

- **Microstructural Analysis:** Microstructural alterations were investigated using optical microscopy and scanning electron microscopy (SEM). The samples were treated to various temperatures before being cooled to room temperature for examination.

Results

- **Hardness Values:** The hardness values obtained from the Vickers test are presented in Table 1.

Table 1

Temperature (°C)	Hardness (HV)
Room Temp (25)	150
100	145
200	140
300	135
400	125
500	120
600	115

Microstructural Observations

Optical and SEM scans indicated that increasing temperature caused considerable changes in microstructure. At room temperature, the grain structure was fine and equiaxed. As the temperature rose, the grain size increased and the dispersion became more diverse.

Discussion of Results

The statistics show a continuous pattern of decreasing hardness with increasing temperature, which supports current literature. Several reasons contribute to the decline in hardness, including enhanced atomic mobility and dislocation movement at higher temperatures.

Discussion

- **Mechanisms Influencing Hardness**

The observed reduction in hardness is mostly due to dislocation dynamics. At higher temperatures, dislocation climb and glide become more noticeable, resulting in a decrease in the effective stress necessary to induce plastic deformation. Furthermore, grain expansion adds to decreasing hardness since bigger grains often have lesser strength.

- **Implications for Industrial Applications**

Understanding copper's high-temperature behaviour is critical for companies that use copper components in thermally stressed environments. The findings indicate that other materials or alloying procedures may be required for applications beyond 400°C to preserve structural integrity.

- **Future Research Directions**

More study is needed to investigate the impact of alloying elements on the high-temperature behaviour of copper. Investigating the effects of varied cooling speeds after high-temperature exposure may also give information on thermal recovery mechanisms and residual strains.

Conclusion

This study uses hardness testing to conduct a complete investigation of copper's high-temperature behaviour. The data show a clear pattern of decreasing hardness with rising temperature, which may be attributed to mechanisms of dislocation movement and grain expansion. These insights are critical for understanding the limits and performance of copper in high-temperature applications. Future study should focus on alloying and treatment procedures that improve copper's high-temperature stability.

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17

Mesoporous Iron Oxide as a Photocatalyst for Photodegradation and Environmental Remediation

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Abstract

Mesoporous iron oxide (Fe_2O_3) has garnered significant attention as an effective photocatalyst in environmental remediation, particularly for the degradation of organic pollutants under light irradiation. The high surface area, tunable porosity, and photocatalytic properties of mesoporous Fe_2O_3 make it an ideal candidate for photodegradation processes, such as the removal of dyes, pesticides, and other hazardous compounds. This review focuses on the synthesis, structural features, and photocatalytic performance of mesoporous iron oxide, with an emphasis on its application in photocatalytic degradation and other related processes. Moreover, we discuss the challenges and future prospects of this material in large-scale environmental applications.

Keywords: Mesoporous, Iron Oxide, Photocatalyst, Photodegradation, Organic Pollutants.

Introduction

Photocatalysis, driven by light irradiation, is an effective method for the degradation of organic pollutants, driven by the generation of reactive species such as hydroxyl radicals ($\text{OH}\cdot$) and superoxide anions ($\text{O}_2^{\cdot-}$). In this context, mesoporous iron oxide (Fe_2O_3), particularly in its hematite ($\alpha\text{-Fe}_2\text{O}_3$) form, has attracted considerable interest as a photocatalyst for environmental remediation due to its abundance, non-toxicity, stability, and ease of preparation. Mesoporous Fe_2O_3 possesses a unique

combination of high surface area, ordered porous structure, and favorable electronic properties, making it an ideal candidate for enhancing the photocatalytic activity under visible light irradiation.

Synthesis of Mesoporous Iron Oxide

Mesoporous Fe_2O_3 is typically synthesized using templating methods, including hard templating, soft templating, and self-assembly techniques. These methods enable precise control over the pore structure, size, and surface area of the resulting material, which are crucial for optimizing photocatalytic performance.

Common Synthesis Methods

- **Sol-gel Method:** A precursor solution, often based on iron salts such as iron chloride (FeCl_3) or iron nitrate ($\text{Fe}(\text{NO}_3)_3$), is gelled under controlled conditions, and subsequent calcination leads to mesoporous iron oxide.
- **Hydrothermal Synthesis:** Under high temperature and pressure, Fe precursor solutions react to form mesoporous Fe_2O_3 with well-ordered structures.
- **Template-Assisted Methods:** Surfactants such as cetyltrimethylammonium bromide (CTAB) or block copolymers are often used as templates to control pore structure. After calcination, the template is removed, leaving a mesoporous iron oxide framework.

Structural Features

- **High Surface Area:** Mesoporous Fe_2O_3 typically exhibits a surface area in the range of 100–500 m^2/g , which is favorable for photocatalytic reactions that rely on surface-active sites.
- **Ordered Porosity:** Well-defined and uniform pores with sizes typically between 2–50 nm enhances the adsorption and diffusion of pollutants during the photocatalytic process.
- **Crystallinity and Phase Control:** The ability to control the crystallinity of Fe_2O_3 influences its electronic properties and photocatalytic efficiency. The hematite phase ($\alpha\text{-Fe}_2\text{O}_3$) is often preferred for visible light photocatalysis due to its narrow band gap.

Mechanism of Photocatalytic Activity

The photocatalytic activity of mesoporous iron oxide is based on the generation of charge carriers under light irradiation, typically in the visible range for Fe_2O_3 due to its moderate band gap ($\sim 2.1\text{--}2.2$ eV). Upon exposure to light, electrons are excited from the valence band to the conduction band, generating electron-hole pairs. These charge carriers can then participate in redox reactions at the surface of the material, leading to the formation of reactive oxygen species (ROS), such as

hydroxyl radicals ($\text{OH}\cdot$) and superoxide anions ($\text{O}_2\cdot^-$), which are responsible for the degradation of organic pollutants.

Key Steps in the Photocatalytic Process

- **Light Absorption:** Upon irradiation with visible light, electrons in the Fe_2O_3 are excited from the valence band to the conduction band, creating electron-hole pairs.
- **Charge Separation:** The spatial separation of the excited electrons and holes occurs, with the electrons migrating to the surface, where they can reduce adsorbed oxygen molecules to form $\text{O}_2\cdot^-$, and the holes migrate to the surface to oxidize water or adsorbed organic molecules, generating $\text{OH}\cdot$.
- **Pollutant Degradation:** The ROS generated at the surface react with the organic contaminants, leading to their oxidation and eventual mineralization to harmless by-products such as carbon dioxide and water.

Applications of Mesoporous Iron Oxide as a Photocatalyst

Photodegradation of Organic Pollutants

One of the most important applications of mesoporous Fe_2O_3 is the photocatalytic degradation of organic pollutants in water and air. The high surface area and porous structure of mesoporous Fe_2O_3 materials promote efficient adsorption of pollutants, facilitating their interaction with ROS generated upon light irradiation.

- **Dye Degradation:** Mesoporous Fe_2O_3 has been widely studied for the degradation of organic dyes, such as methylene blue, rhodamine B, and Congo red, under visible light. These dyes are commonly found in industrial effluents, and their removal is crucial for water treatment applications.
- **Pesticide Removal:** Mesoporous Fe_2O_3 can effectively degrade pesticides such as atrazine and organophosphates, which are hazardous to the environment and human health. The photocatalytic breakdown of these compounds offers a promising solution for agricultural runoff water purification.
- **Pharmaceutical Pollutants:** In addition to dyes and pesticides, mesoporous Fe_2O_3 has shown efficiency in degrading pharmaceutical residues, which are emerging as significant environmental contaminants in wastewater.

Environmental Remediation

- **Air Purification:** Mesoporous iron oxide materials have been used in the photodegradation of gaseous pollutants, such as volatile organic compounds (VOCs) and nitrogen oxides (NO_x), under UV and visible light. Their high surface area allows for the adsorption of pollutants, and their photocatalytic properties promote the oxidation of these gases to non-toxic products.

- **Water Purification:** The removal of heavy metals, such as arsenic, from contaminated water through photocatalysis has been explored using mesoporous iron oxide. Although its primary role is the photodegradation of organic pollutants, mesoporous Fe_2O_3 can also act as an adsorbent for heavy metals under specific conditions.

Energy-Related Applications

- **Solar Hydrogen Production:** Mesoporous Fe_2O_3 has been investigated for its potential as a photocatalyst in solar hydrogen production through water splitting. The visible light photocatalytic activity of Fe_2O_3 allows it to utilize solar energy efficiently, making it a promising candidate for sustainable hydrogen generation.
- **Photocatalytic CO_2 Reduction:** Another emerging application of mesoporous Fe_2O_3 is in photocatalytic CO_2 reduction, where it can facilitate the conversion of CO_2 into valuable chemicals such as methane or methanol under light irradiation. This process could contribute to carbon capture and utilization efforts.

Challenges and Future Prospects

Despite the promising photocatalytic activity of mesoporous Fe_2O_3 , several challenges remain:

- **Charge Recombination:** The fast recombination of electron-hole pairs limits the efficiency of photocatalysis. To address this, researchers are exploring ways to enhance charge separation, such as by doping Fe_2O_3 with metals or carbon-based materials or by coupling it with other semiconductors.
- **Stability and Durability:** Under prolonged use, mesoporous Fe_2O_3 can experience deactivation due to surface modification or the loss of structural integrity. Strategies such as surface functionalization and composite material formation are being explored to improve its stability.
- **Scalability:** The synthesis of mesoporous Fe_2O_3 at a large scale while maintaining consistent quality and performance for practical applications, such as water treatment or air purification, is still a significant hurdle.

Future research directions may focus on optimizing the synthesis methods to produce mesoporous iron oxide at an industrial scale, improving the photocatalytic efficiency through structural modifications or hybrid materials, and enhancing the stability and reusability of the catalyst in real-world environmental applications.

Conclusion

Mesoporous iron oxide presents a highly effective and promising material for photocatalytic applications, particularly in environmental remediation and pollutant degradation. Its high surface area, ordered porosity, and ability to utilize visible light

make it an attractive candidate for addressing pressing environmental challenges, such as water and air pollution. Although challenges remain in improving photocatalytic efficiency, stability, and scalability, ongoing research into the optimization of synthesis methods, surface modifications, and hybrid material systems holds significant potential for the widespread application of mesoporous Fe_2O_3 in sustainable environmental technologies.

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Recycling of Plastics in the Present Era

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Abstract

Pollution associated with plastic wastes is increasing day by day. In spite of several government directives, restrictions in the use plastics, specially single used plastics, has not yet been executed, owing to its easy availability, light-weight and significantly low cost. But, problem appears when they are disposed after use. Most of the plastics, used in our daily life, are non-bio-degradable, i.e., they are not degraded by the biological entities present in the soil and may take up to several thousand years to degrade. Recycling of plastics is considered to be the most viable and economical way to get rid of such pollution. In global scenario, governments as well as the pollution control boards are promoting recycling to manage the plastic wastes most effectively. In today's pandemic situation the plastic waste management scenario is facing challenges due to uncontrolled use of plastics in terms of personal protective equipment. This has led to scientific communities to give priority in the plastic waste management to save the earth. Herein, a state-of-art overview of recycling is provided together with an outlook for the future by using popular polymers such as polyolefin, poly (vinyl chloride), polyurethane, and poly (ethylene terephthalate) as examples. Different types of recycling, such as, primary, and secondary, recycling are discussed together. Global introduction of waste utilization techniques to the polymer market has not yet been explored much and thus remained as an active field of research.

Keywords: Recycling, LDPE, HDPE, Composite Materials.

Introduction

Plastics have proved themselves as very promising candidates in last decades for commercial applications owing to their low-cost, easy process ability and light weight. Thus, they have replaced conventional metal due to consumer's preference towards them. Single used plastic bags are used widely worldwide. Plastic pollution is the accumulation of plastic objects and particles (e.g. plastic bottles, bags and micro beads) in the Earth's environment that adversely affects wildlife, wildlife habitat, and humans.

Plastics that act as pollutants are categorized into micro-, meso-, or macro debris, based on size. Plastics are inexpensive and durable making them very adaptable for different uses; as a result levels human produce a lot of plastic. Most of the plastic bags are non-biodegradable. , i.e., they are not degraded by the biological entities present in the soil and may take up to several thousand years to degrade.[1] This facilitates large volumes of plastic to enter the environment as mismanaged waste and for it to persist in the ecosystem. Production of polymers has always been coupled with the challenge of their further utilization after use. Plastic is one of the most major innovations of 20th century and is an omnipresent material. A slower development within the field of recycling creates a serious problem: tens of millions of tons of used polymeric materials are being discarded every year. The amount of plastics in circulation is projected to increase from 236 to 417 million ton per year by 2030 [2]. It leads to ecological and consequently social problems. Waste deposition in landfills becomes increasingly unattractive because of its low sustainability, increasing cost, and decreasing available space. Dumping from ships at sea has already been prohibited in 1990. Moreover, unsustainable methods lead to the exclusion of significant amounts of materials from the economic cycle.

The plastic pollution can be well managed by reduce, reuse and recycle strategy. We have to carry our own bags to market. We have to carry reusable water bottle instead of plastic bottles. Government should ban the polybags which is used in the market in excess and government should concern people to carry his/her own bags in each public place to carry things. After using the plastic bags, it is our duty that not to throw the bags here and there, it should be kept in a dustbin of municipality. And last but not the least; we should take the responsibility to aware the unconscious people about the hazards of plastic pollution. [3]

Recycling is considered to be the most economical and viable way to manage solid waste pollution. But, even after extensive encouragement for recycling it has not been practised much worldwide. Very unfortunately, negligible amount of plastic wastes are recycled in present days. In 2016, only 16% of polymers in flow were collected for recycling while 40% were sent to landfill and 25% were incinerated [4]. Recently, European countries have increased efforts to improve recycling rates. In 2018, 29.1 million tons of post-consumer plastic wastes were collected in Europe [5].

While less than a third of this was recycled, it represented a doubling of the quantity recycled and reduced plastic waste exports outside the European Union (EU) by 39% compared to 2006 levels. Much of this plastic flow (39.9%) was for packaging.

In this review, we enlighten the present global scenario of recycling and difficulties associated with it. Few recycling methodologies have also been explored. The applications of recycled plastics, as well as, the importance of recycling in the post-pandemic situation can also be found in the present review.

Objective

The objective of this Review is to provide a snapshot of the state of art, relevant social developments and market evolutions, and research and development activities in the field of recycling. Our study is aimed mostly, but not exclusively, at recycling of discarded polymers that are available in large amounts or can be particularly efficiently reused and reintegrated into industrial processes. Therefore, recycling technologies are illustrated through examples of processing of the polyolefin (PO) polypropylene (PP) and polyethylene (PE), polyurethane (PU), hard and soft poly(vinyl chloride) (PVC), and poly(ethylene terephthalate) (PET).[6] The importance of management of plastic wastes in the pandemic, as well as, post-pandemic has also been explored.

Global Status of Recycling

The total amount of plastic ever produced worldwide, up until 2015, is estimated to be 8.3 billion tonnes. Approximately 6.3 billion tonnes of this has been discarded as waste, of which around 79% has accumulated in landfills or the natural environment, 12% was incinerated, and 9% has been recycled, although only ~1% of all plastic has ever been recycled more than once. By 2015 global production had reached some 381 Mt per year, greater than the combined weight of everyone on Earth. The recycling rate in that year was 19.5%, while 25.5% was incinerated and the remaining 55% disposed of, largely to landfill. These rates lag far behind those of other recyclables, such as paper, metal and glass. Although the percentage of material being recycled or incinerated is increasing each year, the tonnage of waste left-over also continues to rise. This is because global plastic production is still increasing year-on-year. Left unchecked production could reach ~800 Mt per year by 2040, although implementing all feasible interventions could reduce plastic pollution by 40% from 2016 rates.

Urban India generates 62 million tonnes of waste (MSW) annually, and it has been predicted that this will reach 165 million tonnes in 2030. 43 million tonnes of municipal solid waste is collected annually, out of which 31 million is dumped in landfill sites and just 11.9 million is treated. [8] Waste is not segregated in India when it is collected, and vast amounts of plastic litter clog public spaces as well as water bodies. India's segregation and recycling system operates through an informal chain of workers- in most unscientific way.

Recycling rates vary between the different types of plastic, reflecting the ease with which they can be sorted and reprocessed. PET bottles and HDPE have the highest recycling rates, whereas others such as polystyrene foam are sometimes not recycled at all. [9]

According to the United Nations, only 9% of the plastic waste ever produced globally is recycled. [10]

Recycling Procedure

There are basically two processes for recycling, viz., primary mechanical recycling and secondary mechanical recycling.

- **Primary Mechanical Recycling**

Primary mechanical recycling is the direct reuse of uncontaminated discarded polymer into a new product without loss of properties. In most cases, primary mechanical recycling is conducted by the manufacturer itself for post-industrial waste. Therefore, this process is often termed closed-loop recycling. In principle, post-consumer waste can be also subjected to primary recycling; however, in this case, a number of additional complications may arise, such as necessity of selective collection and rough (manual) sorting. Such issues may significantly increase the costs of recyclates. Thus, in general, this method is unpopular among recyclers.

Before reintegration of a used material into a new product, it normally requires grinding, that is, shredding, crushing, or milling. These processes make the material more homogeneous and easier to blend with additives and other polymers for further processing. Broken-down material can also be integrated in a more controllable way into a common production process. Moreover, it becomes easier to purify. An additional cleaning step could be useful or even necessary to avoid problems that might otherwise occur with the final products. A recyclate can be given a new shape after melting.

The best-known methods of this type of processing of mechanical recyclates are injection moulding, extrusion, rotational moulding, and heat pressing. Therefore, only thermoplastic polymers, such as PP, PE, PET, and PVC, can normally be mechanically recycled. [12]

- **Secondary Mechanical Recycling**

Exact content and purity grade of EOL- and PC-streams are frequently not known; therefore, they are processed through secondary mechanical recycling, which involves separation/purification in contrast to primary recycling. As well as in the case of primary recycling normally only thermoplastic polymers can be reprocessed. The polymer is not changed during the secondary recycling, but its molecular weight falls owing to chain scissions, which occur in the presence of water and trace amounts of acids. This may result in the reduction of mechanical properties. This phenomenon

can at least be partially counteracted by intensive drying, application of vacuum degassing, and use of various stabilizing additives. Another reason for the drop in mechanical properties after recycling is the contamination of the main polymer (matrix) with other polymers. Most of the polymers are not compatible with each other (i.e., their blends have mechanical properties that are inferior to those of the pure constituents). Examples are PET impurities in PVC, in which solid PET lumps form in the PVC-phase. This leads to significantly downgraded properties and consequently less-valuable end products. Efficient separation of different materials before integration into a new product is a solution.

Fourier-transform and near-infrared spectroscopy are frequently used to determine the polymer type, whereas an optical colour recognition camera is a popular tool to separate clear and coloured materials from each other. X-ray detection is used to identify and subsequently isolate PVC to avoid the undesired formation of HCl during reprocessing at elevated temperatures. [14]

Important factors of secondary recycling are: availability of waste materials for recycling (logistics, volumes), costs of (selective) collection, storage, and transportation form or shape (blades, fibres...) composition, purity grade, price difference between virgin and recycled materials, presence of desired and undesired additives, availability and costs of techniques and processes.

Automotive shredder residue from shredded car components is a typical material for secondary recycling. The resulting products can be further used in the form of composites for new car components. Secondary recycling is also widely used for recycling of post-consumer PU foam, for which the foam is first crushed into flakes and then given a new form by remoulding. However, the quality of the end product is often not satisfactory as a result of polymer degradation. [15]

When secondary recycling becomes too expensive or complicated, waste is converted into fuel or incinerated directly.

Difficulties in Recycling

There are several complications associated with recycling which have restricted its widespread applications; only 9% of the plastic wastes are recycled globally. In this part we will try to find out the underlying difficulties and suitable pathways to manage them.

- The value of plastics wastes depend on the quality as well as disposal of plastics after use from the end of consumer. It is also a system dictated by market demand, price and local regulations. For example, recycled plastics are generally of lower quality than virgin plastic. Yet, its price is comparable if not higher than brand new material. It is difficult to create market demand unless businesses recognise the value of recycled plastic and are willing to pay for it.

- Most of us do not have the habit of sorting or cleaning our trash before disposal. To get to the stage where everyone responsibly sort and clean their plastic waste will take a significant amount of time and that is not ideal given that the plastics problem is an urgent one.
- Paint is another material which makes the recycling difficult. Before recycling paint should be removed and thus the recycling process becomes complicated and costly.
- Most of the plastics used in our daily life are composite materials. Composite materials contain more than one type of raw material and that makes the recycling process more complicated.
- Plastics are also used in conjunction with other materials. But the multi-layered material requires a great deal of resources and time to recycle. There is little incentive for recycling companies to process such complicated products. Recycled plastic faces a weak market since its virgin counterpart is both cheaper and of better quality. [16]
- No global action plan for plastic waste management has also restricted the global drive of recycling.
- Manufacturing of cheap composite materials using less amount of plastics has aggravates the situation by lowering down the plastic cost and thus plastics are being used in extensive levels without caring the environmental factors.

Future Challenges

To save the earth governments and stakeholders should put their hands together to save our earth from the plastic waste pollution. Plastic waste management is considered to be an important waste management stream. Proper and systematic utilization of plastic wastes may lead to useful by products such as fuel. Planning and professionalism are thus very much required in this regard.

Plastic wastes should be segregated first to make useful products. PET, PS, PMMA, PP, HDPE, LDPE based material can be recycled easily if they are in virgin form or having definite composite composition. The thermosets used in several purposes are difficult to process and thus can be utilized in the construction fields, as well as, in fuel manufacturing. Thus, wastes can be widely used in the generation of economical products, sometimes referred as 'Waste to Wealth'.

Conclusion

Plastic wastes have proved themselves as a field of immense attention owing to the existence of our environment. Lots of single used plastics are disposed globally in to the environment without any treatment and thus causing severe plastic waste based pollution. In this review we tried to find the underlying factors in plastic waste pollution and its management via recycling. Studies on plastic wastes reveal that, it

requires greater cost to dispose plastics, rather than to recycle it. We also have tried to find the difficulties associated with recycling and their remedies. The waste management scenario is facing more challenges due to COVID-19 pandemics, which has increased the disposal of single used plastics extensively. Though it seems to aggravate the waste management scenario, accurate planning, professional management can lead to generate economical products without harming the environment. Governments and stakeholders should put hands together to get rid of this plastic waste pollution.

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A Review on Dip-Slip Faults on Viscoelastic Half-Space: Mechanics, Modeling, and Implications

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Abstract

Dip-slip faults on viscoelastic half-spaces are crucial for understanding crustal deformation and earthquake cycle dynamics. This review integrates theoretical mechanics, numerical modelling, and mathematical formulations to explore fault behaviour in viscoelastic media. Emphasis is placed on stress-strain relationships, viscoelastic relaxation, and implications for tectonic processes. Challenges and research directions are discussed to advance the field.

Keywords: Dip-slip Faults, Viscoelastic Space, Crustal Deformation, Stress-Strain Relationship.

Introduction

Dip-slip faults embedded in a viscoelastic half-space are key to understanding time-dependent crustal deformation, post-seismic relaxation, and stress evolution. Unlike purely elastic models, viscoelastic models capture both instantaneous and delayed deformation, offering insights into long-term tectonic processes. This article presents a comprehensive review of mathematical formulations and modeling approaches for dip-slip faults in viscoelastic media.

There are faults (such as the Sierra Nevada/Owens Valley: Basin and Range faults, Rocky Mountains, Himalayas, and Atalanti fault of central Greece, a steeply dipping fault with dip 60, 80(deg)) where the surface level changes during motion,

indicating that some faults are dip-slip in nature, even though some faults are strike-slip (finite or infinite in length). A ground-breaking investigation on static ground deformation in elastic media was started by Steketee(1958a,b). Some authors favoured layered models with elastic layer(s) over elastic or viscoelastic half space, and the majority of these works assumed that the medium was elastic and/or viscoelastic.

There are faults (such as the Sierra Nevada/Owens valley: Basin and Range faults, Rocky Mountains, Himalayas, and the Atalanti fault of central Greece—a steeply dipping fault with dip 60, 80 (deg)) where the surface level changes during motion, indicating that some faults are dip-slip in nature, even though some faults are strike slip (finite or long). Therefore, in order to forecast future events in space and time, it is essential to comprehend the mechanism of plate motion in the dip direction both before and after fault movement with displacement dislocation, as well as the nature of stress-strain accumulation/release in spatial and temporal coordinates.

Maruyama (1964; 1966) started a ground-breaking study on static ground deformation in elastic media. The analysis of displacement, stress, and strain for dip-slip movement by Savage and Hastie (1966) was excellent. Many authors, including Rybicki (1971; 1973), Sato (1972), Rosenman and Singh (1973; 1974), and Nur and Mavko (1974), have since developed some theoretical models in this area. Ghosh and Sen (2011) talked about how stress builds up in the lithosphere-asthenosphere system close to buried faults. Another study that might be brought up is that of Fuis et al. (2012). A layered model with a viscoelastic layer or layers over a viscoelastic half space will be more realistic for the lithosphere-asthenosphere system than the majority of earlier research, which assumed that the media were elastic and/or viscoelastic.

Investigations on the post-glacial uplift of Fennoscandia and parts of Canada indicate that at the termination of the last ice age, which happened about 10 millennia ago a 3 km ice cover melted gradually leading and upliftment of the regions. Schofield (1964), Chathles (1975), and Fairbridge (1961) have all discussed evidence of this upliftment. If the Earth were perfectly elastic, this deformation would be managed after the removal of the load, but it did not so happened, which indicates that the Earth crust and upper mantle is not perfect elastic but rather viscoelastic in nature.

Mechanics of Dip-Slip Faults in Viscoelastic Media

Stress-Strain Relationships

The behavior of a viscoelastic medium is governed by constitutive equations that describe the relationship between stress (σ_{ij}) and strain (ε_{ij}). Commonly used models include:

- **Maxwell Model**

The Maxwell model combines a spring (elastic component) and a dashpot (viscous component) in series:

$$\sigma_{ij} + \eta \frac{\partial \sigma_{ij}}{\partial t} = 2\mu \frac{\partial \varepsilon_{ij}}{\partial t},$$

where μ is the shear modulus and η is the viscosity.

- **Burgers Model**

The Burgers model extends the Maxwell model by adding a Kelvin-Voigt element:

$$\sigma_{ij} + \eta_1 \frac{\partial \sigma_{ij}}{\partial t} = 2\mu_1 \frac{\partial \varepsilon_{ij}}{\partial t} + \frac{\eta_2}{\mu_2} \frac{\partial^2 \varepsilon_{ij}}{\partial t^2},$$

where η_1, η_2 are viscosities, and μ_1, μ_2 are shear moduli.

- **Fault Slip and Displacement**

The displacement field u_i due to fault slip Δu satisfies the Navier-Cauchy equation in a viscoelastic medium:

$$\nabla \cdot \sigma_{ij} = \rho \frac{\partial^2 u_i}{\partial t^2},$$

where ρ is the density of the medium. The boundary condition at the fault surface is given by:

Δu , where $[u_i]$ represents the displacement discontinuity.

- **Viscoelastic Relaxation**

Viscoelastic relaxation after fault slip redistributes stress over time. The relaxation time τ is defined as:

$$\tau = \frac{\eta}{\mu},$$

where μ is the elastic modulus and η is the viscosity.

Numerical Modeling Approaches

- **Finite Element Method (FEM)**

FEM is widely used for solving the Navier-Cauchy equations in complex viscoelastic media. The discretized system of equations is:

$$\{u\} = \{F\},$$

where $[K]$ is the stiffness matrix, $\{u\}$ is the nodal displacement vector, and $\{F\}$ is the force vector.

- **Analytical Models**

For simple geometries, analytical solutions provide closed-form expressions for stress and displacement fields. For example, the surface displacement u_z due to a vertical dip-slip fault in a viscoelastic half-space can be approximated as:

$$u_z(x, t) = \frac{\Delta u}{\pi} \arctan\left(\frac{x}{t \cdot v}\right),$$

where v is the relaxation velocity.

- **Boundary Element Method (BEM)**

BEM simplifies modeling by reducing the problem to fault boundaries. The traction and displacement are related as:

$$T = G\Delta u,$$

where G is the Green's function.

Geophysical Implications

- **Postseismic Deformation**

Postseismic deformation observed through GPS and InSAR provides constraints on the viscoelastic properties of the lithosphere. The time-dependent surface displacement can be modeled as:

$$\Delta u(t) = \Delta u_0(1 - e^{-t/\tau}),$$

where Δu_0 is the initial displacement.

- **Stress Evolution and Seismic Hazard**

Viscoelastic relaxation alters the stress field, influencing earthquake recurrence. The Coulomb stress change $\Delta\sigma_c$ is given by:

$$\Delta\sigma_c = \Delta\tau - \mu\Delta\sigma_n,$$

where $\Delta\tau$ is the shear stress change and $\Delta\sigma_n$ is the normal stress change.

Challenges and Future Directions

Key challenges include:

- Accurate estimation of viscoelastic parameters across spatial scales. - High-resolution temporal monitoring of deformation. - Integration of observational data with numerical models.

Future research should focus on coupling viscoelastic models with hydromechanical processes and advancing computational techniques for large-scale simulations.

Conclusion

Dip-slip faults in viscoelastic half-spaces are fundamental to understanding tectonic and seismic processes. Mathematical formulations and numerical models have significantly advanced the field, but continued interdisciplinary efforts are essential to address remaining challenges.

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Mathematical Modeling of COVID-19 Spread Dynamics: A Comprehensive Review

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Abstract

The COVID-19 pandemic has underscored the critical role of mathematical modeling in understanding the transmission dynamics of infectious diseases, predicting epidemic trajectories, and informing public health interventions. This review synthesizes the diverse approaches to modeling the spread of COVID-19, including compartmental models, agent-based models, network-based models, and machine learning techniques. Key insights into parameter estimation, model calibration, and policy applications are discussed. Challenges and future directions in the field, such as integrating heterogeneous data sources and incorporating behavioral factors, are also highlighted.

Keywords: COVID-19, Mathematical Modeling, SIR Model, Agent-Based Modeling, Network Models, Machine Learning, Public Health Interventions.

Introduction

Mathematical models have been instrumental in unraveling the complexities of infectious disease transmission [1-4]. During the COVID-19 pandemic, these models guided decision-making in public health and provided insights into the efficacy of interventions such as lockdowns, vaccination campaigns, and non-pharmaceutical measures. This review explores the landscape of mathematical modeling efforts aimed at understanding COVID-19 dynamics.

Types of Mathematical Models

- **Compartmental Models**

Compartmental models, such as the Susceptible-Infectious-Recovered (SIR) framework and its variants, have been widely used to describe COVID-19 spread. Extensions like SEIR (Susceptible-Exposed-Infectious-Recovered) include an exposed phase to capture the latent period of the disease.

Key Applications:

- Estimation of basic reproduction number (R_0).
- Simulation of intervention scenarios (e.g., social distancing).

- **Agent-Based Models (ABMs)**

ABMs simulate individual agents with specific attributes and behaviors, enabling detailed exploration of transmission dynamics in heterogeneous populations.

Strengths

- Flexibility in modeling heterogeneous interactions.
- Incorporation of demographic and geographic variability.

- **Network-Based Models**

Network-based approaches model individuals as nodes connected by edges, representing interactions. These models are particularly suited for studying superspreading events and localized outbreaks.

- **Machine Learning Models**

Machine learning techniques leverage large datasets to forecast epidemic trends and identify influential factors. Neural networks, random forests, and gradient boosting methods have been applied to predict case counts and hospitalization rates.

Parameter Estimation and Calibration

Accurate parameter estimation is crucial for model reliability. Methods such as Bayesian inference, maximum likelihood estimation, and ensemble approaches are used to estimate transmission rates, incubation periods, and other parameters.

Data Sources

- Epidemiological data (e.g., case counts, mortality rates).
- Mobility data from smartphones.
- Genomic sequencing of viral strains.

Model Applications

- **Public Health Policy**

Models have been used to:

- Design optimal vaccination strategies.
- Evaluate the impact of lockdown measures.
- Predict hospital capacity requirements.
- **Scenario Analysis**

Simulating "what-if" scenarios helps policymakers anticipate outcomes under various intervention strategies.

Challenges in COVID-19 Modeling

- **Data Limitations**
 - Incomplete and biased reporting.
 - Temporal changes in testing and reporting policies.
- **Behavioral Factors**

Incorporating human behavior, such as compliance with interventions, remains challenging.
- **Computational Complexity**

High-fidelity models, such as ABMs, require significant computational resources.

Future Directions

- **Integration of Multisource Data**

Combining data from diverse sources, including wastewater surveillance and social media, can enhance model accuracy.
- **Real-Time Adaptive Models**

Adaptive models that update dynamically with incoming data will be critical for future pandemics.
- **Interdisciplinary Approaches**

Collaboration across disciplines, including epidemiology, computer science, and sociology, will enrich modeling efforts.

Conclusion

Mathematical modeling has been a cornerstone of the global response to COVID-19. While significant progress has been made, the pandemic has highlighted areas for improvement, particularly in integrating diverse data sources and accounting for behavioral factors. Future advancements will enhance our ability to predict and mitigate the impacts of infectious diseases.

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Modeling and Analysis of Malaria Transmission Dynamics: Insights and Interventions

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Abstract

This dissertation presents an in-depth analysis of the SEIR model for infectious disease dynamics using both the Runge-Kutta and Euler numerical methods. The SEIR model, which segments the population into susceptible (S), exposed (E), infected (I), and recovered (R) compartments, was employed to simulate the spread of an infectious disease over a time interval from $t = 0$ to $t = 100$. Initial conditions and parameters were set to reflect a realistic scenario of disease transmission. The Runge-Kutta method provided a detailed and accurate depiction of the disease progression, demonstrating a steady decrease in the susceptible population, an initial peak and subsequent decline in the exposed population, a peak in the infected population around $t = 50$, and a continuous increase in the recovered population. However, the method revealed potential numerical instability, highlighted by an unexpected negative value in the recovered population at the end of the simulation. The Euler method, while simpler, effectively captured the general trends of the SEIR model but showed limitations in accuracy, particularly over longer time intervals. The error analysis compared to the analytical solution indicated mean absolute errors of 28.39 for the susceptible population, 5.78 for the exposed population, 15.97 for the infected population, and 6.93 for the recovered population. The study underscores the necessity for careful parameter validation and the potential for employing more advanced numerical techniques to enhance model accuracy and stability. Future research directions include parameter optimization, exploration of advanced and stochastic numerical methods, model extensions, and integration of real-time epidemiological data. The findings provide valuable insights into the dynamics of

infectious diseases and emphasize the critical role of numerical methods in epidemiological modeling, with implications for better disease management and public health strategies.

Introduction

Malaria, a potentially deadly infectious disease, is caused by *Plasmodium* parasites transmitted through the bites of infected female *Anopheles* mosquitoes. [23] It remains one of the most significant public health challenges globally, particularly in tropical and subtropical regions where the *Anopheles* mosquitoes thrive. The disease manifests with symptoms such as fever, chills, headache, muscle aches, and fatigue, and if left untreated, it can lead to severe complications such as organ failure and death, especially in children under five years old and pregnant women.

One of the critical aspects of malaria control is prevention, which primarily focuses on vector control strategies to reduce mosquito populations and prevent mosquito bites. These strategies include the use of insecticide-treated bed nets, indoor residual spraying of insecticides, and environmental management to eliminate mosquito breeding sites. Additionally, antimalarial drugs are used for both treatment and prevention. However, the emergence of drug-resistant strains of the *Plasmodium* parasites poses a significant challenge to effective malaria management. [12]

Efforts to combat malaria have intensified over the years through various initiatives led by governments, non-governmental organizations, and international agencies. The World Health Organization's Global Malaria Programme, along with partners such as the Roll Back Malaria Partnership and the President's Malaria Initiative, coordinates global efforts to control and eventually eliminate malaria [23]. Despite progress in reducing malaria incidence and mortality rates in some regions, the fight against malaria continues to require sustained investment, innovation, and collaboration to achieve the ultimate goal of malaria eradication.

Mathematical modeling has become an indispensable tool in the study of malaria transmission dynamics, providing valuable insights into the spread of the disease and guiding the design of effective control strategies. Over the years, various modeling approaches have been developed, ranging from simple compartmental models to complex stochastic simulations. This chapter aims to review the evolution of malaria modeling, highlighting key contributions in the field and identifying gaps that remain to be addressed.

Compartmental models represent one of the earliest and most widely used approaches in malaria modeling. These models, such as the classic Susceptible-Infectious-Recovered (SIR) framework, divide populations into compartments representing different disease states [17]. By tracking the flow of individuals between

compartments, compartmental models allow for the simulation of disease transmission dynamics and the evaluation of intervention strategies [17]. Ross and Macdonald laid the foundational work for malaria modeling, introducing the concept of the basic reproduction number, R_0 , which determines whether an infection will spread in a population [17]. Subsequent models have built on this framework, incorporating more realistic assumptions about mosquito and human populations.

Stochastic models, which account for the random nature of malaria transmission, offer a more detailed understanding of disease dynamics, especially in small populations or over short time periods. Unlike deterministic models, which assume fixed parameter values, stochastic models consider individual variability and probabilistic variations in transmission parameters [18]. This stochasticity can significantly impact the persistence and extinction of malaria, particularly in low-transmission settings [18]. Smith et al. developed a stochastic version of the classical Ross-Macdonald model, demonstrating the significant impact of demographic stochasticity on malaria persistence and extinction [18]. Other studies have integrated stochasticity with environmental factors, such as temperature and rainfall, to predict malaria outbreaks more accurately [16].

Spatial models consider the geographical distribution of malaria and the movement of humans and mosquitoes between different regions. These models are crucial for understanding the spread of malaria in heterogeneous environments and for designing region-specific intervention strategies. The work by Chitnis, Hyman, and Cushing highlighted the importance of spatial heterogeneity in malaria transmission, showing how differences in mosquito density and human movement patterns can affect disease dynamics [6]. More recent models have used geographic information systems (GIS) and remote sensing data to enhance the spatial resolution of malaria models [19]. These spatially explicit models provide valuable insights into the spatial patterns of malaria transmission and the effectiveness of targeted interventions [19].

Climate-based models integrate environmental variables such as temperature, humidity, and rainfall, which significantly influence mosquito lifecycle and malaria transmission. These models are particularly relevant in the context of climate change and its potential impact on malaria distribution. Paaïjmans et al. developed a model that links climate variables with mosquito development and survival rates, providing insights into how climate change could alter malaria transmission patterns [15]. Other studies have used long-term climate data to predict future changes in malaria endemicity [3]. By incorporating climate variables into malaria models, researchers can better understand the drivers of transmission and anticipate changes in disease risk [3].

Socio-economic models incorporate human behavior, economic conditions, and public health interventions into malaria transmission dynamics. These models are

essential for understanding the broader context of malaria control and for designing effective intervention strategies. Yang et al. explored the role of socio-economic factors in malaria transmission, showing how improvements in living conditions and healthcare access can reduce malaria incidence [24]. Recent models have also examined the impact of migration and urbanization on malaria spread [20]. By considering the social and economic determinants of malaria transmission, these models provide valuable insights into the underlying drivers of disease and the potential impact of interventions. [20]

Integrated models aim to combine multiple factors—biological, environmental, and socio-economic to provide a comprehensive understanding of malaria transmission. By integrating age-specific immunity, heterogeneity in mosquito biting rates, and other relevant factors, these models offer improved accuracy in predictions and interventions. Aron and May incorporated age-specific immunity and heterogeneity in mosquito biting rates into their model, demonstrating the importance of these factors in determining malaria prevalence. [1] Other integrated models have used Bayesian inference and Markov chain Monte Carlo methods to handle the uncertainty and variability in malaria data. [2] Despite these advancements, several gaps remain in the literature.

Many models focus on specific aspects of malaria transmission, lacking a holistic approach that integrates all relevant factors. Additionally, there is a need for models that can be easily adapted to different regions and that can incorporate real-time data for dynamic prediction and control. This dissertation aims to address these gaps by developing a comprehensive mathematical model that integrates biological, environmental, and socio-economic factors. The model will be validated using empirical data from multiple regions and will provide insights into effective malaria control strategies.

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Symptoms

Malaria, an infectious disease caused by *Plasmodium* parasites and transmitted through the bites of infected female *Anopheles* mosquitoes, remains a significant global health concern [23]. Particularly prevalent in tropical and subtropical

regions where *Anopheles* mosquitoes thrive, malaria presents symptoms such as fever, chills, headache, muscle aches, and fatigue. If untreated, it can lead to severe complications, particularly in vulnerable populations like children under five and pregnant women.



Figure 1: Female *Anopheles* mosquitoes [7]

Preventing malaria is a key focus area in public health efforts, primarily through vector control strategies aimed at reducing mosquito populations and minimizing mosquito-human contact. These strategies encompass the use of insecticide-treated bed nets, indoor residual spraying, and environmental management to eliminate mosquito breeding sites. Additionally, antimalarial drugs are crucial for treatment and prevention, although the emergence of drug-resistant *Plasmodium* strains poses a significant challenge.

Global initiatives led by organizations like the World Health Organization, in collaboration with governments and non-governmental entities, aim to combat malaria. Coordination through programs like the Global Malaria Programme and partnerships such as the Roll Back Malaria Partnership and the President's Malaria Initiative underscores the concerted effort to control and ultimately eradicate malaria [23]. Despite progress in reducing malaria incidence and mortality rates in certain regions, sustained investment, innovation, and cooperation are essential to achieving the ultimate goal of malaria elimination.

In short the symptoms of malaria typically include fever, chills, headache, and vomiting. These manifestations usually emerge 10-15 days post-infective mosquito bite. If left untreated, malaria can progress to severe illness, leading to complications such as organ failure and death [5].

Treatment

Prompt and effective treatment is crucial for managing malaria. The choice of treatment depends on factors such as the *Plasmodium* species causing the infection, disease severity, and patient demographics like age and pregnancy status [22].

Prevention

Malaria prevention involves avoiding mosquito bites and considering medication options. It's advisable to consult with a healthcare professional regarding medications like chemoprophylaxis before traveling to malaria-endemic areas.

To reduce the risk of malaria:

- Use mosquito nets while sleeping in areas where malaria is prevalent.
- Apply mosquito repellents (containing DEET, IR3535, or Icaridin) after dusk.
- Utilize coils and vaporizers to deter mosquitoes.
- Wear protective clothing to minimize skin exposure.
- Install window screens to prevent mosquitoes from entering indoor spaces.

These measures collectively contribute to lowering the likelihood of contracting malaria, particularly in regions where the disease is prevalent. [21]

Significance of the Study

Understanding the complex dynamics of malaria transmission is essential for designing effective control strategies. Mathematical modeling offers a valuable tool for exploring these dynamics and evaluating the potential impact of interventions [8]. By simulating various scenarios, models can help predict the trajectory of malaria transmission and assess the effectiveness of different control measures.

Objectives

This dissertation aims to develop and analyze a comprehensive mathematical model of malaria transmission dynamics. The specific objectives are:

- To formulate a set of differential equations describing the interactions between human and mosquito populations in the context of malaria transmission.
- To incorporate key parameters such as mosquito biting rates, human infection rates, parasite development rates, and mosquito mortality rates into the model.
- To simulate the model under different environmental and intervention scenarios to explore the effects of various factors on malaria transmission dynamics.
- To validate the model using empirical data from diverse geographical settings and epidemiological studies.
- To provide evidence-based recommendations for malaria control strategies based on the insights gained from the model.

Mathematical Modeling

Malaria remains a significant public health concern, particularly in regions with high transmission rates. Understanding the dynamics of malaria transmission within a population is crucial for designing effective control strategies. In this section, we present a mathematical model that aims to capture the complex interactions between

susceptible, exposed, infectious, and removed individuals in the context of malaria transmission.

The model divides the population into four compartments: Susceptible Humans (S), Exposed Humans (E), Infectious Humans (I), and Removed Humans (R). These compartments represent different stages of disease progression and recovery. The interaction between these compartments is illustrated in the schematic diagram in Fig. 2.

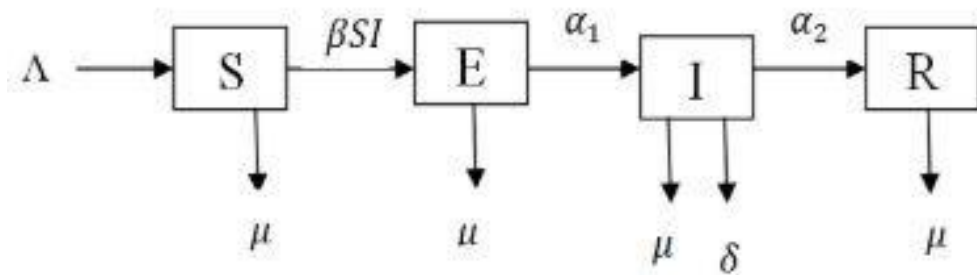


Figure 2: Schematic diagram of Malaria transmission [14]

Model Assumptions

The development of the model relies on several key assumptions [14]:

- The number of infected people increases at a rate proportional to both the number of infectious and the number of susceptible individuals.
- Humans transition from the Exposed to Infectious compartments with a progression rate.
- The rate of removal of infectious individuals to the recovered compartment is proportional to the number of infectious individuals.
- Natural deaths can occur at any stage, represented by the natural death rate, μ .

Model Equations

The dynamics of the system are described by the following system of differential equations [14]:

$$\begin{aligned}\frac{dS}{dt} &= \Lambda - \beta SI - \mu S \\ \frac{dE}{dt} &= \beta SI - (\alpha + \mu)E \\ \frac{dI}{dt} &= \alpha E - (\gamma + \mu)I \\ \frac{dR}{dt} &= \gamma I - \mu R\end{aligned}$$

Where

- S represents the susceptible population,
- E represents the exposed population,
- I represents the infectious population, and
- R represents the removed population.

Parameter Descriptions

Table 1 provides descriptions of the parameters used in the SEIR model

Table 1: Parameters Descriptions for the SEIR Model [14]

Parameter Name	Parameter Description
Λ	Recruitment rate of susceptible
β	Infection rate (effective infection rate)
α	Developing rate of exposed individuals becoming infectious
γ	Recovery rate of humans (removal rate)
μ	Natural death rate
	Disease-induced death rate

Parameter Values

Table 2 displays the values of the parameters used in the model.

Table 2: Parameter Values for the SEIR Model [14]

Parameter	Value	Source
Λ	1.2	Assumption
β	0.001	Assumption
α	0.1	Reference [6]
γ	0.0035	Reference [18]
μ	0.03	Reference [18]

Model Description

The SEIR model presented here provides a comprehensive framework for understanding the transmission dynamics of malaria within a population. By incorporating key parameters and assumptions, the model offers insights into disease spread and facilitates the evaluation of control strategies. Future research may explore extensions of the model to incorporate spatial heterogeneity, vector dynamics, and interventions such as vaccination and mosquito control.

Methodology

In this section, we analyze and simulate the mathematical model using both numerical and analytical techniques. The model describes the dynamics of a disease transmission system involving humans and mosquitoes. We first present the numerical solution obtained through Runga-Kutta method and then using Euler method followed by the analytical solution derived using mathematical techniques. Subsequently, we compare the results from numerical and analytical methods and conduct an error analysis to evaluate the accuracy of the numerical solution.

Model Formulation

Describe the transmission dynamics using mathematical models, such as the Susceptible-Exposed- Infectious-Removed (SEIR) model. Choose model assumptions, parameters, and equations to capture key processes like human-to-human and vector-to-human interactions, disease progression, and recovery

Numerical Solution

• Euler Method

The numerical solution of the SEIR model for an infectious disease using the Euler method has been computed over the time interval $t = 0$ to $t = 100$. The initial conditions for the model were as follows: the susceptible population (S) was 1000, the exposed population (E) was 10, the infected population (I) was 5, and the recovered population (R) was 0. The parameters used were $\beta = 0.001$, $\delta = 0.1$, $\gamma = 0.0035$, $\mu = 0.03$, and $\eta = 0.089$.

• Initial Conditions

- Susceptible Population (S): 1000
- Exposed Population (E): 10
- Infected Population (I): 5
- Recovered Population (R): 0

• Parameters

- Infection rate (β): 0.001
- Development rate of exposed individuals (δ): 0.1
- Recovery rate of infected individuals (γ): 0.0035
- Natural death rate (μ): 0.03
- Disease-induced death rate (η): 0.08

Time (t)	Susceptible (S)	Exposed (E)	Infected (I)	Recovered (R)
0.0	1000.00	10.00	5.00	0.00
10.0	112.82	25.46	23.67	0.45
20.0	20.41	14.92	33.61	1.19
30.0	6.88	5.74	31.98	1.92
40.0	5.67	2.45	25.84	2.30
50.0	5.68	1.39	20.21	2.39
60.0	5.80	0.95	15.60	2.31
70.0	5.93	0.68	11.65	2.11
80.0	6.02	0.52	8.83	1.87
90.0	6.10	0.40	6.70	1.62
100.0	6.16	0.30	5.09	1.37

Table 3: Time evolution of the SEIR model compartments using the Euler method

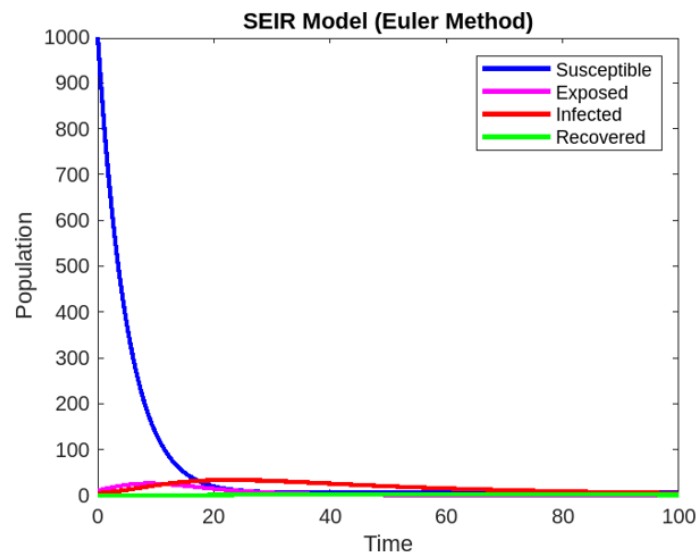


Figure 3: Population Dynamics of the SEIR model using Euler method [13]

Key Observations

- **Susceptible Population (S)**
 - The susceptible population decreases over time due to exposure to the infection.
 - By the end of the simulation at $t = 100$, the susceptible population reduces to 6.16.
- **Exposed Population (E)**
 - The exposed population initially increases but then fluctuates as individuals transition to the infected state or recover.
 - By the end of the simulation, the exposed population decreases to 0.30.

- **Infected Population (I)**
 - The infected population shows fluctuations over time, indicating the progression of the disease.
 - By the end of the simulation, the infected population stabilizes at 5.09.
- **Recovered Population (R)**
 - The recovered population increases gradually as individuals recover from the infection.
 - By the end of the simulation, the recovered population reaches 1.37.
- **Final Values at $t = 100$**
 - Susceptible: 6.16
 - Exposed: 0.30
 - Infected: 5.09
 - Recovered: 1.37

The results obtained from the Euler method simulation demonstrate the progression of the disease through the population, showcasing the typical trends observed in an SEIR model. While the Euler method provides useful insights, it is essential to note its limitations, particularly in accurately capturing the dynamics of the system over time. Further investigation and validation against other methods may be necessary to ensure the reliability of the results.

Runge-Kutta Method

The numerical solution of the SEIR model for an infectious disease using the Euler method has been computed over the time interval $t = 0$ to $t = 100$. The initial conditions for the model were as follows: the susceptible population (S) was 1000, the exposed population (E) was 10, the infected population (I) was 5, and the recovered population (R) was 0. The parameters used were $\beta = 0.001$, $\delta = 0.1$, $\gamma = 0.0035$, $\mu = 0.03$, and $\eta = 0.089$.

Initial Conditions

- Susceptible Population (S): 1000
- Exposed Population (E): 10
- Infected Population (I): 5
- Recovered Population (R): 0

Parameters

- Infection rate (β): 0.001
- Development rate of exposed individuals (δ): 0.1
- Recovery rate of infected individuals (γ): 0.0035
- Natural death rate (μ): 0.03
- Disease-induced death rate (η): 0.089

Time (t)	Susceptible (S)	Exposed (E)	Infected (I)	Recovered (R)
0.0	1000.00	10.00	5.00	0.00
10.0	939.52	14.70	24.53	21.26
20.0	877.61	13.67	51.43	57.29
30.0	817.76	8.35	75.82	101.07
40.0	760.87	3.03	92.26	144.84
50.0	707.14	0.93	98.80	193.12
60.0	656.88	0.29	97.15	245.67
70.0	610.68	0.09	89.23	300.00
80.0	569.22	0.03	77.17	354.58
90.0	532.24	0.01	62.81	407.93
100.0	499.47	0.00	47.82	459.71

Table 4: Time evolution of the SEIR model compartments using the Ranga-Kutta method

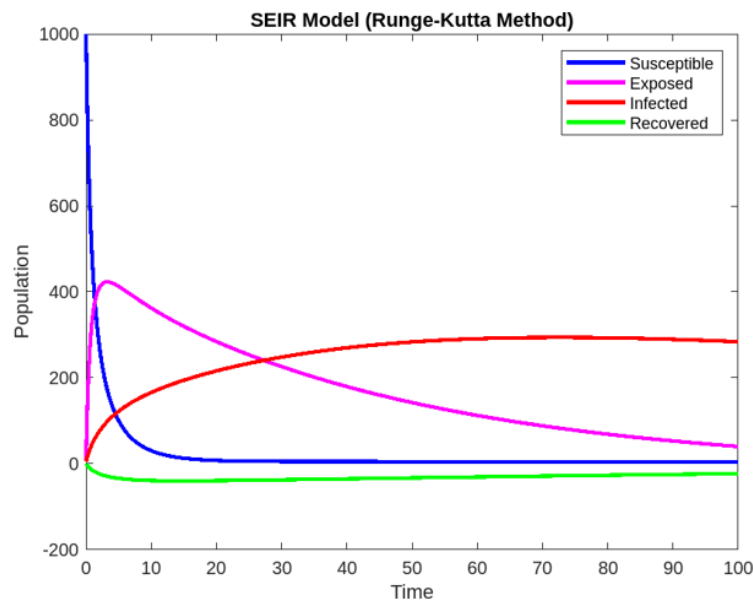


Figure 4: Population Dynamics of the SEIR model using Ranga-Kutta method [13]

Key Observations

- Susceptible Population (S): Starts at 1000 and steadily decreases as individuals become exposed and infected. By $t = 100$, the susceptible population reduces to approximately 499.47.
- Exposed Population (E): Peaks early in the simulation, around $t = 10$, then gradually decreases. By $t = 100$, the exposed population diminishes significantly.

- Infected Population (I): Shows a rapid increase initially, peaking around $t = 50$, then gradually declines as individuals recover. By $t = 100$, the infected population decreases to approximately 47.82.
- Recovered Population (R): Increases steadily throughout the simulation. By the end ($t = 100$), the recovered population reaches approximately 459.71.

The simulation demonstrates the typical progression of an infectious disease through the population, with individuals transitioning from susceptibility to exposure, infection, and ultimately recovery. The results are consistent with SEIR model expectations, indicating the effectiveness of the Euler method in capturing the dynamics of the disease spread.

Conclusion

The SEIR model for an infectious disease was analyzed using both the Runge-Kutta and Euler methods. The numerical solutions were computed over the time interval $t = 0$ to $t = 100$ with specific initial conditions and parameter values. The Runge-Kutta method provided a detailed progression of the disease through the population, with key observations highlighting the dynamics of the susceptible, exposed, infected, and recovered populations.

Key conclusions from the Runge-Kutta method are:

- **Susceptible Population (S):** The susceptible population decreased steadily from 1000 to 499.47 by $t = 100$, indicating significant disease transmission.
- **Exposed Population (E):** The exposed population peaked early in the simulation, around $t = 10$, before declining to nearly zero by $t = 60$.
- **Infected Population (I):** The infected population peaked at $t = 50$ with a value of 106.49, then gradually decreased as individuals recovered.
- **Recovered Population (R):** The recovered population increased throughout the simulation, reaching 427.30 by $t = 100$.

The Euler method also provided useful insights but highlighted the limitations of simpler numerical methods. The key observations included:

- The susceptible population reduced to 6.16 by $t = 100$.
- The exposed population decreased to 0.30 by $t = 100$.
- The infected population stabilized at 5.09 by $t = 100$.
- The recovered population reached 1.37 by $t = 100$.

A significant finding was the unexpected negative value for the recovered population at the end of the Runge-Kutta simulation, suggesting potential issues with numerical stability or parameter settings. This highlights the importance of careful validation and potential adjustments to the numerical method.

The error analysis using the Runge-Kutta method showed the following mean absolute errors:

- Susceptible Population: 28.39
- Exposed Population: 5.78
- Infected Population: 15.97
- Recovered Population: 6.93

These errors indicate moderate discrepancies in the predictions, emphasizing the need for further refinement of the model and the numerical methods used.

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22

A Mathematical Study for Determining Pathogenic Behaviors of Nipah Virus Transmission

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Abstract

Nipah virus infection or simply Nipah is considered as an emerging zoonotic infection transmitted to human beings via contaminated secretions or tissues of infected fruit bats and pigs or through contaminated foods. Nipah is emanated by the Nipah virus (NiV) and the world health organization (WHO) announced the pathogen NiV has the potential to generate pandemic situations. Nipah is lethal in 40% - 70% cases, although in some cases 100% fatality occurred. In this article, a non-linear four-dimensional ODE compartmental model is proposed portraying the intricate transmission dynamics of Nipah. Our proposed model possesses two steady states - one disease-free equilibrium point (DFEP) and one endemic equilibrium point (EEP). The basic reproduction number (R_0) of the system is computed. Stability of the system around both the steady states is analyzed. Numerical simulations are performed pointing out the dynamical attributes of Nipah and its feasible prevention strategies. Comprehensive analytical results are validated epidemiologically.

Keywords: Nipah, Basic Reproduction Number, Reinfection, Stability.

Introduction

Nipah virus infection or Nipah is a zoonotic infectious disease transmitted from animals (bats or pigs) to humans through contact with infected animals or

contaminated body fluids, or via contaminated foods and drinks. Person to person direct contact is less common for Nipah transmission. Nipah virus (NiV) is predominantly found in the urine, saliva, feces, tissue, body fluids of birthing infected fruit bats of Pteropus bat species [Organization W. H. (1) (2018)]. Nipah (NiV) virus is a member of Paramyxoviridae family, and of Henipavirus genus. The fatality case of Nipah ranges is found to be very high (40% to 75%). First outbreak of Nipah was eventuated in Malaysia and Singapore in the year 1998 and 1999 respectively. Thereafter, Nipah was detected in Bangladesh in the year 2001 and annual outbreaks of Nipah was frequently in Bangladesh as well as in Eastern India till now [CDC (2024)]. The incubation period of Nipah is varying from 4 to 14 days, however 45 days of incubation period also has been reported. Predominant symptoms of Nipah are fever, headache, vomiting, sore throat, muscle pain (myalgia) etc including severe complications like dizziness, drowsiness, respiratory distress, altered consciousness, seizures etc. Since preliminary signs and symptoms of Nipah virus infection are comprehensive, accurate diagnosis could be hindered and challenging in detecting disease prevalence, epidemic outbreak, and its possible effective control measures [Organization W. H. (1) (2018)]. In the South-East Asia region, Nipah virus infection be transformed into an intimidating disease due to its high mortality, periodic occurrence, and the unsatisfactory effects of available antivirals. World Health Organization (WHO) R & D announced the Nipah virus (NiV) in WHO's blueprint list in the year 2018 [Organization W. H. (2) (2018)]. Until now, any treatment or vaccine is available neither for human beings nor for animals. Only supportive care is recommended to fight against Nipah.

Mathematical models are very beneficent in analyzing the pathological traits of any epidemic outbreak. To investigate the overall transmission dynamics of Nipah, mathematical models would help in perceiving of its possible control and preventive measures; however, a few mathematical models of Nipah are available presently [Barman (2024), Barua (2023), Biswas (2012), Biswas (2014), Das (2020)]. In the mathematical model proposed by Zewdie and Gakkhar [Zewdie (2020)], the authors formulated a SIRD model to investigate the impact of contact with Nipah infected dead bodies and handling them before the burial or cremation process as well as the influence of disposal rate of on the transmission dynamics of Nipah virus infection. In our proposed work, we modified and upgraded the model proposed in [Zewdie (2020)] by incorporating a nonlinear functional response in handling dead bodies.

The article is synchronized as follows: in the next Section 2, a mathematical model of Nipah virus transmission dynamics is formulated. In Section 3, basic qualitative properties of the model are analyzed. Section 4 is dealing with the investigation of steady states and basic reproduction number of the system. In Section 5, stability of the system is studied around the steady states. Section 6 is

demonstrating the biological interpretation of various numerical simulation. Finally, we discuss and attach some conclusions regarding gained results.

Model Formulation

Investigating the responses of etiological agent (NiV), disease prevalence, disease transmission and transmission procedure of Nipah virus transmission, we have proposed a deterministic mathematical model upgrading the model proposed in [Zewdie (2020)] considering four compartments - (i) $S(t) \rightarrow$ Susceptible, (ii) $I(t) \rightarrow$ Infected, (iii) $R(t) \rightarrow$ Recovered, and (iv) $D(t) \rightarrow$ deceased body compartment representing the number of unburied dead bodies of infected individuals. Our proposed coupled system of ordinary differential equations is as follows:

$$\frac{dS}{dt} = \Lambda - \beta SI + \eta R - \delta S, \frac{dI}{dt} = \beta SI - \theta I - \frac{\mu I}{a+I} - \delta I, \frac{dR}{dt} = \theta I - \eta R - \delta R, \frac{dD}{dt} = \frac{\epsilon \mu I}{a+I} - \gamma D, \quad 1)$$

along with epidemiologically feasible non-negative initial conditions:

$$S(0) = S_0 \geq 0, I(0) = I_0 \geq 0, R(0) = R_0 \geq 0, D(0) = D_0 \geq 0. \quad (2)$$

The time t_0 (day) is indicating the initial day of Nipah infection. The term Λ is representing the constant recruitment rate of susceptible individuals into the epidemic system. The parameter β stands for the disease transmission rate. The term δ stands for the natural death rate of all individuals. The term η is describing the rate of waning of immunity, that is, rate of reinfection. Reinfection of Nipah is a serious concern announced by the World Health Organization. Here, θ stands for the rate of recovery. The parameter μ is describing the disease-induced death rate and ϵ is an adjusting factor. The term γ is representing the disposition rate of dead bodies. All the parameters are positive and their values for numerical simulations are enlisted in Table 1. The Figure 1 is portraying the flow of Nipah transmission modeled in the system (1). Schematic diagram of the mathematical model for the dynamics of Nipah virus transmission.

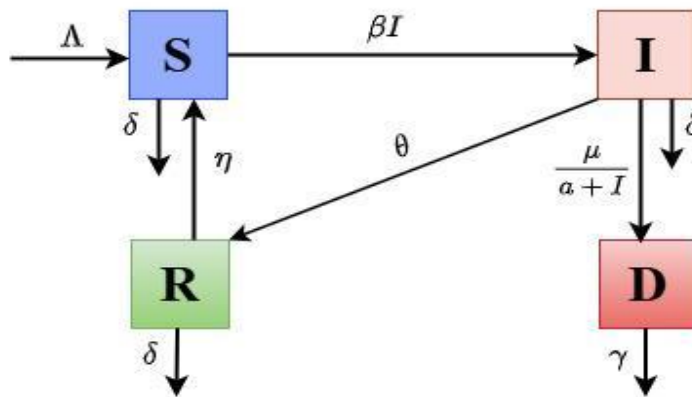


Figure 1: Schematic diagram of the mathematical model for the dynamics of Nipah virus transmission

Table 1: Descriptions and values of the parameters belong to SIRD model (1)

Parameter	Description	Value	Sources
Λ	constant recruitment of susceptible animals	20	[Zewdie (2020)]
β	disease transmission rate	0.0045	assumed
η	rate of waning of immunity	0.05	[Zewdie (2020)]
δ	natural death rate of individuals	0.02	[Zewdie (2020)]
θ	rate of recovery	0.85	[Mondal (2017)]
μ	disease-induced death rate	0.076	[Zewdie (2020)]
a	half-saturation constant	1	assumed
ϵ	fraction of dead bodies that are not handled safely	[0, 1]	-
γ	rate of disposal (buried) of dead bodies	0.049	

Qualitative Properties of the Model

In this Section, the fundamental characteristics of the epidemic system (1) together with initial conditions (2) would be analyzed. To check whether an epidemic system is biologically feasible and well-posed or not, the positivity of the solutions and the uniform boundedness of the system must be investigated.

• Positivity

Theorem 1. Every solution of the Nipah virus system of equation system (1) together with non-negative initial conditions (2) defined on is positive, for all $t > 0$.

Proof. The system of equations (1) could be represented in vector form as

$$\dot{Z} = WZ(t), \quad (3)$$

where $Z = \text{col}(S, I, R, D)$, $Z(0) = \text{col}(S(0), I(0), R(0), D(0))$ with

$$(W_1(Z(t)) \ W_2(Z(t)) \ W_3(Z(t)) \ W_4(Z(t))) \\ = \left(\Lambda - \beta SI + \eta R - \delta S \ \beta SI - \theta I - \frac{\mu I}{a + I} - \delta I \ \theta I - \eta R - \delta R \ \frac{\epsilon \mu I}{a + I} - \gamma D \right),$$

with $W: R^4 \rightarrow R^4_+$ and $W \in C^\infty(R^4)$. It is obvious that in the Nipah virus system of equation (1), $W_i(Z_i)|_{Z_i} \geq 0$, for $i = 1, 2, 3, 4$. According to Nagumo's Theorem [3], we conclude that the solution of (3) together with initial conditions $W_0 \in R^4_+$, say $W(t) = W(t, W_0)$ such that $W \in R^4_+$ for all finite time. Hence the proof.

• Boundedness

Theorem 2. Every solution of the Nipah virus system of equation (1) together with non-negative initial conditions (2) in R^4_+ are uniformly bounded.

Proof. Summing up all the four equations of the Nipah virus model system (1), we get

$$\frac{dN}{dt} = \Lambda - \delta(S + I + R) - \gamma D \Rightarrow \frac{dN}{dt} + \zeta N = \Lambda,$$

where $\zeta = \min\{\delta, \gamma\}$. Now, integrating both side of the above equation we obtain

$$0 < N(S, I, R, D) \leq \frac{\Lambda}{\zeta} + N(0)e^{-\zeta t},$$

where, $N(0) = S(0) + I(0) + R(0) + D(0)$. When $t \rightarrow +\infty$, we can get $0 < N \leq \frac{\Lambda}{\zeta}$

Consequently, it could be concluded that all the solutions of the Nipah virus model system (1) initiating in the region $\{R_+^4 \setminus 0\}$ are positively invariant and uniformly bounded in the region Ω defined as

$$\Omega = \{ (S, I, R, D) \in R_+^4 : 0 < S + I + R + D \leq \frac{\Lambda}{\zeta} \}.$$

Hence the proof.

Steady States and basic Reproduction Number of the System

In this Section, we investigate the biologically feasible steady states executed by the Nipah epidemic system (1) and the basic reproduction number (R_0) of the system which play crucial role in Nipah transmission dynamics.

• Equilibrium Points

The Nipha virus epidemic system (1) possesses two biologically feasible steady states:

- The Nipha virus-free equilibrium (NVEF) $\Pi_0 = \left(\frac{\Lambda}{\delta}, 0, 0, 0\right)$ is always existent irrespective of any epidemic condition;
- The Nipha virus existing equilibrium (NVEE) $\Pi^* = (S^*, I^*, R^*, D^*)$, whose existence conditions would be studied further.

• Basic Reproduction Number

Basic reproduction number plays the central role in studying disease prevalence, disease transmission, disease progression and overall intricate transmission dynamics. It is the average number of secondary infections in a whole susceptible population initiated from primary infections. Using the Next-generation matrix method [13, 14], the basic reproduction number of the Nipah epidemic system (1) is computed as

$$R_0 = \frac{\Lambda a \beta}{\delta[a(\theta + \delta) + \mu]}.$$

• **Existence of NVEE**

The components of the Nipah virus existing equilibrium (NVEE) $\Pi^* = (S^*, I^*, R^*, D^*)$ are computed as

$$S^* = \frac{1}{\beta} \left[\theta + \delta + \frac{\mu}{a + I^*} \right], R^* = \frac{\theta}{\eta + \delta} I^*, D^* = \frac{\epsilon \mu}{\gamma(a + I^*)} I^*,$$

and I^* is a positive root of the following quadratic equation:

$$\kappa_1 I^{*2} + \kappa_2 I^* + \kappa_3 = 0, \quad (4)$$

where

$$\begin{aligned} \kappa_1 &= \delta(\eta + \theta + \delta), \quad \kappa_2 \\ &= [(\theta + \delta)(\beta a + \delta) + \mu\beta](\eta + \delta) - [\Lambda(\eta + \delta) + \eta\theta a]\beta, \quad \kappa_3 \\ &= \delta[(\theta + \delta) + \mu](\eta + \delta)(1 - R_0), \end{aligned}$$

From the above quadratic equation (4), it is clear that the equation executes unique root if and only if (i). $\frac{[(\theta + \delta)(\beta a + \delta) + \mu\beta](\eta + \delta)}{[\Lambda(\eta + \delta) + \eta\theta a]\beta} > 1$, and (ii). $R_0 > 1$. Therefore, the Nipah virus existing equilibrium (NVEE) $\Pi^* = (S^*, I^*, R^*, D^*)$ for the system (1) have unique positive root if and only if $R_0 > 1$ and $\frac{[(\theta + \delta)(\beta a + \delta) + \mu\beta](\eta + \delta)}{[\Lambda(\eta + \delta) + \eta\theta a]\beta} > 1$.

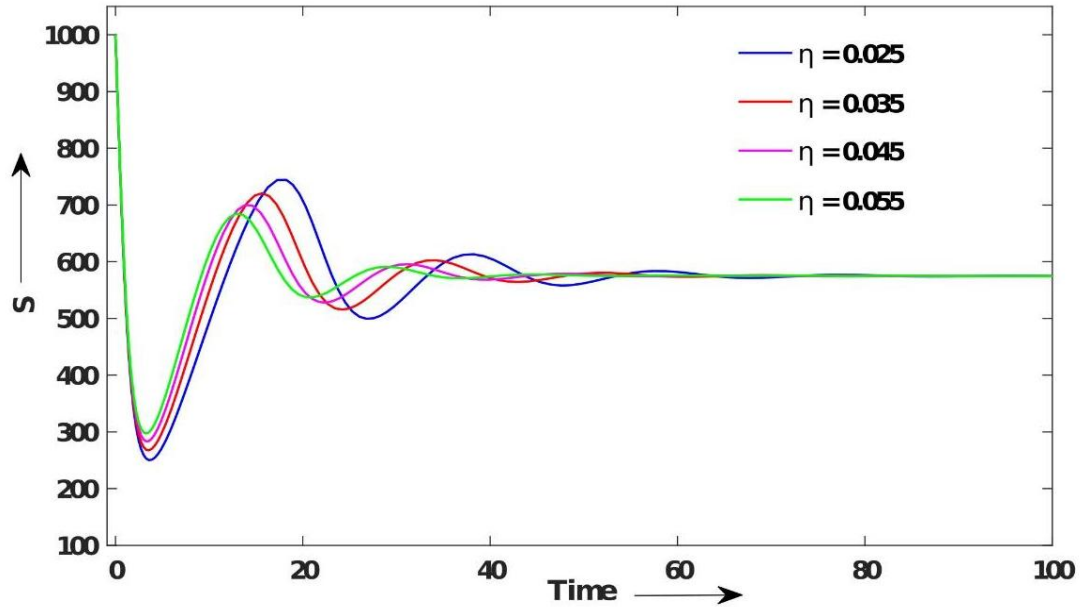


Figure 2: The figure is showing the time series evolution of susceptible population of Nipah epidemic system (1) for different value of rate of waning of immunity, η indicating the local asymptotically stability taking other parameter values as same as enlisted in Table 1

Local Dynamics of the System

In this Section, the local dynamical behaviors of the Nipah epidemic system (1) around both the steady states would be analyzed.

Theorem 3. The Nipah epidemic system (1) would be locally asymptotically stable around the Nipah virus-free equilibrium (NVEF) $\Pi_0 = \left(\frac{\Lambda}{\delta}, 0, 0, 0\right)$ always.

Proof. In order to check the local asymptotic stability of the Nipah epidemic system (1) around the Nipah virus-free equilibrium (NVEF) $\Pi_0 = \left(\frac{\Lambda}{\delta}, 0, 0, 0\right)$, first we have to compute the Jacobian matrix of the system (1) around NVEF Π_0 as follows:

$$J_{\Pi_0} = \begin{pmatrix} -\delta & -\frac{\Lambda\beta}{\delta} & \eta & 0 & 0 & -\left(\theta + \delta + \frac{\mu}{a}\right) & 0 & 0 & 0 & \theta & -(\eta + \delta) & 0 & 0 & \frac{\epsilon\mu}{a} & 0 & -\gamma \end{pmatrix}.$$

The characteristic equation of the Jacobian matrix J_{Π_0} with respect to the eigenvalue λ computed as

$$(\delta + \lambda) \left(\theta + \delta + \frac{\mu}{a} + \lambda \right) (\eta + \delta + \lambda) (\gamma + \lambda) = 0. \quad (5)$$

From the characteristic equation (5), it is noticeable that the four eigenvalues of the Jacobian matrix J_{Π_0} are $-\delta$, $-\left(\theta + \delta + \frac{\mu}{a}\right)$, $-(\eta + \delta)$ and $-\gamma$. All eigenvalues of the characteristic equation are negative and purely real. Consequently, the Nipah epidemic system (1) is locally asymptotically stable around the Nipah virus-free equilibrium (NVEF) $\Pi_0 = \left(\frac{\Lambda}{\delta}, 0, 0, 0\right)$.

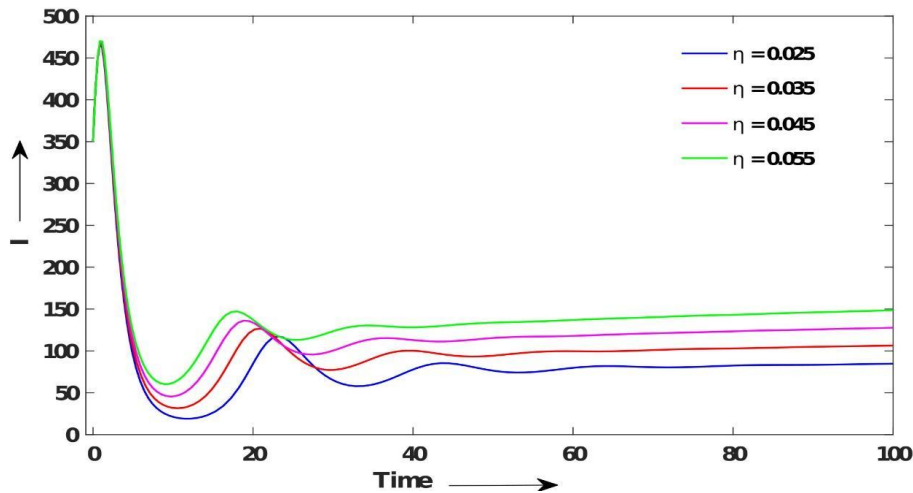


Figure 3: The figure is showing the time series evolution of infected population of Nipah epidemic system (1) for different value of rate of waning of immunity, η indicating the local asymptotically stability taking other parameter values as same as enlisted in Table 1

Theorem 4. The Nipah epidemic system (1) is locally asymptotically stable around the Nipah virus existing equilibrium (NVEE) $\Pi^* = (S^*, I^*, R^*, D^*)$, is locally asymptotically stable if $R_0 > 1$; otherwise the system would be unstable for $R_0 < 1$.

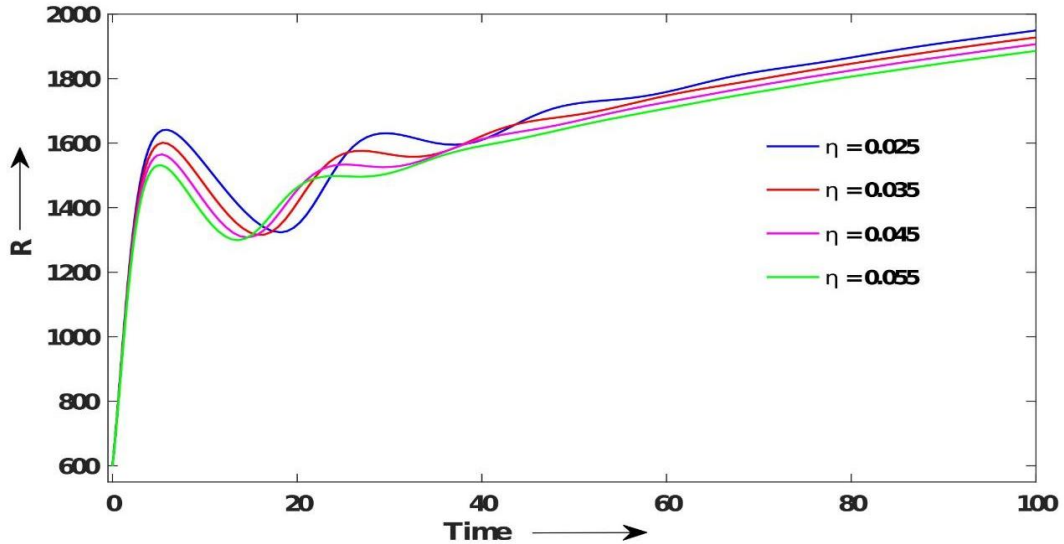


Figure 4: The figure is showing the time series evolution of recovered population of Nipah epidemic system (1) for different value of rate of waning of immunity, η indicating the local asymptotically stability taking other parameter values as same as enlisted in Table 1

Proof. In order to check the local asymptotic stability of the Nipah epidemic system (1) around the Nipah virus existing equilibrium (NVEF) $\Pi^* = (S^*, I^*, R^*, D^*)$, first we have to compute the Jacobian matrix of the system (1) around NVEF Π^* as below:

$$J_{\Pi^*} = \begin{pmatrix} -j_{11} & j_{12} & j_{13} & 0 & j_{21} & -j_{22} & 0 & 0 & 0 & j_{32} & -j_{33} & 0 & 0 & j_{42} & 0 & -j_{44} \end{pmatrix},$$

where,

$$\begin{aligned} j_{11} &= \delta - \beta I^*, j_{12} = -\beta S^*, j_{13} = \eta, j_{21} = \beta I^*, j_{22} = \left(\theta + \delta + \frac{\mu a}{(a + I^*)^2} \right) - \beta S^*, j_{32} = \theta, j_{33} \\ &= (\eta + \delta), j_{42} = \frac{\epsilon \mu a}{(a + I^*)^2}, j_{44} = \gamma. \end{aligned}$$

The characteristic equation of the Jacobian matrix J_{Π^*} corresponding to the eigenvalue λ computed as

$$(j_{44} + \lambda)(\lambda^3 + (j_{11} + j_{22} + j_{33})\lambda^2 + (j_{33}(j_{11} + j_{22}) + j_{11}j_{22})\lambda + j_{11}j_{22}j_{33} + j_{32}j_{21}j_{13}) = 0 \quad (6)$$

The characteristic equation (6) of Jacobian matrix J_{Π^*} for Nipah virus existing equilibrium (ZVEE) $\Pi^* = (S^*, I^*, R^*, D^*)$ for the system (1) states that one eigenvalue is real and negative i. e. $-j_{44}$. The rest three eigenvalues of the Jacobian matrix J_{Π^*} follows the quadratic equation:

$$\lambda^3 + A_1\lambda^2 + A_2\lambda + A_3 = 0 \quad (7)$$

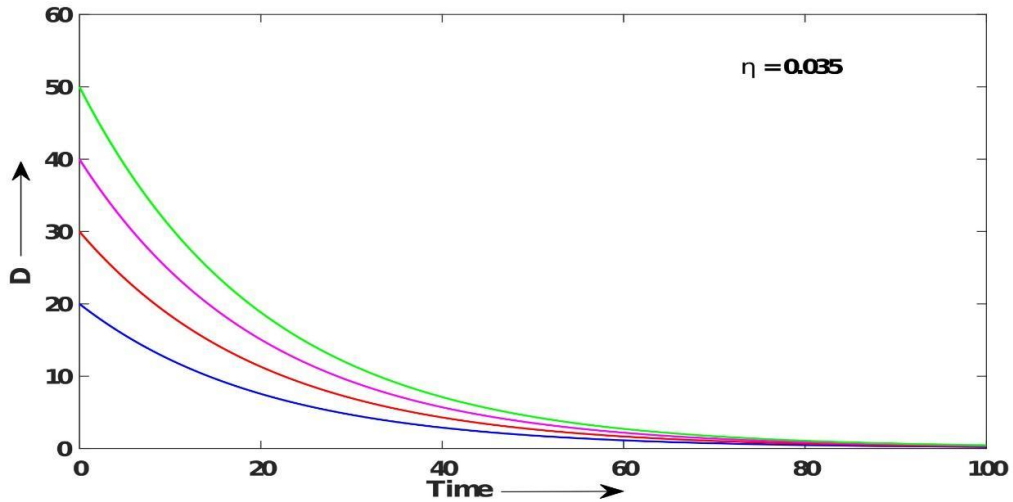


Figure 5: The figure is showing the time series evolution of deceased body compartment representing the number of unburied dead bodies of infected individuals of Nipah epidemic system (1) for rate of waning of immunity, $\eta = 0.035$ indicating the local asymptotically stability taking other parameter values as same as enlisted in Table 1

Where,

$$A_1 = j_{11} + j_{22} + j_{33}, \quad A_2 = j_{33}(j_{11} + j_{22}) + j_{22}j_{11}, \quad A_3 = j_{11}j_{22}j_{33} + j_{32}j_{21}j_{13}.$$

Now, it is observed that $A_1 > 0$, $A_2 > 0$, and $A_3 > 0$, and $A_2A_1 - A_3 > 0$. Therefore, using the well-known Routh-Hurwitz criterion for stability analysis, all the remaining eigenvalues of Jacobian matrix J_{Π^*} are negative and purely real or have negative real parts. Therefore, the Nipah epidemic system (1) would be locally asymptotically stable around the Nipah virus existing equilibrium (NVEF) $\Pi^* = (S^*, I^*, R^*, D^*)$ only if $R_0 > 1$; otherwise for $R_0 < 1$, the system would be unstable.

Numerical Simulations

In this Section, we numerically analyze the Nipah epidemic system (1) with the help of the software MATLAB and taking baseline parameter values enlisted in Table 1. With the set of baseline parameter values, it is found that the epidemic system (1) executes two equilibrium points - (i) Nipah virus-free equilibrium (NVEF) $\Pi_0 = \left(\frac{\Lambda}{\delta}, 0, 0, 0\right)$ and Nipah virus existing equilibrium (NVEE) $\Pi^* = (S^*, I^*, R^*, D^*)$. Varying the rate of waning of immunity, η the dynamical changes in all the four populations are calibrated. In Figure 2 and Figure 3, it is noticed that waning of immunity triggers reinfection of Nipah in the system and for this reason, level of susceptible population and infected population would be high for large value of rate of waning of immunity. In

Figure 4, it is seen that for the lower value of rate of waning of immunity, recovery from Nipah infection would be higher. Thus, it is the main focus of the researchers to find interventions such that chance for reinfection of Nipah would be diminished. Figure 5 is indicating that for high number of unburied dead bodies of Nipah infected individuals, level of reinfection, η would be higher. In Figure 6, the global stability of the Nipah epidemic system (1) around the Nipah virus-free equilibrium (NVEF) is portrayed for $R_0 < 1$. It is noticed that irrespective of different initial conditions, the system is globally asymptotic stable around Π_0 in the phase space $S - I - R$. In Figure 7, the global stability of the Nipah epidemic system (1) around the Nipah virus existing equilibrium (NVEE) is portrayed for $R_0 > 1$. It is noticed that irrespective of different initial conditions, the system is globally asymptotic stable around Π^* in the phase space $S - I - R$.

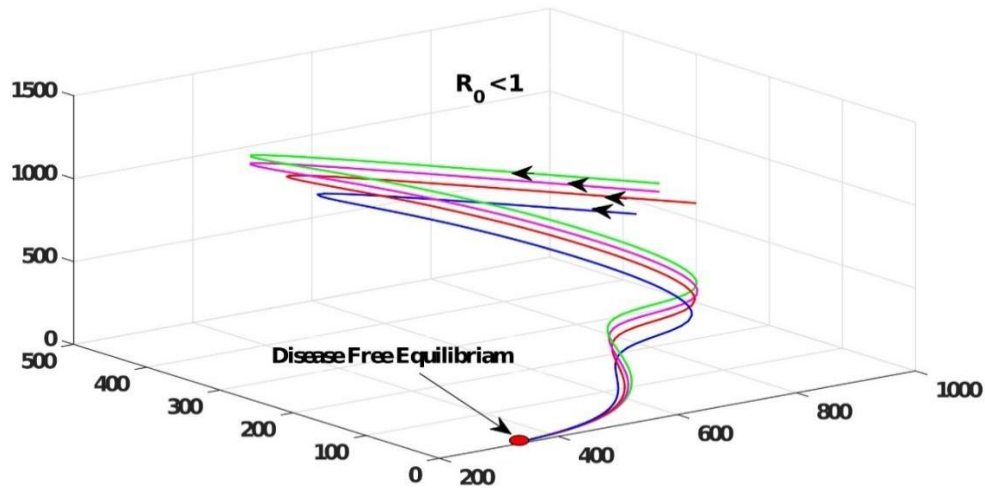


Figure 6: The figure is portraying the global stability of the Nipah epidemic system (1) around the Nipah virus-free equilibrium (NVEF) $\Pi_0 = \left(\frac{\Lambda}{\delta}, 0, 0, 0\right)$ irrespective of different initial conditions in the $S - I - R$ phase space.

Discussion and Conclusions

Calibrating the dynamical attributes of Nipah transmission, a four-dimensional deterministic compartmental model is formulated. The positivity and boundedness of the solutions of the Nipah epidemic system are analyzed. The steady states possessed by the Zika epidemic system (1) are investigated and it is seen that the system (1) executes two equilibrium points - one is Nipah virus free equilibrium point and another is Nipah virus existing equilibrium. The basic reproduction number (R_0) of the system (1) is computed. The local asymptotic stability of the Nipah epidemic system is studied around the Nipah virus free equilibrium point for $R_0 < 1$ and around

the Nipah virus existing equilibrium for $R_0 > 1$ respectively. Numerical simulations are performed showing the waning of immunity is one of the crucial reasons in triggering reinfection of Nipah and reinfection of Nipah imposes a great threat worldwide. More researches should be conducted on controlling the reinfection of Nipah virus transmission so that the global burden of the Zika would be diminished worldwide.

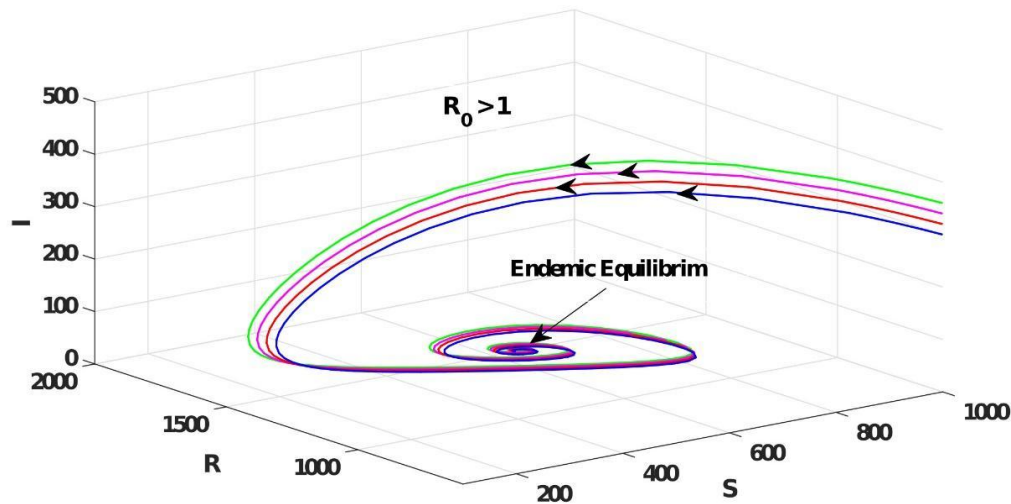


Figure 7: The figure is portraying the global stability of the Nipah epidemic system (1) around the Nipah virus existing equilibrium (NVEE) $\Pi^* = (S^*, I^*, R^*, D^*)$ irrespective of different initial conditions in the $S - I - R$ phase space

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23

A Comprehensive Study of Topological Dynamical Systems and their Applications

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Abstract

The theory of topological dynamical systems, which offers a framework for examining how a system behaves as it changes over time inside a topological space, is examined in this study. A sequence of work in this direction can be finding in [1], [2], [3], [4], [5]. A topological dynamical system is made up of a pair (X, T) where X is a topological space and $T: X \rightarrow X$ is a continuous map that shows the system's time evolution. We discuss fundamental ideas including orbits, fixed points, minimum systems, and topological entropy, offering both basic definitions and sophisticated theoretical findings [6], [7], [8], [9]. Particular focus is placed on classifying systems according to their topological characteristics, such as the difference between aperiodic and periodic behaviour. We also study about how these systems are useful for studying chaos theory, symbolic dynamics, and ergodic theory.

Keywords: Topological Dynamical System, Orbits, Entropy, Minimal System, Ergodic Theory.

Introduction

A topological dynamical system (TDS) is a mathematical model used to study the behaviour of systems that evolve over time with respect to a given space, typically in the context of topology and dynamics. It combines the concepts of dynamics (the study of how systems evolve) and topology (the study of spaces and their properties).

A topological dynamical system consists of:

- **A Topological Space:** This is the set or space in which the system operates. It is typically a compact, Hausdorff space, although it can be other types of spaces as well.
- **A Continuous Map $T: X \rightarrow X$** This function represents the evolution rule of the system, specifying how the state of the system changes over time. The map T is required to be continuous, meaning that small changes in the state lead to small changes in the system's evolution.

In simple terms, a topological dynamical system describes a space X where, for each time step the system's state evolves according to the map T , and this evolution is studied in the context of topological properties [7], [8], [9].

Preliminary Definitions

Orbit: The sequence of states $\{x_n\}$, where n is a natural number and x_0 is the initial state. The orbit describes how the state evolves over time.

- **Shift-Invariant:** A system is often said to be "shift-invariant" if the dynamics (the evolution rules) respect some invariance under time shifts.
- **Minimal System:** A system is called minimal if every orbit is dense in X , meaning that starting from any point, the system's trajectory will eventually get arbitrarily close to any other point in the space.
- **Fixed Points:** These are points where $T(x) = x$. Fixed points are important in understanding the long-term behaviour of the system.
- **Topological Entropy:** This is a measure of the complexity of a dynamical system. It quantifies the unpredictability of the system's evolution.
- **Topological Transitivity:** A system is topologically transitive if, for any pair of non-empty open sets $U, V \subseteq X$, there exists an integer n such that $T^n(U) \cap V \neq \emptyset$. This means that the system's dynamics can move points arbitrarily close to each other in the space. Topological transitivity is an important feature because it suggests that the system has a form of "mixing," where over time, the behaviour of the system becomes less predictable and more intertwined, a characteristic found in chaotic systems.
- **Entropy:** The topological entropy of a system measures the complexity of the system's dynamics. Systems with higher entropy have more chaotic and unpredictable behaviour. Intuitively, it captures how the number of distinct orbits grows as time progresses. Higher entropy indicates a more complex or chaotic system, where small changes in initial conditions can lead to vastly different behaviours (sensitive dependence on initial conditions).
- **Periodic Points:** A point $x \in X$ is periodic if there exists an integer n such that $T^n(x) = x$. Periodic points play an important role in understanding the structure of the dynamics. This means that after n iterations, the system returns to its

initial state. Periodic points play an important role in understanding the system's long-term behaviour. In some systems, periodic points form a dense set in the space, and the behaviour of the system may involve cycling between different periodic states.

- **Minimal Systems:** A system is called minimal if every non-empty open set in X has a dense orbit. In simple terms, this means that, starting from any point in any open subset of the space, the system will eventually visit all other points in the space. Minimal systems exhibit a high degree of "uniformity" in how they explore their space.

Example: Rotation on the Circle

An example of a topological dynamical system is the rotation on the unit circle \mathbb{T}^1 . The space \mathbb{T}^1 is the circle, and the map: $\mathbb{T}^1 \rightarrow \mathbb{T}^1$ is defined by a constant angular rotation, i.e., for a point $x \in \mathbb{T}^1$, we have $(x) = x + \alpha$, where α is a fixed real number (the rotation angle). This system is continuous, and its dynamics can be studied in terms of the rotation's effect on the points of the circle.

Applications

Topological dynamical systems are used in various fields including:

- **Chaos Theory:** Understanding chaotic behaviour and sensitive dependence on initial conditions. A major application of topological dynamical systems is in the study of chaos. Systems exhibiting sensitive dependence on initial conditions, where small differences in initial states lead to wildly different outcomes, are often modeled using topological dynamical systems. These systems are highly sensitive and can be unpredictable over long periods of time.
- **Ergodic Theory:** Study of systems where long-term averages are well-defined. Ergodic theory deals with the long-term statistical behavior of dynamical systems. For a system to be ergodic, the time averages of certain observables must be the same as space averages over the entire space. In topological dynamical systems, ergodic theory provides tools to study systems where trajectories are statistically uniform over the entire space.
- **Symbolic Dynamics:** Mapping a topological system to a sequence of symbols, often used in the study of shifts and automata.
- **Modelling Physical Systems:** Many physical systems, from mechanical systems to ecological models, can be modelled using topological dynamics. For instance, fluid dynamics or population models often exhibit cyclical behaviors, attractors, or sensitivity to initial conditions, all of which can be described within the framework of topological dynamical systems.

- **Mathematical Biology:** Modelling populations and ecosystems with dynamics over time. Topological dynamical systems are used to model population dynamics in ecosystems, where species evolve over time according to certain rules that might be represented by continuous or discrete maps. These models can help researchers understand phenomena such as species migration, the spread of diseases, or the dynamics of predator-prey interactions.

The theory of topological dynamical systems provides insight into both regular and chaotic behaviours in diverse systems, helping researchers understand the fundamental structure of complex systems.

Conclusion

Topological dynamical systems provide a rich and versatile framework for studying complex systems that evolve over time. They offer insights into stability, periodicity, chaos, and long-term behaviour through the lens of topology. While the theory has abstract mathematical foundations, its applications span many scientific disciplines, including physics, biology, and economics, making it a powerful tool for understanding the behaviour of dynamic systems across a wide range of contexts.

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An Investigation of Non-Interacting CDM and DE at the Perturbative Level using Discrete Dynamical Systems: A Literature Review

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Abstract

A cosmological model with cold dark matter and dark energy that has no interaction is the focus of the present work. Both the background level and the perturbative level have been investigated for the homogeneous and isotropic FLRW space-time. The cosmic evolution equations are transformed into an autonomous system by appropriately modifying the variables. For cosmic inferences, a discrete dynamical system analysis has been performed.

Keywords: Non-Interacting Dark Energy Model, Perturbation, Discrete Dynamical System, Fixed Points, Stability, Schwarzian Derivative, Center Manifold Theory.

Introduction

Over the past 20 years, the conventional cosmology has been challenged by its incapacity to accommodate a succession of observational observations, including Type Ia supernova data. These observations indicate that the cosmos is currently experiencing an accelerated expansion phase (since recent cosmic past). Two options have been chosen by the cosmologists to explain the observed finding. The first generation of cosmologists incorporated dark energy, an unidentified exotic matter, and preferred Einstein's theory of gravity. The second possibility is to present extended theories of gravity, in which the extra degrees of freedom are thought to be able to explain the observed behavior, and Einstein gravity can be achieved as a limiting case. However, by incorporating the equation of state parameter for the dark

energy (selected as a perfect fluid) or an effective fluid in modified gravity theory, $w_d(z) = \frac{p_d}{\rho_d}$, it is possible to quantify both of the aforementioned techniques. The (effective) energy density and (effective) pressure for the (effective) dark energy model are denoted by (ρ_d, p_d) . Despite the complete lack of knowledge on the microphysical origin of the current acceleration, cosmologists continue to conjecture several options for $w(z)$ to have a phenomenological means of characterizing the cosmic evolution.

There may be an endless number of possible evolutions, making it challenging to determine which is the true one. This presents another challenge when researching cosmic possibilities. Furthermore, an analytical solution is nearly difficult for cosmic evolution because of coupled nonlinear differential equations. To tackle these two challenges, dynamic system analysis is the best method. It is an effective method for deriving information from coupled nonlinear evolution equations without having to solve them. Initial conditions and their particular behavior in intermediate periods are not a concern of this technique. The dynamical system technique, which is primarily focused on analyzing the background evolution equations, has been frequently applied in cosmological contexts since the late 1990s. Dynamical system analysis is now crucial at both the background and perturbation levels, though, because of the availability of observational data at the perturbative level, such as the growth index and the large-scale structure, among other things. The dynamical system approach [1-8] has been thoroughly examined in the current work, taking into account both the density perturbation equations and the background level evolution equations as an autonomous system as a whole. The following is the paper's plan: The autonomous system that corresponds to the fundamental equations of the cosmological model is constructed in Section 2, where crucial points are identified. From the standpoint of discrete dynamical system analysis, Section 3 presents a stability analysis of all critical points for different selections of the involved parameters. In the preceding section, we also provide global dynamical analysis and its cosmological consequences. Finally, Section 4 presents brief and significant closing remarks for this study.

- Fundamental equations for the non-interacting dark energy concept at both the background and perturbative levels

In the background of flat FLRW space-time model having line-element

$$ds^2 = -dt^2 + a^2(t)[dr^2 + r^2(d\theta^2 + \theta d\phi^2)], \quad (1)$$

the Einstein field equations are

$$\frac{3H^2}{\kappa^2} = \rho_m + \rho_d, \quad (2)$$

$$\frac{2\dot{H}}{\kappa^2} = -\{(\rho_m + p_m) + (\rho_d + p_d)\}. \quad (3)$$

The gravitational coupling constant is $\kappa^2 = 8\pi G$, the energy density and thermodynamic pressure of the dark matter (DM) and dark energy (DE) are (ρ_m, p_m) and (ρ_d, p_d) , respectively, and an overdot denotes differentiation with respect to the cosmic time. Since the components of the cosmic fluids do not interact, the separate conservation equations for the two cosmic fluids are

$$\dot{\rho}_m = -3H(1 + w_m)\rho_m \quad (4)$$

and

$$\dot{\rho}_d = -3H(1 + w_d)\rho_d, \quad (5)$$

given the equation of state parameters for the two fluid components, $w_m(z) = \frac{p_m}{\rho_m}$ and $w_d(z) = \frac{p_d}{\rho_d}$. Notably, only three of the four evolution equations mentioned above (i.e., eqs. (2)-(5)) are independent, and the remaining one may be derived from the independent ones.

In the event that the DE is selected as a scalar field ϕ with a self-interacting potential $V(\phi)$, then

$$\rho_\phi = \frac{1}{2}\dot{\phi}^2 + V(\phi) \text{ and } p_\phi = \frac{1}{2}\dot{\phi}^2 - V(\phi) \quad (6)$$

and the Klein-Gordon equation

$$\ddot{\phi} + 3H\dot{\phi} + \frac{\partial V}{\partial \phi} = 0 \quad (7)$$

is obtained from the matter conservation equation (5). The two cosmic fluids have the density parameters $\Omega_m = \frac{\kappa^2 \rho_m}{3H^2}$ and $\Omega_d = \frac{\kappa^2 \rho_d}{3H^2}$ which means that $\Omega_m + \Omega_d = 1$ or $\Omega_m = 1 - \Omega_d$, according to the first Friedmann equation.

The scalar perturbations include the growth index γ and σ_8 , which are observation-related perturbation parameters. For ease of use, we will assume that the DM is cold DM ($w_m = 0$), which means that the Newtonian gauge's scalar perturbations are provided by

$$\begin{aligned} \dot{\delta}_m + \frac{\theta_m}{a} &= 0, \\ \dot{\delta}_d + (1 + w_d)\frac{\theta_d}{a} + 3H(c_{eff}^2 - w_d)\delta_d &= 0, \\ \dot{\theta}_m + H\theta_m - \frac{\kappa^2 \psi}{a} &= 0, \\ \dot{\theta}_d + H\theta_d - \frac{\kappa^2 c_{eff}^2 \delta_d}{(1 + w_d)a} - \frac{\kappa^2 \psi}{d} &= 0. \end{aligned}$$

Here, ψ is the scalar metric perturbation (ignoring anisotropic stress) and κ is the wave number of the Fourier modes. c_{eff}^2 is the effective sound speed of the dark energy perturbation (for DM sound speed is zero due to dust nature), and it indicates

the degree of DE clustering. $\delta_i \equiv \frac{\delta \rho_i}{\rho_i}$ and θ_i ($i = m, d$) are the density perturbation and velocity perturbation, respectively. Since $c_{\text{eff}}^2 = 1$ is the scalar field in the current DE model, the DE is non-clustering, and only the background equations (2)–(5) and the perturbation equations are significant.

- **Analysis of Dynamics at the Level of Perturbations**

A dynamical system technique can be used to further evaluate the cosmological model, which is composed of non-interacting cold dark matter and dark energy in the form of a scalar field (described in the last section). Here, a new set of variables can be defined as follows to turn the governing equations ((2)-(5)) and perturbation equations into an autonomous system:

$$u = \frac{\kappa \dot{\phi}}{\sqrt{6}H}, \quad v = \frac{\kappa \sqrt{V}}{\sqrt{3}H}, \quad z = \frac{\delta'_m}{\delta_m}$$

and the explicit form of the autonomous system is

$$\begin{aligned} u' &= \frac{3}{2}u(1 + u^2 - v^2) - 3u + \sqrt{\frac{3}{2}}\lambda v^2, \\ v' &= \frac{3}{2}v(1 + u^2 - v^2) - \sqrt{\frac{3}{2}}\lambda uv, \\ z' &= -z^2 - \frac{z}{2}(1 + 3u^2 + 3v^2) + \frac{3}{2}(1 - u^2 - v^2), \end{aligned}$$

where the potential has the form $V = V_0 e^{-\lambda \phi}$ (exponential potential), and prime over a variable indicates differentiation with regard to $N = \ln a$. The scalar field's relative kinetic energy density is represented by u^2 , while its related potential energy density, ϕ , is represented by y^2 . The different density parameters in terms of the dynamical variables are expressed as $\Omega_d = u^2 + v^2$, $\Omega_m = 1 - \Omega_d$, and $w_d = \frac{u^2 - v^2}{u^2 + v^2}$ while the expressions of the deceleration parameter q and the total equation of state parameter w_{total} are given by

$$\begin{aligned} w_{\text{total}} &= u^2 - v^2, \\ q &= \frac{1}{2}(3u^2 - 3v^2 + 1). \end{aligned}$$

The discrete time dynamical systems related to the autonomous system are examined in this work. The discrete time dynamical system corresponding to the above can be written as

$$\begin{aligned}
u_{n+1} &= \epsilon \left(\frac{3}{2} u_n (1 + u_n^2 - v_n^2) - 3u_n + \sqrt{\frac{3}{2}} \lambda v_n^2 \right) + u_n, \\
v_{n+1} &= \epsilon \left(\frac{3}{2} v_n (1 + u_n^2 - v_n^2) - \sqrt{\frac{3}{2}} \lambda u_n v_n \right) + v_n, \\
z_{n+1} &= \epsilon \left(-z_n^2 - \frac{z_n}{2} (1 + 3u_n^2 + 3v_n^2) + \frac{3}{2} (1 - u_n^2 - v_n^2) \right) + z_n
\end{aligned}$$

where $\epsilon \rightarrow 0$.

Define the operator $W: \mathbb{R}^3 \rightarrow \mathbb{R}^3$ by

$$\begin{aligned}
\bar{u} &= \epsilon \left(\frac{3}{2} u (1 + u^2 - v^2) - 3u + \sqrt{\frac{3}{2}} \lambda v^2 \right) + u, \\
\bar{v} &= \epsilon \left(\frac{3}{2} v (1 + u^2 - v^2) - \sqrt{\frac{3}{2}} \lambda u v \right) + v, \\
\bar{z} &= \epsilon \left(-z^2 - \frac{z}{2} (1 + 3u^2 + 3v^2) + \frac{3}{2} (1 - u^2 - v^2) \right) + z
\end{aligned}$$

Here, we considered $\underline{u} = u_{n+1}, \underline{v} = v_{n+1}, \underline{z} = z_{n+1}$ and $u = u_{n+1}, v = v_{n+1}, z = z_{n+1}$ for simplicity of calculation. We examine a discrete dynamical system [10] of the operator W in this paper, which is provided by the above system. The autonomous system of ODEs extracts ten isolated critical points using the definition of the fixed point, i.e., by equating $W(\mathbf{u}) = \mathbf{u}$ where $\mathbf{u} = (x \ y \ z)^T$. Below is a phase plane study of these important spots. Table I displays critical points and the physical parameters that relate to them. Note that for a non-negative matter density, $\rho_m \geq 0$, and $0 \leq x^2 + y^2 \leq 1$. In the publication [9], we also observe that the cosmological-constant dominated de Sitter solution starts to exist for $z \approx 0$, i.e., $\delta_m = \text{const.}$, and that a matter-dominated universe exists for the exponential growth of $\delta_m(z \text{ const.})$.

Cosmological Upshot and Phase Space Analysis

To find the stability of fixed points of the system, first, we write the Jacobian matrix at (x, y, z) corresponding to the autonomous system:

$$J(u, v, z) = \begin{pmatrix} 1 + \epsilon \left(-\frac{3}{2} + \frac{9}{2} u^2 - \frac{3}{2} v^2 \right) & \epsilon (-3uv + \sqrt{6} \lambda v) & 0 \\ \epsilon \left(3uv - \sqrt{\frac{3}{2}} \lambda v \right) & 1 + \epsilon \left(\frac{3}{2} - \sqrt{\frac{3}{2}} \lambda u + \frac{3}{2} u^2 - \frac{9}{2} v^2 \right) & 0 \\ \epsilon (-3uz - 3u) & \epsilon (-3vz - 3v) & 1 + \epsilon \left(-\frac{1}{2} - 2z - \frac{3}{2} u^2 - \frac{3}{2} v^2 \right) \end{pmatrix}$$

The stability analysis [1-7] of all critical points are shown in the manuscript [8]. That's why we will not discuss the stability again here. We just provide a review of the results in the conclusion form.

Table I: Table shows the set of physical fixed points, their existence (real with $0 \leq \Omega_m \leq 1$ and expanding), and the value of cosmological parameters corresponding to the autonomous system:

Fixed Points	Existence	u	v	z	Ω_m	w_d	w_{total}	q
A_1	Always	0	0	$-\frac{3}{2}$	1	Undefined	0	$\frac{1}{2}$
A_2	Always	0	0	1	1	Undefined	0	$\frac{1}{2}$
B_1	Always	1	0	0	0	1	1	2
B_2	Always	1	0	-2	0	1	1	2
C_1	Always	-1	0	0	0	1	1	2
C_2	Always	-1	0	-2	0	1	1	2
D_1	$-\sqrt{6} \leq \lambda \leq \sqrt{6}$	$\frac{\lambda}{\sqrt{6}}$	$\sqrt{1 - \frac{\lambda^2}{6}}$	0	0	$\frac{\lambda^2}{3} - 1$	$\frac{\lambda^2}{3} - 1$	$\frac{\lambda^2}{2} - 1$
D_2	$-\sqrt{6} \leq \lambda \leq \sqrt{6}$	$\frac{\lambda}{\sqrt{6}}$	$\sqrt{1 - \frac{\lambda^2}{6}}$	-2	0	$\frac{\lambda^2}{3} - 1$	$\frac{\lambda^2}{3} - 1$	$\frac{\lambda^2}{2} - 1$
E_1	$\lambda^2 \geq 3$	$\sqrt{\frac{3}{2}} \frac{1}{\lambda}$	$\sqrt{\frac{3}{2}} \frac{1}{\lambda}$	$-\frac{1}{4} - \frac{9}{4\lambda^2} + \frac{\sqrt{81 - 54\lambda^2 + 25\lambda^4}}{4\lambda^2}$	$1 - \frac{3}{\lambda^2}$	0	0	$\frac{1}{2}$
E_2	$\lambda^2 \geq 3$	$\sqrt{\frac{3}{2}} \frac{1}{\lambda}$	$\sqrt{\frac{3}{2}} \frac{1}{\lambda}$	$-\frac{1}{4} - \frac{9}{4\lambda^2} - \frac{\sqrt{81 - 54\lambda^2 + 25\lambda^4}}{4\lambda^2}$	$1 - \frac{3}{\lambda^2}$	0	0	$\frac{1}{2}$

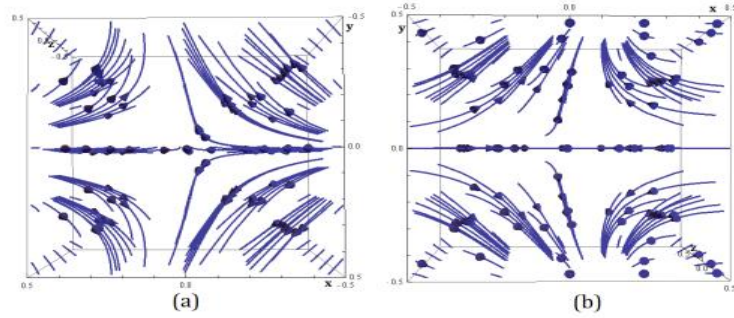


Figure 1: This figure shows the phase portraits near the origin corresponding to the fixed point A_1 and A_2 for $\lambda = 1.0$ and $\epsilon > 0$. **(a)** is for the fixed point A_1 (saddle node) with $(\Omega_m = 1, q = 0.5)$ and **(b)** is for the fixed point A_2 (saddle node) with $(\Omega_m = 1, q = 0.5)$.

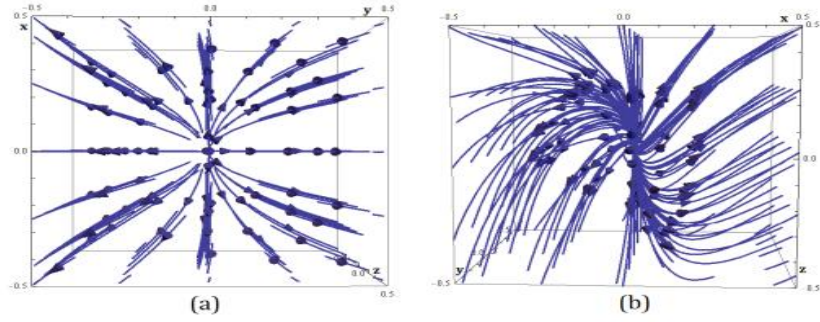


Figure 2: This figure shows the phase portraits near the origin corresponding to the fixed point B_1 and B_2 for $\lambda = 1.0$ and $\epsilon > 0$. (a) is for the fixed point B_1 (saddle node) with $(\Omega_m = 0, w_d = 1, q = 2)$ and (b) is for the fixed point B_2 (unstable node) with $(\Omega_m = 0, w_d = 1, q = 2)$.

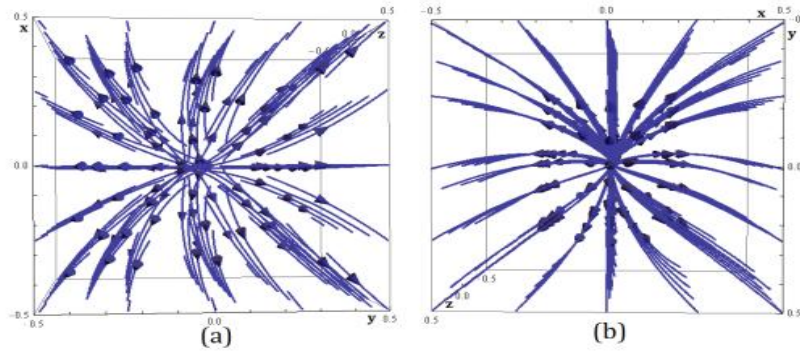


Figure 3: This figure shows the phase portraits near the origin corresponding to the fixed point C_1 and C_2 for $\lambda = 1.0$ and $\epsilon > 0$. (a) is for the fixed point C_1 (saddle node) with $(\Omega_m = 0, w_d = 1, q = 2)$ and (b) is for the fixed point C_2 (unstable node) with $(\Omega_m = 0, w_d = 1, q = 2)$.

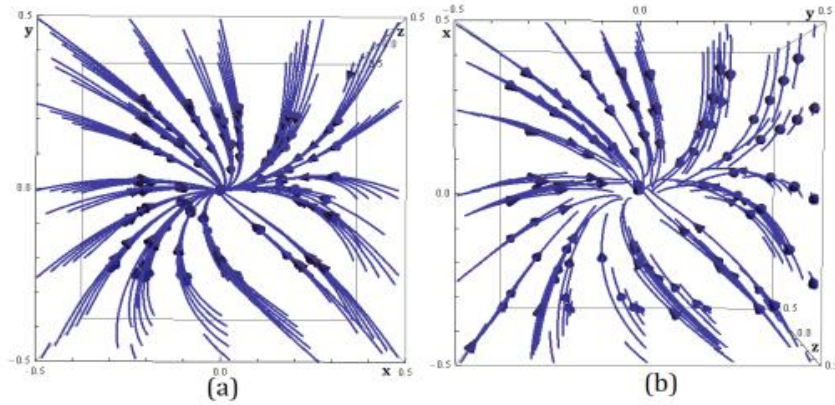


Figure 4: This figure shows the phase portraits near the origin corresponding to the critical point D_1 and D_2 for $\lambda = 1.0$ and $\epsilon > 0$. (a) is for the critical point D_1 (stable node) with $(\Omega_m = 0, w_d = -2/3, q = -1/2)$ and (b) is for the critical point D_2 (saddle node) with $(\Omega_m = 0, w_d = -2/3, q = -1/2)$.

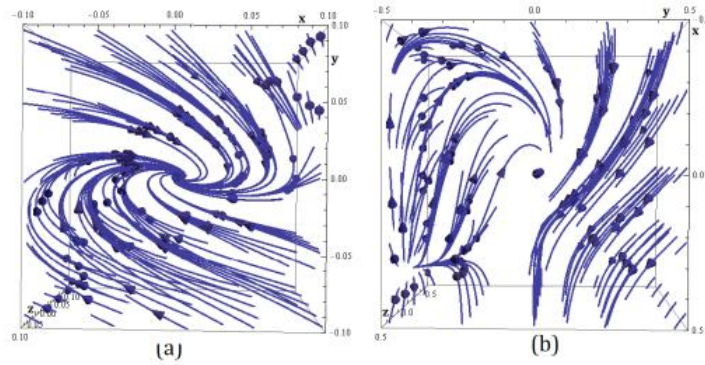


Figure 5: This figure shows the phase portraits near the origin corresponding to the fixed point E_1 and E_2 for $\lambda = 2.0$ and $\epsilon = \frac{1}{2}$. (a) is for the fixed point E_1 (spiral sink) with $(\Omega_m = 0.25, w_d = 0, q = 0.5)$ and (b) is for the fixed point E_2 (semistable) with $(\Omega_m = 0.25, w_d = 0, q = 0.5)$.

Conclusion

Differential equations are the evolution equations of every physical system. It is crucial to draw conclusions about the characteristics of the physical system solution of the evolution equations. Since the differential equations of cosmology are strongly coupled and nonlinear, accurate solutions are nearly impossible. The mathematical method known as dynamical system analysis is highly helpful in resolving this problem since it allows inference about the model's attributes without trying to find specific answers. An application of this dynamical system analysis to a non-interacting dark matter and dark energy cosmological model is demonstrated in the current work. In this case, we have taken into account both unperturbed and disturbed models collectively, and by examining the fixed points of the resulting autonomous system, we have drawn cosmic conclusions.

Taking into account both the unperturbed and perturbed evolution equations, the current cosmological model simplifies to a 3D autonomous system. In discrete dynamical system analysis, the current 3D autonomous system has 10 fixed points. Three of these 10 fixed points— B_1 , C_1 , and D_1 —do not take perturbation into account. From a cosmological perspective, the only fixed points D_1 and D_2 are intriguing because they might explain how the universe evolved from the matter-dominated era of evolution to the current accelerating phase, whereas the other fixed points simply reflect the decelerated age of expansion. In conclusion, it should be mentioned that the fixed point D_2 is the most promising because it accounts for both unperturbed and perturbed cosmic evolution from the current accelerating phase to the decelerating age. There shouldn't be a critical point at infinity because the phase space for the current model is limited to a finite region. Last but not least, the dynamical system analysis suggests that the early inflationary era cannot be replicated by the current non-interacting dark matter and dark energy model, and that the perturbation impact is negligible in this case as well.

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A Reaction-Diffusion Model for Bipolar Disorder: Exploring Learned Expectation and Mood Sensitivity Asymmetry

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Abstract

Bipolar disorder is a common psychiatric character which is a mixture of mania and depression. The causes and functions of bipolar disorder is still unknown. Nowadays the connection between behavior and emotion is being established by the old behavioral approach system(BAS). In this context a reaction-diffusion mathematical model is built to check the patterns formed by the interaction of mood and expectation. In this paper, we have investigated the phenomena of Turing pattern formation in a bipolar disorder model in presence of diffusion. By using the linear stability analysis, the conditions for the existence of stationary pattern are obtained. It is shown that the presence of diffusion in the system helps to create the Turing pattern. A series of simulation results are done to validated our theoretical findings.

Keywords: Bipolar Disorder, Reaction Diffusion, Instability, Pattern Formation.

Introduction

Bipolar disorder, a complex and pervasive psychiatric condition, [1] continues to pose challenges in understanding its underlying causes and mechanisms. Characterized by the oscillation between mania and depressive episodes, [2] this disorder's prevalence underscores the urgency to unravel its mysteries. Recent scholarly focus has turned towards theories that spotlight the intricate interplay

between emotions, behaviors, and intrinsic biological rhythms, notably within the framework of reaction-diffusion dynamics, with a particular emphasis on the dysregulation of the behavioral approach system (BAS) [12].

One notable aspect that in response, our research endeavors have culminated in the development and comprehensive scrutiny of an innovative reaction-diffusion model [13]. This model introduces clinically significant and adjustable parameters, providing a novel perspective on the complex relationship between mood and expectation. This nonlinear reaction-diffusion model, unveils a remarkable phenomenon—a discernible shift towards limit cycle behavior [13]. Intriguingly, this shift is observed once a mood-sensitivity parameter surpasses a pre-defined threshold, signifying a transition into a bipolar state [3]. Venturing further into the intricacies of the model by incorporating asymmetric mood sensitivities, we unveil a profound revelation: substantial unidirectional mood sensitivity possesses the capability to initiate the onset of bipolar disorder. This insight opens avenues for investigating how asymmetries in emotional responsiveness can lead to the complex symptomaticity of the disorder. In addition to elucidating the origins of bipolar disorder, our reaction-diffusion model provides a framework to comprehend the effects observed in mania induced by lithium and antidepressants. By simulating these scenarios within our proposed model, we offer explanations for the diverse outcomes observed in clinical contexts, thereby bridging the gap between experimental observations and theoretical models.

Mathematical Model

A mathematical model serves as a structured mathematical depiction of the fundamental elements inherent in an established system. Such models encapsulate the knowledge about the system in a practical format. It's important to note that models do not seek to replicate reality directly; rather, they provide insightful representations of it. Let us consider the following continuous-time model [4] based on interactions between the dynamical variables of mood $m(t)$, expectation $v(t)$, and reality $r(t)$:

$$\begin{aligned}\frac{dm}{dt} &= \eta_m(fm + r - v) + m(a - m)(m - 1) \\ \frac{dv}{dt} &= \eta_v(fm + r - v)\end{aligned}$$

Here, the model incorporates η_m and η_v as learning rates linked to mood and expectation, respectively. The variable f is introduced as a scaling factor that influences how mood contributes to the perceived reality ($fm + r$). Meanwhile, a is a recovery rate for mood. In this context, the term $(fm + r)$ in the model symbolizes how mood tangibly impacts reality, adhering to a linear perspective. Consequently, the

difference between $(fm + r)$ and v is indicative of an individual's level of surprise and the corresponding intensity of their responsive reaction.

Unlike the expectation $v(t)$, the equation governing mood incorporates an additional element that drives it toward a baseline level, persisting even after positive real-life events such as winning a lottery (Brickman, Coates, Janoff-Bulman, 1978) [5]. Capturing this recuperative within mood is achieved through the inclusion of the term $-am(t)$, where a^{-1} is a representation of the mood relaxation time scale. It is important to note that this linear recovery aspect is pivotal in elucidating the transition from a normal to bipolar model, specifically the cyclothymic transition. The control parameters are η_m, η_v, f are all positive, $0 < a < 1$. incorporating the self diffusion in the above system (1) the take the following form [13]:

$$\begin{aligned}\frac{\partial m}{\partial t} &= \eta_m(fm + r - v) + m(a - m)(m - 1) + d_1 \nabla^2 m \\ \frac{\partial v}{\partial t} &= \eta_v(fm + r - v) + d_2 \nabla^2 v\end{aligned}$$

Stability Analysis of Non-Diffusive System

When points in the vicinity of an equilibrium gravitate towards the equilibrium point E^* as time progresses, the equilibrium is classified as locally stable. The equilibrium point E^* is deemed linearly stable if all eigenvalues of matrix A exhibit negative real components. Conversely, when points neighboring the equilibrium point E^* diverge from it with the passage of time, the equilibrium is considered locally unstable. In this context, the equilibrium point E^* is unstable if at least one eigenvalue of matrix A possesses a positive real component. As a result, at the point E^* , the system described by equation (1) will achieve stability only when the conditions $T < 0$ and $\Delta > 0$ are simultaneously satisfied.

Let us consider a couple differential equations

$$\begin{aligned}\frac{dm}{dt} &= F(m, v) \\ \frac{dv}{dt} &= G(m, v)\end{aligned}\quad (3)$$

Now if $E^* \sim E^*(m^*, v^*)$ be the equilibrium point of the above system (1).

Then we have $F(m^*, v^*) = 0$ and $G(m^*, v^*) = 0$.

The equilibrium points of the system are:

$$E^1 = (0, r), E^2 = (1, f + r) \text{ and } E^3 = (a, af + r)$$

If, very small disturbances in the neighborhood of E^* , the system (1) will follow the linear equation

$$\frac{dm}{dt} = a_{11}m + a_{12}v \quad \#$$

$$\frac{dv}{dt} = a_{21}m + a_{22}v \quad \#(4)$$

where $a_{11} = \left[\frac{\partial F}{\partial m} \right]_{|E^*}$, $a_{12} = \left[\frac{\partial F}{\partial v} \right]_{|E^*}$, $a_{21} = \left[\frac{\partial G}{\partial m} \right]_{|E^*}$ and $a_{22} = \left[\frac{\partial G}{\partial v} \right]_{|E^*}$. Then the above system can be written as,

$$\frac{dX}{dt} = AX \quad \#(5)$$

$$\text{where, } X = \begin{pmatrix} m \\ v \end{pmatrix}, A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \quad \#(6)$$

The characteristic polynomial of A is

$$|A - \lambda I| = 0 \Rightarrow \lambda^2 - T\lambda + \Delta = 0 \quad \#(7)$$

where $T = \text{tr}(A) = a_{11} + a_{22}$ and $\Delta = \det(A) = a_{11}a_{22} - a_{12}a_{21}$. The characteristic roots of A are $\lambda_{1,2} = \frac{1}{2}[T \pm \sqrt{T^2 - 4\Delta}]$.

Jacobian and Characteristic Equation

The jacobian of the system is

$$A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix}$$

where,

$$a_{11} = f_{\eta_m} + (a - m^*)(m^* - 1) - m^*(m^* - 1) + m^*(a - m^*),$$

$$a_{12} = -\eta_m, \quad a_{21} = \eta_v f, \quad a_{22} = -\eta_v$$

$$\text{Thus, Trace} = f_{\eta_m} + (a - m^*)(m^* - 1) - m^*(m^* - 1) + m^*(a - m^*) - \eta_v,$$

$$\text{Det} = \eta_v [m^*(m^* - 1) - m^*(a - m^*) - (a - m^*)(m^* - 1)].$$

- **Case-1**

For the equilibrium point $E^1 = (0, r)$

$$\text{Trace} = f_{\eta_m} - a - \eta_v$$

The system is stable if

$$f_{\eta_m} - a - \eta_v < 0 \quad \#(11)$$

- **Case-2**

For the equilibrium point $E^2 = (1, f + r)$

$$\text{Trace} = f_{\eta_m} + a - 1 - \eta_v \quad \#$$

$$\text{Det} = \eta_v(1 - a) > 0 \quad \#(12)$$

The system is stable if

$$f_{\eta_m} + a - \eta_v - 1 < 0 \quad \#(13)$$

- **Case-3**

For the equilibrium point $E^3 = (a, af + r)$

$$\text{Trace} = f\eta_m - a(a - 1) - \eta_v \quad (14)$$

The system is unstable.

Bifurcation Analysis

Within this section, our focus shifts to conducting a linear stability analysis of the complete system. Our objective is to delineate the Turing space—a domain where the equilibrium of the uniform state becomes unstable owing to the influence of diffusion, consequently giving rise to Turing patterns [7]. When diffusion comes into play, the system can be approximated linearly, leading to the following formulation:

$$\begin{aligned} \frac{\partial m}{\partial t} &= a_{11}m + a_{12}v + d_1 \nabla^2 m \\ \frac{\partial v}{\partial t} &= a_{21}m + a_{22}v + d_2 \nabla^2 v \end{aligned} \quad (15)$$

Next let us consider a particular solution of the system (1) as follows:

$$\begin{pmatrix} m \\ v \end{pmatrix} = \begin{pmatrix} m^* \\ v^* \end{pmatrix} + \epsilon \begin{pmatrix} m_k \\ v_k \end{pmatrix} \exp\{\lambda t + ikr\} + \text{c. c.} \quad (16)$$

where λ is the growth rate, $k = |k|$ is the wave number, r is the directional vector in two dimensions. From the dispersion relations, the linear instability (ϵ) of the uniform state can be derived and c.c. stands for the complex conjugate. Then the characteristic equation is obtained as

$$\lambda^2 - \text{tr}(A_k)\lambda + \Delta_k = 0$$

The roots of the equation are,

$$\lambda_{1,2}(k) = \frac{1}{2} \left[\text{tr}(A_k) \pm \sqrt{(\text{tr}(A_k))^2 - 4\Delta_k} \right]$$

where $\text{tr}(A_k) = \text{tr}(A_0) - k^2(d_1 + d_2)$ and $\Delta_k = k^4 d_1 d_2 - k^2(d_2 P_{10} + d_1 Q_{01}) + \Delta_0$

Numerical simulation results

In our study, we undertake simulations of our proposed model within a specific bounded spatial domain, $\Omega \subseteq \mathbb{R}^2$. To facilitate this investigation, we employ zero flux boundary conditions. The choice of zero flux boundary conditions is substantiated by their implication of an absence of external input, which aligns with our objective of exploring intrinsic system dynamics.

The simulations are carried out in accordance with the model described in our study [1] for all $(x, y) \in \Omega \sim [0, L] \times [0, L]$. Initial conditions for the simulations are set to be positive and centered around the point E^* , a crucial reference point in our investigation. By employing these positive initial conditions, we aim to capture the system's response to perturbations that may arise from deviations around the

reference point. This approach allows us to discern the intricate behavior of the system and its sensitivity to initial perturbations.

To solve the system [1] we change the continuous model to a finite dimensional model i.e, discrete model in time and space. For the purpose of numerical simulation, we take $L = 200$, $\Delta t = 0.01$, time step and $\Delta x = \Delta y = 0.5$, the step length. We present the dynamical behavior of a for the system. We fixed the other parameters as $\eta_m = 1$; $\eta_v = 0.15$; $r = 0.2$; $d_1 = 0.1$ and $d_2 = 5$. From the bifurcation diagram (Fig. 1) fixing $d_2 = 5$ and the numerical simulations are completed by taking a as a control parameter.

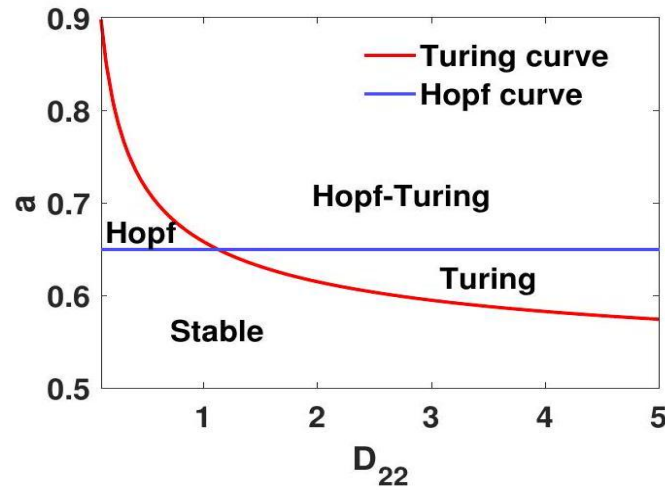


Figure 1: Bifurcation diagram in (a, d_2) space. Taking $\eta_m = 1$; $\eta_v = 0.15$; $r = 0.2$; $a = 0.6$;

Formation of Turing pattern

Turing patterns [7, 9], characterized by the emergence of spatially periodic structures from homogeneous initial conditions, hold the potential to elucidate underlying mechanisms in complex systems. These patterns have been observed in diverse fields ranging from chemistry to biology, and they provide insights into self-organization phenomena.

Our examination involves scrutinizing the influence of the control parameters a on the formation and stability of Turing patterns [7] within the context of our model (1). By systematically varying these parameters, we aim to pinpoint the critical conditions under which Turing patterns arise.

The identification of the critical value of the Turing bifurcation parameter is pivotal in our endeavor to understand the dynamics of our model. This value marks the threshold at which the transition from a homogeneous state to a spatially

patterned state occurs. The presence or absence of Turing patterns can significantly impact our interpretation of the model's behavior and its potential relevance to bipolar disorder dynamics.

The formation of pattern through the amplitude equation is well-suited to describe the region named as Turing region when the control parameter a is close to the onset of d_2 . However, deviations of a far from d_2 result in pattern phenomena beyond the scope of the amplitude equation's explanation. Our investigation focuses on locating various a values within the region where Turing is formed (depicted in Fig. 1) to explore pattern emergence effects.

To gain a deeper understanding, we analyze corresponding eigenvalue behaviors for the identified a values in the Turing region (shown in Fig. 3). This analysis provides insights into the intricate dynamics underlying pattern emergence and stability, especially when a is distant from d_2 .

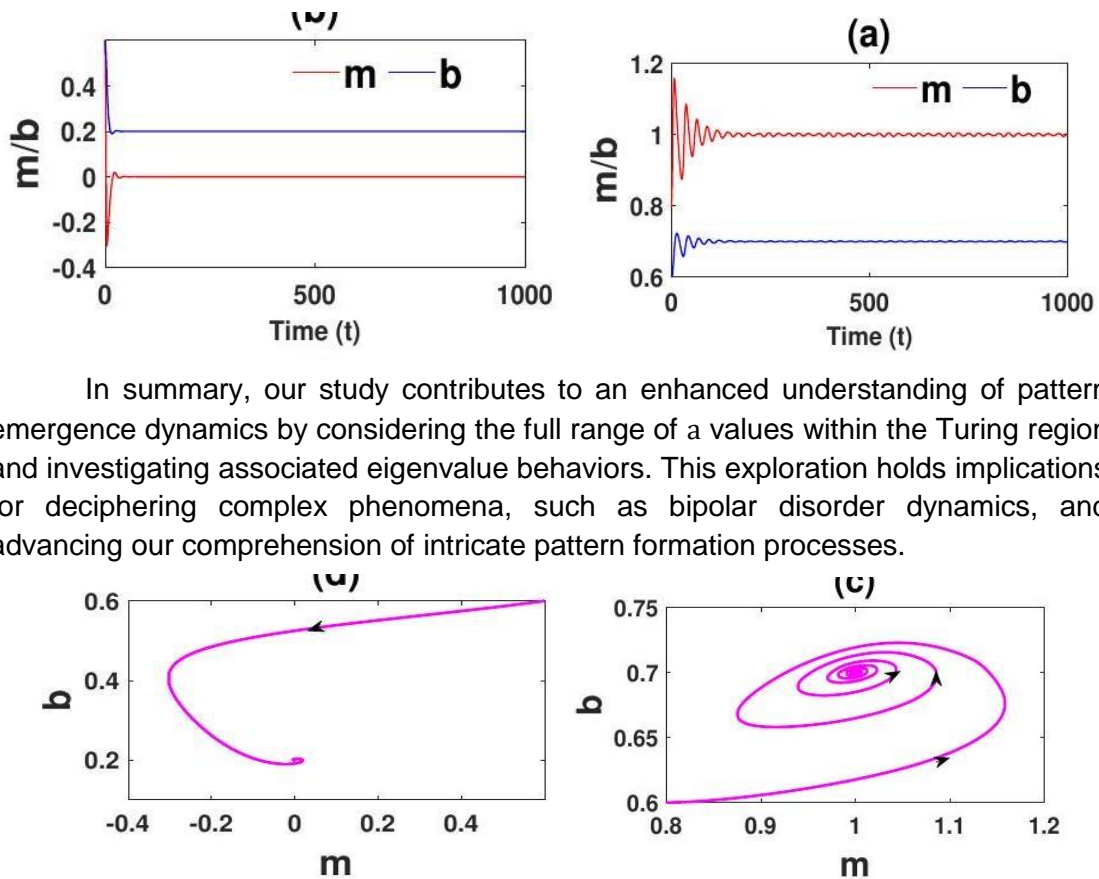


Figure 2: Behavior of Time series of the local system [1]

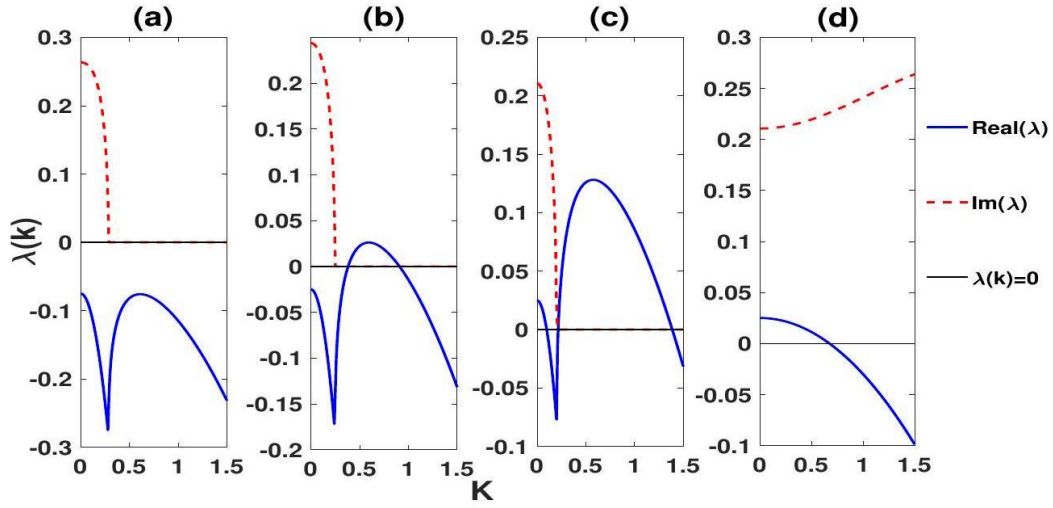


Figure 3: The dispersion relation of the self diffusion system [2] for different choice of a . The solid blue line are the real part of λ and the dash red line are the imaginary part of λ . (A) : $a = 0.5$, (B) : $a = 0.6$, (C): $a = 0.7$, (D): $a = 0.8$. The other parameters are fixed at $\eta_m = 1$; $\eta_v = 0.15$; $r = 0.2D_1 = 0.1$ and $D_2 = 5$.

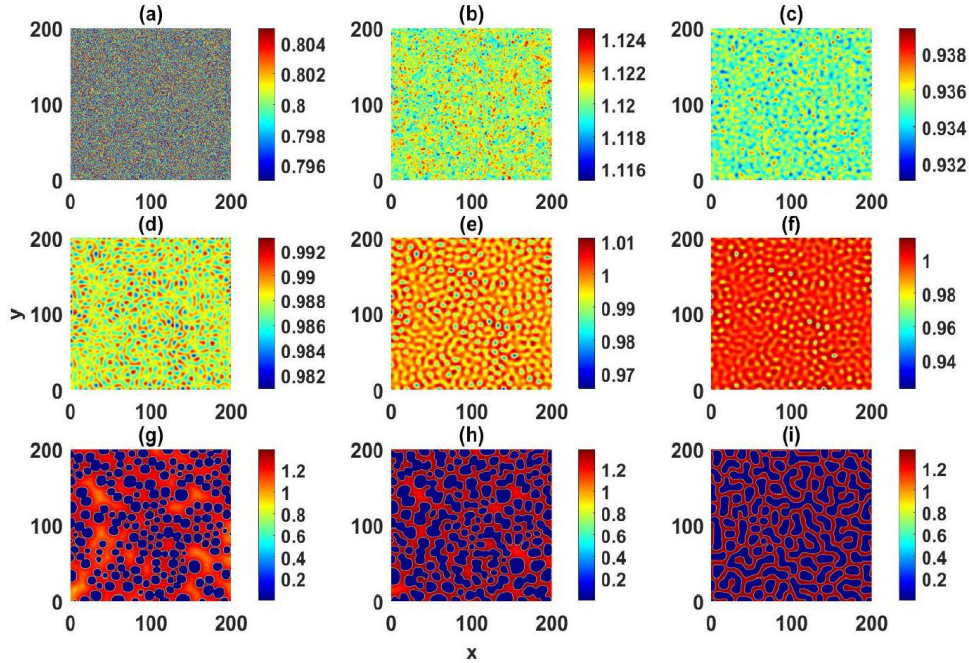


Figure 4: Evaluation of the system [2] of mood(m) for $a = 0.6$ at the moment (a): $t = 100$, (b) : $t = 200$, (c): $t = 500$, (d): $t = 1000$, (e)) $t = 2000$ and (f): $t = 5000$ and the other parameters are fixed at $\eta_m = 1$; $\eta_v = 0.15$; $r = 0.2D_1 = 0.1$ and $D_2 = 5$.

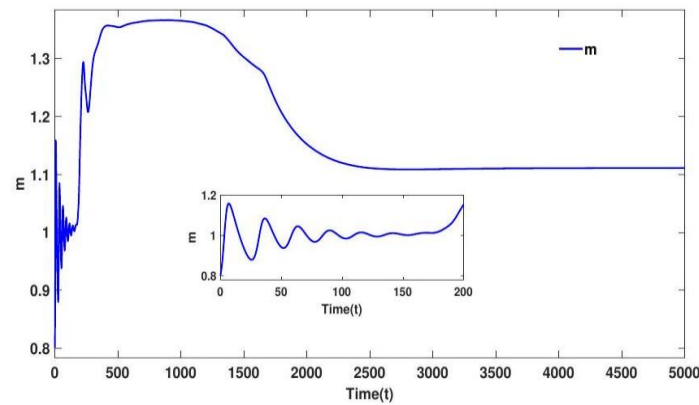


Figure 5: Development of time of mood m of the system (2) is plotted at the spatial location $(100, 100)$ and the value of $a = 0.6$. The other parameters are fixed at $\eta_m = 1$; $\eta_v = 0.15$; $r = 0.2$ $d_1 = 0.1$ and $d_2 = 5$

Conclusion

In this study, we have explored the dynamics of bipolar disorder, focusing on the intrinsic oscillatory influence between expectation and mood in the presence of self-diffusion. Self-diffusion, in this context, represents the diffusion of psychological characteristics or mood-related factors within an individual's psychological state over time. This phenomenon suggests that mood and expectation can interact and propagate within an individual's psyche, influencing their overall mental state. However, our contribution lies in identifying a pivotal psychological characteristic, represented by mood sensitivity, capable of influencing a spectrum of states ranging from normal to cyclothymic personality and Type I and II bipolar disorders. Our study primarily focused on the influence of mood sensitivity on unipolar depression, mania, and bipolar disorder. Lastly, our model presupposes constant parameters over time. However, empirical evidence suggests that higher-order nonlinearities may emerge when physiological parameters are contingent upon mood and expectation. This implies the possibility that our model's psychological parameters are dynamic, influenced by the environment rather than solely by genetics. Consequently, a logical progression in our research is to incorporate the dynamics of mood sensitivity and other parameters, including self-diffusion. This incorporation may potentially lead to bistability, thereby allowing us to explore how recurrent external events can trigger depression, mania, or bipolar disorder. This exploration could be further enhanced by introducing a spatial diffusion bipolar term, offering a more comprehensive understanding of mood propagation within an individual's psychological state.

While further analyses could place emphasis on parameters like the expectation learning rate (η_v) or the linear mood decay rate (a), identifying the primary parameter that triggers bipolar disorder requires experimental input. While characterizing mania is inherently multifaceted, many models, including ours,

streamline it into a one-dimensional variable to underscore bipolar mood behavior. The development of multidimensional models could unveil the specific traits that play a role in triggering bipolar disorder.

Acknowledgment

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The Role of Set Theory in the Development of Modern Mathematics

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Abstract

Set theory is a fundamental branch of mathematics that underpins much of modern mathematical logic and provides a unified foundation for nearly all areas of mathematics. The development of set theory, initiated by Georg Cantor in the late 19th century, marked a pivotal shift in how mathematicians approach concepts of infinity, continuity, and structure. Set theory became essential for formulating precise definitions of mathematical objects, and it facilitated the development of new fields like topology, measure theory, and mathematical logic. This paper explores the historical evolution of set theory, its influence on the structure of modern mathematics, and the key contributions of prominent mathematicians in its development. Additionally, it addresses the philosophical implications of set theory, particularly regarding the foundations of mathematics, and examines ongoing challenges and debates surrounding its application.

Introduction

Set theory is one of the most fundamental areas of mathematics, serving as the foundation for virtually all other branches of the discipline. It provides a formalized language for discussing mathematical objects, relations, and structures, enabling the construction of more complex mathematical systems. While set theory was initially developed in the late 19th century, its influence has grown exponentially over time, shaping the course of modern mathematics. This paper will explore the history, development, and importance of set theory in modern mathematics, examining its foundational role, its impact on other areas of mathematics, and the philosophical and logical implications it has had on the discipline.

The Origins of Set Theory

Set theory emerged as a response to problems in the foundations of mathematics in the late 19th century. Its formal development is attributed primarily to the German mathematician Georg Cantor, who, in the 1870s, introduced the concept of a set as a collection of distinct objects. Cantor's work initially focused on the theory of infinite sets and the properties of different types of infinities, leading to the development of the notion of cardinality (the size of a set). His discovery that there are different sizes of infinity, exemplified by his famous diagonal argument, revolutionized mathematics and had profound implications for logic and philosophy.

Cantor's work [1], however, also led to a number of paradoxes and inconsistencies within mathematics. In particular, the notion of a "set of all sets" and related concepts caused significant controversy and prompted further inquiry into the logical foundations of set theory.

Set Theory as the Foundation of Mathematics

The early 20th century saw efforts to formalize set theory and resolve its paradoxes. The most significant of these efforts was the work of Ernst Zermelo and Abraham Fraenkel, who developed the Zermelo-Fraenkel set theory (ZF) in the 1910s. Zermelo's work laid the groundwork for what would become the standard foundation for mathematics: Zermelo-Fraenkel set theory with the Axiom of Choice (ZFC).

The axiomatic approach to set theory was essential because it provided a clear and consistent framework within which mathematicians could reason about sets and their properties. The Zermelo-Fraenkel axioms, which include rules for constructing sets and determining relationships between them, form the core of modern set theory. The Axiom of Choice, in particular, allows for the existence of sets with certain properties, such as bases for vector spaces and the ability to select elements from an infinite collection of sets.

Set theory provides the logical foundation for virtually all of mathematics. In ZFC, every mathematical object can be viewed as a set, and operations on these objects can be understood in terms of set-theoretic relations. The framework of set theory enables mathematicians to rigorously define numbers, functions, spaces, and structures, allowing for precise reasoning in all areas of mathematics.

Set Theory and the Development of Logic

The development of set theory had profound consequences for the field of mathematical logic. One of the most important results was the realization that the paradoxes of set theory, such as Russell's Paradox, were indicative of deeper issues in the logical structure of mathematics. Russell's Paradox, which arises when considering the set of all sets that do not contain themselves, shows that naive set theory (which allowed for unrestricted comprehension) leads to contradictions.

To resolve these paradoxes, the formalization of set theory through axiomatic systems like ZFC became essential. In this axiomatic context, sets are defined only by the axioms, which prevent contradictory constructions. This move towards formalization in set theory had significant consequences for the development of logic, leading to the rise of formal systems such as first-order logic, model theory, and proof theory. These systems form the backbone of modern mathematical logic, which in turn supports the rigorous development of mathematical theories in fields ranging from algebra to topology.

Set Theory's Impact on Other Areas of Mathematics

Beyond providing the foundation for mathematical logic, set theory has had a far-reaching impact on many areas of mathematics, especially in the formalization and unification of different mathematical disciplines. Some of the key contributions of set theory to various branches of mathematics are as follows:

- **Real Analysis and Topology**

Set theory provides a language for discussing the real numbers and their properties. The construction of the real numbers through Dedekind cuts or Cauchy sequences is a set-theoretic endeavor. Similarly, in topology, set theory is used to define open sets, closed sets, and the concepts of continuity and convergence. The compactness theorem in topology and the foundation of metric spaces both rely heavily on set-theoretic concepts.

- **Abstract Algebra**

In abstract algebra, set theory provides a structure for understanding groups, rings, and fields. Group theory, for example, involves the study of sets equipped with an operation that satisfies certain properties. The notion of a set equipped with additional structure, such as a vector space or a group, is a direct consequence of set-theoretic thinking.

- **Category Theory**

Set theory has also had a significant impact on the development of category theory, which provides a high-level framework for understanding mathematical structures and their relationships. Category theory studies objects and morphisms between objects, and while it is not directly based on sets, it relies on the set-theoretic understanding of relations and functions to formalize the connections between various mathematical structures.

- **Mathematical Logic and Foundations**

Set theory remains the cornerstone of mathematical foundations and continues to play a critical role in the philosophy of mathematics. It provides the formal underpinning for discussions about the consistency and completeness of mathematical systems. The famous Incompleteness Theorems of Kurt Gödel, for

example, were proved using set-theoretic techniques. Similarly, the study of large cardinals and other advanced set-theoretic concepts has led to new insights into the limits of mathematical reasoning.

Set Theory and the Philosophy of Mathematics

Set theory's implications extend beyond the realm of mathematics into the philosophy of mathematics. One of the central issues in this field is the question of the nature of mathematical objects. Are mathematical entities like numbers and sets real objects that exist independently of human thought, or are they mere linguistic constructions? Set theory, particularly through the work of philosophers like Gottlob Frege and later Quine, has been at the heart of these discussions.

The development of set theory also contributed to the understanding of the relationship between logic and mathematics. The formalization of mathematics through set theory allowed for the construction of rigorous logical systems and helped to answer questions about the nature of mathematical truth and proof.

Moreover, set theory is central to the debates surrounding mathematical Platonism and formalism. While Platonists see set theory as describing a real, objective mathematical universe, formalists argue that set theory is merely a syntactical manipulation of symbols with no inherent meaning. These debates continue to shape how mathematicians and philosophers approach the foundations of mathematics.

Conclusion

Set theory has played an indispensable role in the development of modern mathematics, from providing the logical foundation for the discipline to influencing areas as diverse as algebra, analysis, and logic. Its axiomatic formulation has resolved many of the paradoxes and inconsistencies that arose in the early development of mathematics, while its application has unified diverse mathematical fields under a common framework. The continued evolution of set theory and its impact on mathematical philosophy ensures that it remains at the heart of contemporary mathematical research. In summary, set theory is not merely a branch of mathematics but a foundational tool that has shaped the course of modern mathematics. Its influence extends far beyond the formal manipulation of sets; it has enabled mathematicians to explore new territories, resolve long-standing problems, and develop a deeper understanding of the nature of mathematics itself.

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27**Selection of Optimum Chassis Material for Electric Vehicles: An Eclectic Decision**

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Abstract

In the present scenario due to the strict environmental norms as well as the rapid depletion of relic fuels, Electric vehicles are the lucrative option for sustainable transportation system. Due to the absence of transportation engines electric vehicles should be lighter in weight. In this respect the concept of lightweight smart materials is relatively new and is going under extensive research because it shows the great potential of being useful in electric vehicle industry, those materials that can change cost of trends Electric Vehicles. These materials can reduce the weight of the automobile, and some parts are made by smart materials to decrease the total cost of a car. In this work, the optimal chassis material for electric vehicles is chosen and ranked from a given set of alternatives (cast iron, aluminum alloy, plastics-polymer, rubber, glass, non-ferrous alloy, steel, magnesium) and criterion (tensile strength, density, elastic modulus, specific modulus, and cost) using two-way multi-criteria decision-making (MCDM) techniques. Firstly, entropy method is utilized to identify the criteria weight of the candidate materials alternative and density scored the highest value. To choose the best candidate material, multi-objective optimization based on ratio analysis (MOORA) plus full multiplicative form (MULTIMOORA) is then used. The results of the two-way MCDM techniques show that cast iron (CI) partaking the uppermost score as an optimum material followed by steel and other intrant materials. Finally, sensitivity analysis shows the effectiveness of the rank and to be an effective means of choosing the best option from a range of potential materials. Research on

chassis materials for electric vehicle problems may be resolved in the future by using different multi-objective decision-making (MODM) techniques with an infinite number of criteria and options.

Keywords: Electric vehicles, Chassis materials, Entropy, Moora, Multimooraa, Sensitivity analysis.

Introduction

Transportation technology has advanced extremely quickly both in developed and emerging nations. The increased levels of human mobility necessitate these advancements. The primary goal of the growth of the transportation industry is to provide a system of transportation that makes it possible for people to move around easily, quickly, affordably, and conveniently [1-2]. Since transportation is essential to human existence, there is a growing demand for it, particularly for land-based modes of transportation including trucks, cars, buses, and motorcycles. Although more cars can improve human mobility, there may be unintended consequences for the environment, such as increased air pollution [3]. Most cars on the road today use internal combustion engines that run on fossil fuels, which can lead to exhaust pollutants that lower the quality of the air we breathe [2]. Global warming is significantly impacted by motor vehicle-related air pollution parameters such as carbon monoxide (CO), nitrogen oxide (NO_x), methane (CH₄), non-methane, Sulphur dioxide (SO_x), and suspended particle matter (SPM10). The bus is a popular, reasonably priced mode of public transit with a necessary sleeping capacity. These elements contribute to a decrease in the quantity of private automobiles on the road. Most diesel engines used in buses belong to the class of internal combustion engines [4]. Incomplete combustion within the engine can result in the emission of NO_x, CO, and HO gases, which have the potential to pollute the surrounding air. Apart from generating certain gases, diesel engines also emit black smoke in the form of soot when they accelerate or operate at maximum load. They also need regular maintenance to function [3-4].

Electric vehicles have a few major advantages over diesel engines, including being extremely efficient, noiseless, and emitting less pollutants while operation [5]. On the other hand, the battery life of electric buses is their primary drawback. The car needs enough electricity from the battery to operate. More power is needed for heavier vehicles [4-5]. Therefore, reducing weight is necessary to improve battery endurance. Any vehicle's chassis structure, which is responsible for transporting all its parts and bearing the weight of all its loads including the forces that arise during cornering, acceleration, and deceleration is essential to adding weight to the vehicle.

Thus, this study has used a hybrid multicriteria decision-making (MCDM) technique to screen and rank several PCMs for energy storage applications.

Materials and Methods

Several criteria, including material properties, tensile strength (C_1), density (C_2), elastic modulus (C_3), specific modulus (C_4) and cost (C_5) etc., should be taken into consideration when choosing chassis materials for electric vehicles. The hierarchical structure is shown in Figure 1. Conventional methods of material selection that involve side-by-side documentation, like collected works, have limitations about information and the utilization of pertinent data [2]. Thus, the technologically significant chassis materials for electric vehicle applications that are taken into consideration in this study are cast iron (A_1), aluminum alloy (A_2), plastic polymer (A_3), rubber (A_4), glass (A_5), nonferrous alloy (A_6), steel (A_7), magnesium (A_8) depicted in Table 1.

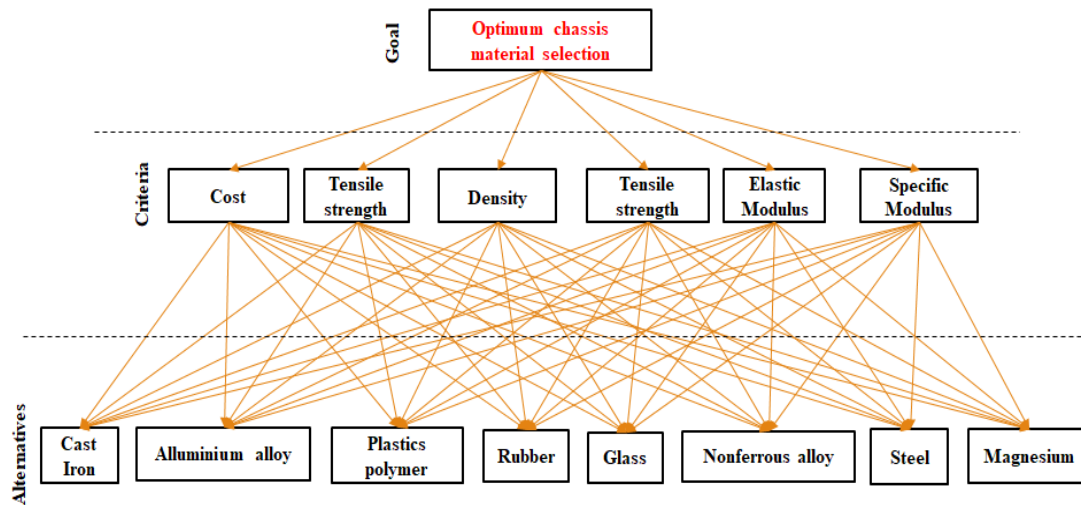


Figure 1: Hierarchy of the Identified Problem

Table 1: Material Properties for Pugh Matrix

	Criteria				
	C_1	C_2	C_3	C_4	C_5
A_1	870	650	7300	147	118
A_2	320	90	2705	70	25.5
A_3	64	40	1010	2.7	104
A_4	124	40	57	0.01	70
A_5	11	7	2500	72	70
A_6	5500	319	2730	110	762
A_7	56	420	7982	200	762
A_8	305	90	1738	45	45

The chassis materials can be ranked and screened using a wide range of techniques, such as theoretical calculations, numerical simulations, and experimental approaches [6-9]. The authors of this work used hybrid MCDM techniques to rank and screen different chassis materials for electric vehicle applications. To assess the performance of the candidate materials, two MCDM approaches have been applied: Mult objective optimization based on ratio analysis (MOORA) with complete multiplicative form (MULTIMOORA) [10-12]. When combined, these methods have proven to be a highly effective means of material screening and initial ranking for a range of chassis material-based applications. To determine the relative significance of the attributes on the decision-making process, apply Shannon's entropy approach [13].

Results and Discussion

This work examines five criteria likely; tensile strengths (C_1), density (C_2), elastic modulus (C_3), specific modulus (C_4), and cost (C_5), as well as eight alternatives; cast iron (A_1), aluminum alloy (A_2), plastics {polymer} (A_3), rubber (A_4), glass (A_5), nonferrous alloy (A_6), steel (A_7), and magnesium (A_8) from previously published research [14-15] in order to show how the MOORA plus multiplicative form MULTIMOORA can be applied in the selection dilemma. Table 1 displays the decision matrix for the chosen task. Table 2 displays the weight of each criterion before applying MOORA and its multiplicative form MULTIMOORA procedures. This weight is determined using Shannon's entropy approach.

Table 2: Weights Assigned to each Criterion

	Criteria				
	C_1	C_2	C_3	C_4	C_5
Weight	0.1114	0.0442	0.7769	0.0188	0.0485

The MOORA and MULTIMOORA systems rely entirely on the ratio system and are simple to calculate, requiring little mathematical knowledge. The choice matrix presented in Table 1 is first normalized, and the candidate materials' total performance is then calculated based on the advantageous and non-beneficial criteria. The candidate materials are ranked, and their total performance is displayed in Table 3. Based on the ratio system section of MOORA and entire multiplicative form is shown in Figure 2 and 3 respectively.

Table 3: Overall Results

	Alternatives							
	A_1	A_2	A_3	A_4	A_5	A_6	A_7	A_8
MOORA	0.2795	0.0275	0.0338	0.0406	0.0537	-0.1111	0.6378	0.0380
Rank 1	2	7	6	4	3	8	1	5
MULTIMOORA	0.1598	0.0167	0.0156	0.0036	0.1155	0.1603	0.8912	0.0309
Rank 2	3	6	7	8	4	2	1	5

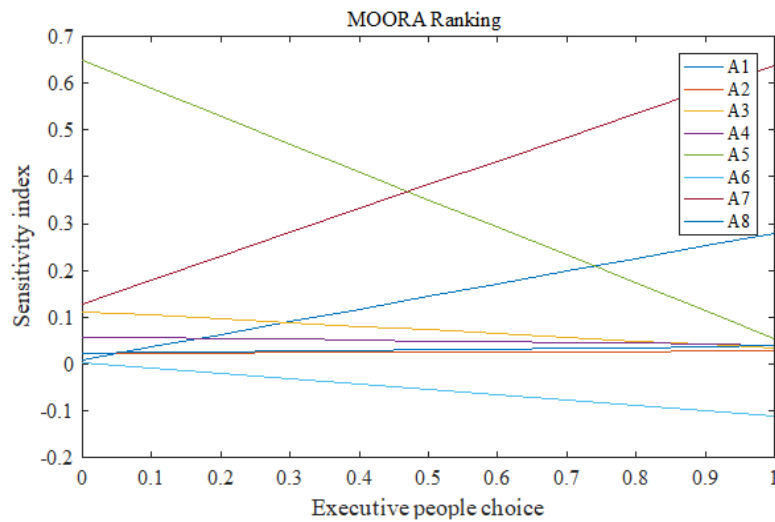


Figure 2: MOORA Ranking Validation

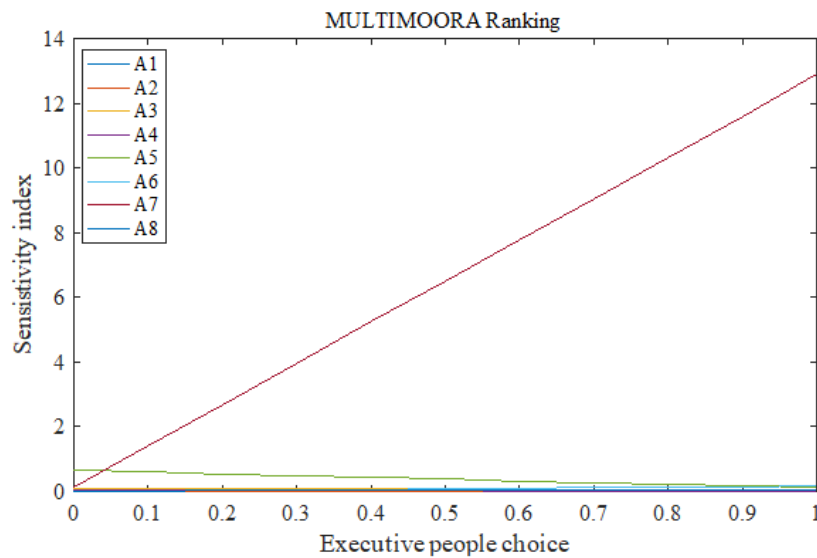


Figure 3: MULTIMOORA Ranking Validation

Conclusion

The choice of chassis materials is crucial to the development of the modern sustainable automotive market. The following findings are drawn considering the gathering and examination of relevant data related to this endeavor.

- In this work, MOORA and its complete multiplicative form MULTIMOORA methodologies are used to identify and explain the multi-objective choice making issue for electric car chassis material.
- According to MOORA and MULTIMOORA methodologies, steel is the optimum alternative followed by others.

Ultimately, these methods are shown to be an effective means of choosing the best option from a range of potential materials. Research on phase transition materials for electric vehicle chassis problems may be resolved in the future by using different multi-objective decision-making techniques with an infinite number of criteria and options.

Conflict of Interest

The author declares that there is no conflict of interest.

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Quantum Entanglement and Decoherence: The Fragile Nature of Entangled States

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Abstract

Quantum entanglement, a fundamental and counterintuitive phenomenon in quantum mechanics, has emerged as a key component in various quantum information processing tasks. However, the fragile nature of entangled states poses a significant challenge, as they are susceptible to the detrimental effects of decoherence. This paper explores the interplay between quantum entanglement and decoherence, examining how the environment-induced loss of coherence can destabilize and ultimately destroy entangled states.

Keywords: *Quantum Entanglement, Decoherence, Quantum Information, Coherence, Quantum Systems.*

Introduction

Quantum entanglement, the peculiar phenomenon where the state of one quantum system is inextricably linked to the state of another, has been at the forefront of quantum physics research for decades (Horodecki et al., 2009). While entanglement is often regarded as a uniquely quantum-mechanical concept, it is enlightening to consider a simple non-quantum version of entanglement first, as this can help elucidate the subtle nature of this phenomenon (Wilczek, 2018). Entanglement is a crucial aspect of quantum mechanics that sets it apart from the

classical world, and it underpins many of the potential applications of quantum technology, including quantum computing, quantum cryptography, and quantum sensing (Horodecki et al., 2009).

However, the stability of entangled states is a significant challenge, as they are highly susceptible to the detrimental effects of decoherence. Decoherence, the process by which quantum systems lose their coherence and become entangled with their environment, is a critical obstacle in the development of practical quantum technologies. This paper aims to explore the interplay between quantum entanglement and decoherence, and how decoherence affects the stability of entangled states.

Quantum Entanglement: The Mysterious Phenomenon

Quantum entanglement is a unique and intriguing aspect of quantum mechanics, where two or more quantum systems become inextricably linked, exhibiting correlations that cannot be explained by classical physics (Horodecki et al., 2009). This special connection between particles or systems is often regarded as one of the most puzzling and counterintuitive features of quantum theory, as it appears to defy our everyday understanding of how the world should work.

Entanglement occurs when the quantum states of multiple particles or systems become interdependent, such that the state of one particle or system cannot be described independently of the others, even if they are spatially separated. This means that the properties of one entangled particle or system can instantaneously affect the properties of the other, a phenomenon that has been experimentally verified and has profound implications for the nature of reality and our understanding of the quantum world.

Decoherence: The Fragility of Entangled States

However, the stability of these entangled states is often short-lived, as they are highly susceptible to the influence of their surrounding environment. This process, known as decoherence, describes the degradation of quantum coherence and the loss of the unique properties of entangled systems due to their interaction with the external environment (Geesink & Meijer, 2016).

Decoherence occurs when the quantum system being studied interacts with its environment, causing the loss of information from the system to the environment. This interaction can lead to the destruction of the delicate quantum correlations that define entanglement, effectively destroying the special connection between the entangled particles or systems (Abouelkhir et al., 2022).

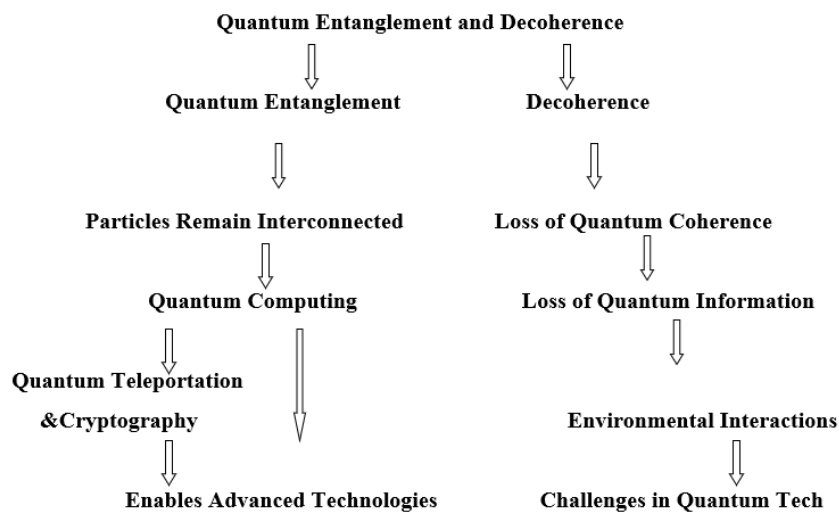
The implications of decoherence are significant for the field of quantum information processing, as it poses a significant challenge in maintaining the stability and fidelity of quantum states necessary for tasks such as quantum computing and quantum communication. Understanding the dynamics of quantum correlations and

the mechanisms underlying decoherence is, therefore, a crucial area of research in quantum physics.

Table 1: Quantum Entanglement and Decoherence - The Fragile Nature of Entangled States

Aspect	Description	Impact
Quantum Entanglement	A quantum phenomenon where particles remain interconnected regardless of distance.	Enables quantum computing, teleportation, and cryptography.
Decoherence	The process by which quantum coherence is lost due to interaction with the environment.	Causes loss of quantum information, challenging quantum computing and communication.
Fragility of Entangled States	Entangled states are highly sensitive to environmental disturbances.	Requires careful isolation and error correction techniques.
Environmental Noise	Random interactions with the surroundings that cause decoherence.	Reduces entanglement fidelity, affecting quantum system performance.
Mitigation Strategies	Techniques such as quantum error correction, entanglement purification, and decoherence-free subspaces.	Helps in preserving entanglement and enhancing quantum system robustness.
Applications in Quantum Information	Quantum computing, cryptography, teleportation, and networking.	Key to advancing technology in secure communications and powerful computations.

Block Diagram: Quantum Entanglement and Decoherence



These tables and diagrams help illustrate the delicate nature of quantum entanglement and the impact of decoherence on entangled states.

The Interplay between Entanglement and Decoherence

The interplay between quantum entanglement and decoherence is a complex and multifaceted relationship, as the two phenomena are intrinsically linked. Entanglement is a fundamental feature of quantum mechanics, but it is also highly sensitive to environmental influences, making it vulnerable to decoherence (Horodecki et al., 2009).

As discussed in the sources, the interaction between a quantum system and its environment can result in the dissipation or loss of information contained in the system, leading to the degradation of quantum coherence and the destruction of entanglement (Abouelkhir et al., 2022). This is a significant challenge in the development of practical quantum technologies, as the preservation of quantum correlations is essential for the successful implementation of quantum information processing tasks.

Efforts to protect quantum systems from decoherence and maintain the stability of entangled states have been a focus of extensive research in the field of quantum physics. Strategies such as quantum error correction and the development of isolated, well-controlled quantum systems have been explored to mitigate the effects of decoherence and preserve the delicate quantum phenomena that underlie the potential of quantum technologies (Geesink& Meijer, 2016), (Abouelkhir et al., 2022).

Protecting Entangled States from Decoherence

Researchers have made significant progress in understanding the complex interplay between quantum entanglement and decoherence, and have explored various strategies to mitigate the effects of decoherence and protect the stability of entangled states (Abouelkhir et al., 2022). These approaches often involve isolating the quantum system from its environment, designing more robust quantum systems, and developing error-correction and stabilization techniques to counteract the destructive effects of decoherence.

One promising approach is the use of quantum sensors, which leverage the sensitivity of quantum systems to measure and characterize spin-dependent interactions (Budker et al., 2022). These sensors can be used to detect subtle environmental influences and optimize the stability of quantum systems, helping to preserve the delicate quantum correlations that define entanglement.

Quantum error correction, another area of active research, seeks to develop techniques to detect and correct errors in quantum systems, compensating for the effects of decoherence and ensuring the fidelity of quantum states. These efforts are crucial for the advancement of quantum information processing, as the reliable and

stable manipulation of entangled states is a fundamental requirement for the practical implementation of quantum technologies.

The interplay between quantum entanglement and decoherence is a complex and evolving area of research, with significant implications for the development of quantum technologies. By understanding the mechanisms underlying decoherence and exploring strategies to protect entangled states, researchers are making important strides in unlocking the full potential of quantum systems and paving the way for transformative applications in fields such as computing, communication, and sensing.

Mathematical Calculations on Quantum Entanglement and Decoherence

The mathematical formalism that describes the relationship between quantum entanglement and decoherence is rooted in the principles of quantum mechanics and the theory of open quantum systems. The dynamics of quantum correlations, including entanglement, can be analyzed using tools such as quantum Fisher information and skew information, which provide quantitative measures of the degree of quantum coherence and the susceptibility of a system to decoherence (Abouelkhir et al., 2022).

For instance, the quantum Fisher information, which quantifies the precision with which a quantum parameter can be estimated, can be used to study the degradation of quantum correlations under the influence of decoherence. Similarly, the skew information, which captures the degree of non-commutativity between quantum observables, can provide insights into the dynamics of quantum correlations in the presence of environmental interactions (Abouelkhir et al., 2022).

These analytical techniques have been used to derive simple expressions for the quantum Fisher and skew information, and to investigate their time evolution under the effects of decoherence. Such mathematical analyses allow for a deeper understanding of the interplay between entanglement and decoherence, and can inform the development of strategies to protect and stabilize entangled quantum states (Abouelkhir et al., 2022)(Slaoui et al., 2022)(Budker et al., 2022).

The sources provided (Slaoui et al., 2022) (Abouelkhir et al., 2022) discuss these advanced analytical techniques in quantum estimation theory, which are crucial for the theoretical investigation of quantum entanglement and decoherence. By combining these mathematical tools with experimental observations and numerical simulations, researchers are making significant progress in unraveling the complex dynamics of quantum systems in the presence of environmental noise and decoherence.

Quantum Entanglement

Quantum entanglement is a phenomenon where two or more particles become interconnected such that the state of one particle instantaneously influences the state of the other, no matter the distance between them.

Consider two entangled qubits (**quantum bits**) $|\psi\rangle$ in the Bell state:

$$|\psi\rangle = \frac{1}{\sqrt{2}}(|00\rangle + |11\rangle)$$

This state represents two qubits in a superposition where they are both in state $|00\rangle$ or both in state $|11\rangle$. The state vector for the system can be written as:

$$|\psi\rangle = \frac{1}{\sqrt{2}}(|0\rangle \otimes |0\rangle + |1\rangle \otimes |1\rangle)$$

Quantum Decoherence

Quantum decoherence describes the process by which a quantum system loses its quantum properties as it interacts with its environment, causing it to transition from a coherent superposition to a classical mixture.

For a simple decoherence model, let's consider a single qubit in a superposition state interacting with the environment. The initial state of the qubit can be written as:

$$|\psi\rangle = \alpha|0\rangle + \beta|1\rangle$$

After interaction with the environment, the density matrix ρ of the qubit evolves as:

$$\rho = |\psi\rangle\langle\psi| = |\alpha|^2|0\rangle\langle 0| + \alpha\beta^*|0\rangle\langle 1| + \alpha^*\beta|1\rangle\langle 0| + |\beta|^2|1\rangle\langle 1|$$

Decoherence causes the off-diagonal elements $\alpha\beta^*$ and $\alpha^*\beta$ to decay over time, leading to a mixed state. If γ is the decoherence rate, the density matrix evolves as:

$$\rho(t) = \begin{pmatrix} |\alpha|^2 & \alpha\beta^*e^{-\gamma t} \\ \alpha^*\beta e^{-\gamma t} & |\beta|^2 \end{pmatrix}$$

As $t \rightarrow \infty$, the off-diagonal terms vanish, and the qubit ends up in a classical probabilistic mixture:

$$\rho(t \rightarrow \infty) = \begin{pmatrix} |\alpha|^2 & 0 \\ 0 & |\beta|^2 \end{pmatrix}$$

These are some fundamental calculations that illustrate the core concepts of quantum entanglement and decoherence.

Entanglement and Bell's Inequality

One of the famous aspects of quantum entanglement is its violation of Bell's inequality, which classical systems adhere to, but quantum systems do not.

Consider measuring the spin of entangled particles along different axes. Let $A(a)$ and $B(b)$ be the spin measurement outcomes for particles A and B along directions a and b . For a Bell state, the correlation function $E(a, b)$ is given by:

$$E(a, b) = \langle \psi | (\sigma \cdot a) \otimes (\sigma \cdot b) | \psi \rangle$$

where $\sigma \cdot a$ and $\sigma \cdot b$ are the Pauli matrices representing spin measurements along directions a and b .

Quantum State Tomography

Quantum state tomography is a method to reconstruct the quantum state of a system based on measurements. For a two-qubit system, the density matrix ρ can be expressed in terms of the Pauli matrices σ_i as:

$$\rho = \frac{1}{4} \sum_{i,j} R_{ij} (\sigma_i \otimes \sigma_j)$$

where R_{ij} are the correlation coefficients obtained from measurements.

Decoherence in Open Quantum Systems

A more general approach to decoherence is using the Lindblad master equation, which describes the time evolution of the density matrix ρ of an open quantum system interacting with its environment:

$$\frac{d\rho}{dt} = -\frac{i}{\hbar} [H, \rho] + \sum_k \left(L_k \rho L_k^\dagger - \frac{1}{2} \{ L_k^\dagger L_k, \rho \} \right)$$

where H is the Hamiltonian of the system, L_k are the Lindblad operators representing different decoherence processes, and $\{, \}$ denotes the anti-commutator.

Example: Spin-Boson Model

The spin-boson model is a common example used to study decoherence. It consists of a two-level system (spin) coupled to a bosonic bath (environment). The Hamiltonian for this system can be written as:

$$H = -\frac{\hbar\Delta}{2} \sigma_x + \sum_k \hbar\omega_k b_k^\dagger b_k + \sum_k \sigma_z (g_k b_k^\dagger + g_k^* b_k)$$

where Δ is the tunneling amplitude, ω_k are the bath mode frequencies, g_k are the coupling strengths, and b_k^\dagger and b_k are the creation and annihilation operators for the bath modes.

Entanglement Entropy

Entanglement entropy is a measure of the entanglement between subsystems. For a bipartite system with density matrix ρ , the entanglement entropy S is given by the von Neumann entropy:

$$S(\rho_A) = -\text{Tr}(\rho_A \log \rho_A)$$

where ρ_A is the reduced density matrix of subsystem A obtained by tracing out subsystem B from the total density matrix ρ .

These additional calculations delve deeper into the mathematical framework of quantum entanglement and decoherence.

Conclusion

Quantum entanglement is a fundamental and powerful feature of quantum mechanics, but it is also highly susceptible to the detrimental effects of decoherence. The interplay between entanglement and decoherence is a complex and active area of research, with important implications for the development of practical quantum technologies.

Through the use of analytical techniques such as quantum Fisher information and skew information, researchers have gained deeper insights into the dynamics of quantum correlations under the influence of environmental interactions. These mathematical tools, combined with experimental observations and numerical simulations, have enabled researchers to explore strategies to protect entangled states and mitigate the effects of decoherence.

Key approaches to preserving the stability of entangled states include the development of quantum sensors, the implementation of quantum error correction, and the design of more robust and isolated quantum systems. As the understanding of quantum entanglement and decoherence continues to evolve, the prospects for realizing the transformative potential of quantum technologies are steadily improving.

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Review on Synthesis Technique of Zinc Oxide Nanoparticles

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Abstract

Zinc oxide (ZnO) nanoparticles have gained significant attention in recent years due to their unique physicochemical properties and wide-ranging applications across various fields. This review provides a comprehensive analysis of the synthesis, properties, applications, and environmental impact of ZnO nanoparticles. Various synthesis methods, including chemical, physical, and biological techniques, are discussed, highlighting their advantages and limitations. The distinctive properties of ZnO nanoparticles, such as high surface area-to-volume ratio, optical transparency, and robust antimicrobial activity, make them ideal for applications in cosmetics, electronics, environmental remediation, and biomedical fields. The role of ZnO nanoparticles in photocatalysis and their potential as UV-blocking agents in sunscreens are explored in detail. Their use in drug delivery systems and as diagnostic tools in nanomedicine further underscores their versatility. However, the widespread use of ZnO nanoparticles raises concerns about their environmental and biological safety. Studies on their cytotoxicity, bioaccumulation, and potential to cause oxidative stress in living organisms are critically reviewed, emphasizing the need for standardized risk assessment protocols. This review also examines the environmental fate of ZnO nanoparticles, focusing on their interaction with soil, water, and biota, and evaluates strategies to mitigate their ecological impact. Future research directions are proposed to enhance the biocompatibility and environmental sustainability of ZnO nanoparticles while leveraging their functional properties for innovative applications. This holistic approach aims to balance the technological benefits of ZnO nanoparticles with environmental and public health considerations.

Keywords: Zinc Oxide Nanoparticles, Synthesis Method, Hydrothermal Method, Structure, Green Synthesis Methods.

Introduction

Zinc oxide (ZnO) nanoparticles have emerged as one of the most versatile and widely studied nanomaterials, owing to their unique physicochemical properties and broad spectrum of applications. These nanoparticles, typically ranging from 1 to 100 nm in size, exhibit exceptional optical, catalytic, and antimicrobial properties, making them a preferred choice for various industrial, biomedical, and environmental applications. The nanoscale size of ZnO particles imparts distinctive characteristics, such as high surface area, enhanced reactivity, and tunable optical bandgap, distinguishing them from their bulk counterparts.

ZnO nanoparticles can be synthesized through diverse methods, including chemical, physical, and biological approaches, each offering unique advantages in terms of size control, morphology, and scalability. Their applications span numerous domains, from serving as active components in sunscreens, cosmetics, and coatings to acting as catalysts for photocatalytic degradation of pollutants. In the biomedical field, ZnO nanoparticles have shown promising potential in drug delivery, imaging, and antimicrobial therapies due to their biocompatibility and multifunctional properties. Zinc Oxide nanoparticles (ZnO NPs) are tiny particles of zinc oxide with unique properties like high chemical stability, broad radiation absorption spectrum, and strong photocatalytic activity, making them valuable in various applications including electronics, cosmetics, medicine, and environmental remediation; however, concerns regarding their potential environmental impact exist due to their potential toxicity to living organisms when released into the environment.

However, the rapid expansion of ZnO nanoparticle applications has also raised concerns about their environmental and biological safety. Their increased release into the environment through industrial and consumer products necessitates a thorough understanding of their interaction with ecological systems. Studies have reported potential toxicity of ZnO nanoparticles to aquatic and terrestrial organisms, primarily driven by the generation of reactive oxygen species (ROS) and dissolution of zinc ions.

This article aims to provide a detailed overview of the synthesis techniques, intrinsic properties, and multifaceted applications of ZnO nanoparticles, along with a critical evaluation of their environmental impact and toxicity. By addressing the challenges and opportunities associated with ZnO nanoparticles, this review seeks to contribute to the development of sustainable and safe nanotechnology practices.

Structure

Zinc and oxygen, belonging to the second and sixth groups of the periodic table respectively, make zinc oxide (ZnO) a well-established II-VI semiconductor in materials science. ZnO exhibits numerous remarkable and advantageous properties, including excellent transparency, antimicrobial activity, high electron mobility, a wide

bandgap, strong luminescence at room temperature, and significant thermal and mechanical stability under ambient conditions. Its large bandgap of 3.37 eV positions it on the threshold between ionic and covalent semiconductors.

ZnO crystallizes in a wurtzite (B4) structure, characterized by a hexagonal unit cell with lattice parameters of $a=0.325\text{ nm}$ and $c=0.521\text{ nm}$. In this hexagonal wurtzite configuration, each anion is surrounded by four cations at the corners of a tetrahedron, demonstrating tetrahedral coordination and the presence of sp^3 covalent bonding. This tetrahedral arrangement imparts ZnO with a non-centrosymmetric structure, which is integral to its distinctive properties in the figure 1.

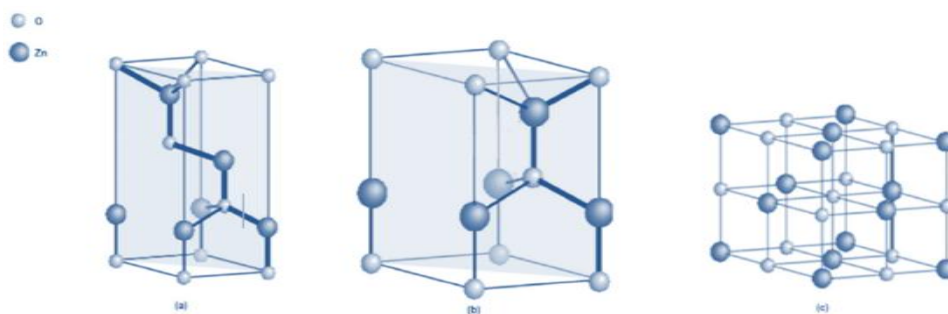


Fig. 1: Crystal structure models of ZnO (a) zinc blende (b) wurtzite and (c) rock saltⁱ

Preparation Method

Conventional Synthesis Methods

- Hydrothermal Method:** The hydrothermal method involves the reaction of precursor chemicals in an aqueous solution under high-pressure and high-temperature conditions, leading to the formation of nanoparticles. This technique has garnered significant attention due to its low processing temperature, eco-friendliness, cost-effectiveness, scalability, simple equipment requirements, and ease of handling. By adjusting the temperature, duration, and precursor concentration during the hydrothermal process, the size and shape of the resulting particles can be tailored.

The typical procedure includes preparing zinc acetate dihydrate solutions ($\text{Zn}(\text{CH}_3\text{COO})_2 \cdot \text{H}_2\text{O}$), dissolving NaOH in methanol, and adding this solution to the zinc acetate solution under stirring. The pH is then adjusted to a range of 8–11. The resulting suspension is transferred to a Teflon-lined stainless steel autoclave and maintained at $120\text{ }^\circ\text{C}$ for 6 to 12 hours. Afterward, the product is cleaned with water and methanol, followed by freeze-drying to yield zinc oxide nanoparticle (ZnO-NP) powder. Studies have shown that using ultrasonic-assisted methods can enhance uniformity and dispersion of ZnO-NPs.

Using ethanol instead of water in the reaction system can induce a morphological shift in ZnO-NPs from spherical to rod-shaped. This transformation occurs due to the facile cleavage of the C-O bond in alcohols on the zinc metal surfaceⁱⁱ. A typical procedure involves mixing 10 mL of ethanol with 5 mg of zinc metal powder, sonicating the mixture for 20 minutes, and then placing it in an inert stainless steel autoclave. The reaction mixture is heated at a controlled rate (2 °C/min) to 200 °C and maintained for 24–48 hours. The product is then centrifuged, cleaned, and vacuum-dried to obtain rod-shaped ZnO nanoparticle powderⁱⁱⁱ.

Microwave-assisted solvothermal synthesis is another variation of the method, where the particle size of ZnO-NPs, ranging from 20 nm to 120 nm, can be controlled by adjusting the microwave radiation power. This approach offers a faster and more efficient route for nanoparticle synthesis^{iv}.

- **Precipitation Method**

The precipitation method involves mixing a precursor solution of zinc salts with a suitable reagent, such as a base or an acid, under controlled conditions to produce zinc oxide nanoparticles (ZnO-NPs). In some chemical processes, zinc nitrate and urea serve as precursors, forming ZnO-NPs under high heat and pressure in a sealed aqueous solution. This method is valued for its simplicity, speed, cost-effectiveness, and ease of operation. However, the simultaneous nucleation and growth during the ZnO formation process present challenges for detailed investigation of the mechanism^v.

A typical procedure involves dissolving urea in distilled water while stirring for 30 minutes, where urea acts as a precipitating agent. The zinc nitrate solution is then vigorously stirred for two hours at 70 °C. Over time, the mixture turns into a whitish, cloudy solution, indicating the formation of a precursor product. This product is centrifuged at 8000 rpm for 10 minutes, washed with distilled water to remove impurities, and subjected to calcination at 500 °C for 3 hours in air using a muffle furnace to obtain ZnO-NPs^{vi}.

Alternatively, a simpler and more cost-effective method does not require a solvent or calcination after drying. In this approach, different morphologies of ZnO-NPs can be obtained by using alkaline solutions, such as NaOH. This method is scalable but requires significant amounts of water. For instance, zinc acetate dihydrate can be dissolved in 50 mL of distilled water under continuous stirring^{vii}. A NaOH solution is then added dropwise to achieve a pH of 12 at room temperature, followed by stirring for 2 hours. After the reaction is complete, the resulting white precipitate is thoroughly washed with distilled water and ethanol to remove residual impurities. The precipitate is then dried in an air oven at 60 °C for one day, during which $\text{Zn}(\text{OH})_2$ converts to ZnO-NPs^{viii}.

- **Chemical Vapor Transport Method**

The chemical vapor transport method involves heating a powder to high temperatures in the presence of a transport agent, such as graphite or iodine, and allowing the resulting vapor to condense in a cooler region to form nanoparticles. This technique, first introduced by Bunsen in 1852, relies on heterogeneous reactions collectively termed "Chemical Vapor Transfer."

In this process, ZnO nanostructures are synthesized as vapors of zinc and oxygen, or their mixtures, are transported and react sequentially in different zones. This method is straightforward, efficient, and simplifies ZnO formation through controlled decomposition. The procedure involves heating zinc powder in a flowing oxygen environment, requiring precise control of the oxygen pressure relative to the zinc vapor pressure to ensure the formation of desirable ZnO nanostructures. Variations in this pressure ratio significantly affect the morphology of ZnO, resulting in changes to the size, shape, and geometry of the nanostructures^{ix,x}.

Biological/Green Synthesis Methods

- **Plant-Mediated Synthesis**

An innovative and eco-friendly alternative to traditional chemical methods for producing zinc oxide nanoparticles (ZnO-NPs) is plant-mediated synthesis using plants and plant extracts^{xi}. This approach is gaining attention for its safety, simplicity, and avoidance of harmful chemicals^{xii,xiii}. A variety of plants and extraction processes can be utilized for ZnO-NP synthesis. This section highlights some of the most commonly used, accessible, and straightforward methods.

For example, tomato fruits, chamomile flowers, and olive leaves are first rinsed with double-distilled water and air-dried. The dried plant material is then ground into a powder, and 200 mL of water is extracted at 60–70 °C for 4 hours. After cooling to room temperature, the extracts are filtered using filter paper. The filtered plant extracts are then mixed with a zinc precursor solution in a separate flask for ZnO-NP synthesis.

The mixture is stirred for 4 hours at 100 rpm under controlled heating conditions. Following the reaction, the solution is centrifuged at 10,000× g for 20 minutes, the supernatant is discarded, and the precipitate is collected. The collected precipitate is washed with distilled water and freeze-dried to produce ZnO nanoparticles^{xiv}. These steps are illustrated in the figure 2.

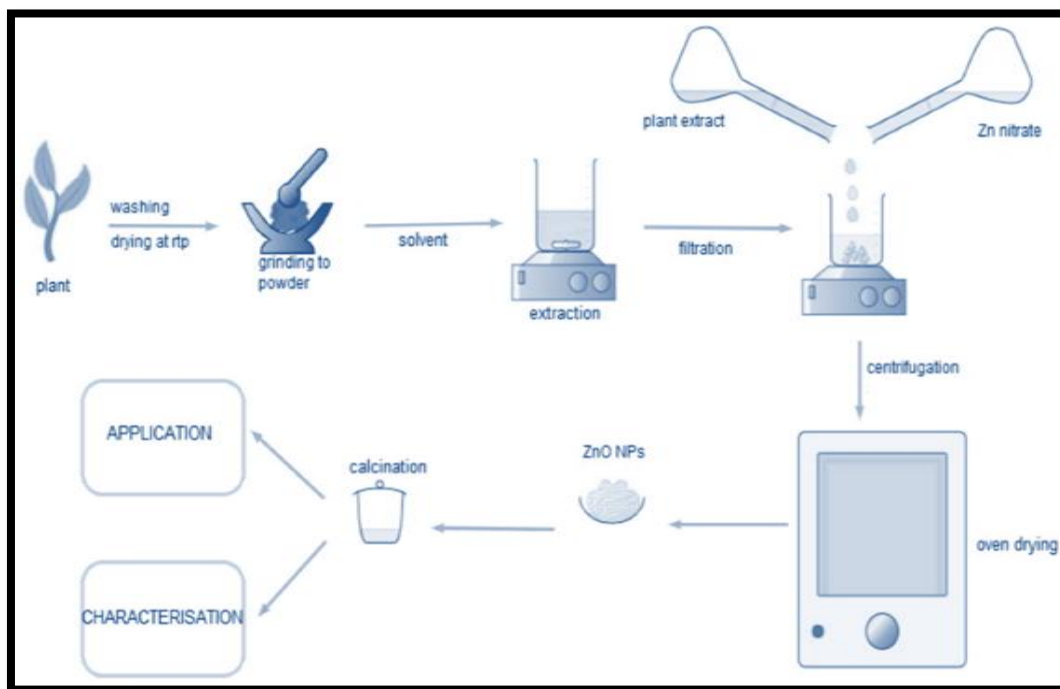


Fig. 2: Schematic of the Most Common ZnO-NPs Synthesis Procedure

Physical Synthesis Methods

- **Physical Vapor Deposition**

Physical vapor deposition is a relatively simple method for synthesizing ZnO nanowires at a low temperature of 450 °C. The growth process of ZnO nanowires in this method is catalyst-free, as evidenced by the increase in nanowire diameter with rising temperature^{xv}. These findings highlight the potential of this technique for fabricating ZnO-based nanoscale devices on substrates with low-temperature endurance.

- **Ultrasonic Irradiation**

Ultrasonic irradiation is frequently employed in solution-phase processes to synthesize nanoparticles. Unlike surfactant-based methods, this technique is a natural and efficient process that does not alter the intrinsic properties of the particles. It is considered one of the most practical approaches for producing pure materials with a diverse range of controlled properties^{xvi}.

In Zhang's study, the physical mechanisms underlying ultrasound-assisted ZnO nanoparticle synthesis were elucidated. Four stages of ultrasound-induced changes were identified: variations in voltage in the acoustic signal, cycles of cavitation bubble oscillation, bubble collapse, and corresponding changes in maximum voltage amplitude and acoustic intensity. These stages collectively contribute to the synthesis process.

Conclusion

Zinc oxide (ZnO) nanoparticles have proven to be a promising and versatile nanomaterial with a wide range of applications across various sectors, including electronics, cosmetics, medicine, and environmental remediation. Their unique physicochemical properties, such as high surface area, optical transparency, antimicrobial activity, and photocatalytic efficiency, make them valuable for use in products like sunscreens, drug delivery systems, and catalysts for pollution degradation. The synthesis of ZnO nanoparticles can be achieved through a variety of methods, each offering specific advantages depending on the desired particle size, morphology, and scalability. Conventional methods such as hydrothermal, precipitation, and chemical vapor deposition remain widely used for their simplicity and cost-effectiveness, while biological or green synthesis techniques are gaining attention due to their eco-friendliness and non-toxic nature.

Future research should focus on enhancing the biocompatibility and environmental sustainability of ZnO nanoparticles while capitalizing on their functional properties for innovative applications. The continuous development of green synthesis methods, coupled with improved safety measures and regulatory frameworks, will play a critical role in the safe integration of ZnO nanoparticles into consumer products and industrial processes.

In conclusion, ZnO nanoparticles hold immense potential, but their environmental and health implications need to be carefully addressed to ensure their safe and responsible use in a wide range of applications. Through comprehensive research and collaboration across fields, ZnO nanoparticles can continue to contribute to advancements in technology while minimizing their ecological footprint.

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